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Calculation of the Effect of Camber and Twist  
on the Pressure Distribution and Drag on some  
Curved Plates at Supersonic Speeds

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# Calculation of the Effect of Camber and Twist on the Pressure Distribution and Drag on some Curved Plates at Supersonic Speeds

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*Summary.*—So far, little is known of the effect of camber or twist on the pressure distribution and drag of a wing flying at supersonic speeds, but with subsonic leading edges. According to the linear theory, for a subsonic leading edge, there is a singularity in the perturbation velocity component normal to the edge. Associated with this singularity is an infinite (or very large) suction over the sharp leading edge, as in subsonic flow.

The present investigation was undertaken with a view to finding the shape of a curved wing, such that the thrust loading on the leading edges, particularly near the wing tips, is removed or modified. The shapes of two groups of such wings have been found :—

- (1) For the first group, when the wings are at design incidence, there are no leading-edge pressure singularities, and therefore no leading-edge thrust. The pressure difference is finite and positive everywhere on the wing, and decreases to zero on the leading edges.
- (2) For wings of the second group, the leading-edge singularity is modified so that its strength increases along the edge from zero at the apex to a maximum, and then decreases to zero, after which it would become negative. The effect of additional incidence is to increase the local lift everywhere and to move the positions of maximum and zero singularity strength further downstream.

In this report, it is also shown how the shapes of wings of the second group can be determined to satisfy certain requirements with respect to camber and twist, or the magnitude of aerodynamic characteristics.

The lift, the induced drag, and the pitching-moment coefficients for some wings of triangular plan form have been calculated, and the results are shown graphically.

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1. *Introduction.*—When the leading edges of a flat delta wing, at incidence, at supersonic speeds, lie within the Mach cone of the vertex, the component of the free-stream velocity, normal to a leading edge, is less than the local sonic velocity, and the leading edge becomes 'subsonic.' According to the linear theory, for a subsonic leading edge, there is a singularity in the perturbation velocity component normal to the edge. Associated with this singularity is an infinite (or very large) suction over the sharp leading edge, as in subsonic flow. The component of this suction force in the free-stream direction tends to reduce the induced drag. The present report is an account of an investigation undertaken with a view to finding the shape of a curved wing (of negligible thickness) such that the thrust loading on the leading edges is removed or modified, while, at the same time, certain requirements with respect to camber and twist, or aerodynamic properties, are satisfied. By removing the suction peaks near the leading edge of the outboard sections of the wing, the associated adverse pressure gradients are reduced, thereby reducing the tendency for the boundary layer to separate. (Some preliminary results were given in Reference 6.)

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In Ref. 2 (R. & M. 2548), the linearised differential equation for supersonic flow is solved in a special system of curvilinear co-ordinates known as hyperboloido-conal co-ordinates, and in Ref. 1, two of these solutions are applied to the case of a thin delta wing (with subsonic leading edges) in steady supersonic flow, when the local incidence varies linearly in a spanwise or chordwise direction, the induced velocity potentials being given by  $\varphi = CyX$  or  $\varphi = CxX$ , where  $X \equiv \sqrt{(x^2 - k^2y^2)}$ ,  $k$  is the cotangent of the apex semi-angle of the surface, and  $C$  is an arbitrary constant.  $x$  is measured downstream from the apex,  $y$  is measured to starboard and  $z$  is measured vertically upwards.

In this report, some general solutions are discussed and the results are applied to determine the shapes of certain thin surfaces with swept-back leading edges, over which the induced flow is given by the velocity potentials  $\varphi = Cx^2X$ ,  $\varphi = Cy^2X$ ,  $\varphi = Cx^3X$  or  $\varphi = Cxy^2X$ . The surfaces are symmetrical with respect to the  $zx$ -plane, and are set symmetrically to the wind direction, the apex pointing against the stream. The solutions are only valid if the surfaces lie wholly within the Mach cone of the apex, therefore the Mach angle  $\mu$  ( $= \text{cosec}^{-1} M$ ) is greater than the apex semi-angle  $\gamma$ .

These solutions are combined to give the shapes of two wings, for which, at design incidence the pressure is finite at all points on the wing, and decreases to zero at the leading edges. Other combinations of these solutions, the solution  $\varphi = xX$  (Ref. 1), and the solution for the flat delta wing at incidence (Refs. 1 and 2) are shown to give wings for which the pressure is finite except at the leading edges, where, in general, it becomes infinite, but such that the strength of the singularity on a leading edge increases along the edge from zero at the apex to a maximum and then decreases until a point of zero pressure is reached, after which the strength would become negative. The total lift in each case is finite.

The above solutions are further combined to give a general solution, which may be used when there are certain conditions to be satisfied.

A number of numerical examples for special values of  $\gamma$  and  $M$  are given, and some examples of the pressure distributions at different incidences are shown graphically. The local spanwise lift distribution, the total lift, the induced drag, and the moment coefficients, and also the variation in camber and twist, have been calculated.

The mathematical work involved is mostly self-checking; wherever possible, the formulae have been checked by using at least two methods of derivation.

**2. Method of Solution.**—The co-ordinates used are the pseudo-orthogonal co-ordinates  $r, \mu, \nu$  used in Refs. 1 and 2, where

$$x = \frac{\beta r \mu \nu}{hk}, \quad y = \frac{r(\mu^2 - h^2)^{1/2}(\nu^2 - h^2)^{1/2}}{h\beta}, \quad z = \frac{r(\mu^2 - h^2)^{1/2}(h^2 - \nu^2)^{1/2}}{k\beta} \quad (1)$$

$$\left. \begin{aligned} \beta^2 &= M^2 - 1 = \cot^2 \bar{\mu} = k^2 - h^2 \\ h^2 &= \cot^2 \gamma, \quad h^2 = \cot^2 \gamma - \cot^2 \bar{\mu} \end{aligned} \right\} \dots \dots \dots (2)$$

It is assumed that the surfaces all lie close to the plane  $\mu = h$ , (or  $z = 0$ ), and that the induced velocities on the surface are small and equal to the induced velocities on the plane. Therefore the relation between the shape of the surface and its induced velocity potential  $\varphi$  is of the form

$$\frac{\partial z}{\partial x} = \frac{1}{V} \left( \frac{\partial \varphi}{\partial z} \right)_{\mu=h}, \quad \dots \dots \dots (3)$$

where  $V$  is the stream velocity.

For the linearised theory, the pressure  $\Delta p$  on an element of the upper surface, and the pressure coefficient  $C_p$  are given by:

$$\Delta p = -\rho V \left( \frac{\partial \varphi}{\partial x} \right)_{\mu=h} \dots \dots \dots (4)$$

$$C_p = \frac{2\Delta p}{\rho V^2} = -\frac{2}{V} \left( \frac{\partial \phi}{\partial x} \right)_{\mu=k}, \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (5)$$

where  $\rho$  is the density of the free stream.

The linearised differential equation for the induced velocity potential  $\phi$ , in terms of the coordinates  $r, \mu, \nu$ , is (R. & M. 2548<sup>2</sup>)

$$\begin{aligned} (\mu^2 - \nu^2) \frac{\partial}{\partial r} \left( r^2 \frac{\partial \phi}{\partial r} \right) - \left( (\mu^2 - h^2)(\mu^2 - k^2) \right)^{1/2} \frac{\partial}{\partial \mu} \left[ \left( (\mu^2 - h^2)(\mu^2 - k^2) \right)^{1/2} \frac{\partial \phi}{\partial \mu} \right] \\ - \left( (\nu^2 - h^2)(k^2 - \nu^2) \right)^{1/2} \frac{\partial}{\partial \nu} \left[ \left( (\nu^2 - h^2)(k^2 - \nu^2) \right)^{1/2} \frac{\partial \phi}{\partial \nu} \right] = 0 \quad \dots \quad \dots \quad \dots \quad (6) \end{aligned}$$

and it has been shown, in Appendix V of Ref. 2, that a solution of equation (6) can be found of the form  $\phi = r^n f(\mu, \nu)$ , where  $f(\mu, \nu)$  is the product of two Lamé functions of  $\mu, \nu$  respectively, of degree  $n$ ,  $n$  being a positive integer.

A standard Lamé function of degree  $n$ ,  $E_n(\mu)$ , can be determined in  $(2n + 1)$  different ways, and belongs to one of four classes  $K, L, M, N$  (Ref. 3). Assuming that  $E_n(\mu)$  has been determined, there is a second solution of Lamé's equation, defined by: (References 1 and 3)

$$F_n(\mu) = E_n(\mu) \int_{\mu}^{\infty} \frac{dt}{[E_n(t)]^2 \{ |(t^2 - h^2)(t^2 - k^2)| \}^{1/2}}$$

As stated in Ref. 2, the normal solutions of equation (6) of the form

$$\phi = r^n F_n(\mu) E_n(\nu) \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (7)$$

have the property that  $\phi \rightarrow 0$  on approaching the Mach cone  $x^2 - \beta^2(y^2 + z^2) = 0$ . Also they are continuous inside the cone, except possibly across the triangular region  $x^2 - k^2 y^2 > 0, x > 0, z = 0$ . Therefore, provided the requisite boundary conditions are satisfied, a function  $\phi$  defined by (7) inside the cone  $x^2 - \beta^2(y^2 + z^2) = 0, x > 0$ , and by  $\phi = 0$  elsewhere, may serve as a solution to any particular problem related to a triangular aerofoil. In order that  $x, y, z$  (cf. equations (1), (2)) shall be expressed, in general, by a single set of values of  $r, \mu, \nu$ , it is assumed that  $0 \leq r \leq +\infty$ , and that  $\mu$  ranges from  $+\infty$  to  $k$  and back, the sign of  $(\mu^2 - k^2)^{1/2}$  changing from positive to negative as  $\mu$  passes through the value  $k$ ; and  $\nu$  ranges from  $k$  to  $h$  and back, the sign of  $(\nu^2 - h^2)^{1/2}$  changing from positive to negative as  $\nu$  passes through the value  $h$ .

For a lifting surface of negligible thickness, we require solutions such that  $\phi$  is an odd function of  $z$ , and on the plane  $z = 0$  ( $\mu = k$ ), is of the form  $\phi = f(x, y^2)(x^2 - k^2 y^2)^{1/2}$ , where  $f(x, y^2)$  is a rational algebraic function of  $x$  and  $y^2$ . Our solutions are therefore based on Lamé functions of the  $M$  class, that is  $E_n(\mu)$  is of the form

$$E_n(\mu) \equiv M_n(\mu) = (|\mu^2 - k^2|)^{1/2} (\mu^{n-1} + a_1 \mu^{n-3} + \dots) \equiv (|\mu^2 - k^2|)^{1/2} P_n(\mu) \quad \dots \quad (8)$$

where  $P_n(\mu) = \mu^{n-1} + a_1 \mu^{n-3} + \dots$ ,

the last term in the expansion for  $P_n(\mu)$  being  $a_{(n-2)/2} \mu$  or  $a_{(n-1)/2}$  according as  $n$  is even or odd; and therefore  $F_n(\mu)$  is of the form

$$F_n(\mu) = (|\mu^2 - k^2|)^{1/2} P_n(\mu) \int_{\mu}^{\infty} \frac{dt}{[P_n(t)]^2 \{ |(t^2 - k^2)(t^2 - h^2)| \}^{1/2}} \quad \dots \quad (9)$$

It has been shown in Reference 1 that

$$\lim_{\mu \rightarrow k} F_n(\mu) = \frac{1}{\beta k P_n(k)}, \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (10)$$

and that, if  $\varphi_n = C_n r^n F_n(\mu) E_n(\nu)$ , then

$$\lim_{\mu \rightarrow k} \varphi_n = \frac{C_n r^n E_n(\nu)}{\beta k P_n(k)}, \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (11)$$

and

$$\lim_{\mu \rightarrow k} \left( \frac{\partial \varphi_n}{\partial z} \right) = C_n r^{n-1} P_n(\nu) \beta k P_n(k) \int_k^\infty \frac{d}{dt} \left[ \frac{1}{t [P_n(t)]^2 (t^2 - h^2)^{1/2}} \right] \frac{dt}{(t^2 - k^2)^{1/2}}. \quad \dots \quad \dots \quad (12)$$

The general solutions for odd and even values of  $n$  are discussed in sections 3 and 4, but the solutions which follow, in sections 6 and 7, for  $n = 3$  and  $n = 4$ , are complete in themselves, and can be read without reference to sections 3 and 4.

3. *Solutions for  $n = 2N + 1$ , where  $N$  is a positive integer.*—For  $n = 2N + 1$ , there are  $(N + 1)$   $M$ -functions of the form

$$M_{2N+1}^m(\mu) = (|\mu^2 - h^2|)^{1/2} P_{2N+1}^m(\mu), \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (13)$$

where  $P_{2N+1}^m(\mu) = \mu^{2N} + a_{1,m} \mu^{2N-2} + \dots + a_{N,m}$ ,  $\dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (14)$

$$m = 1, 2, \dots (N + 1).$$

We consider the solution

$$\varphi_m = C_{2N+1} r^{2N+1} F_{2N+1}^m(\mu) E_{2N+1}^m(\nu).$$

At the plane  $z = 0$ ,  $\mu \rightarrow k$ , and

$$r^2 = (x^2 - \beta^2 y^2) / \beta^2, \quad r^2 \nu^2 = h^2 x^2 / \beta^2. \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (15)$$

Hence, using equation (11), it can be shown that

$$\begin{aligned} \lim_{\mu \rightarrow k} \varphi_m &= \frac{C_{2N+1} r^{2N+1} (k^2 - \nu^2)^{1/2} P_{2N+1}^m(\nu)}{\beta k P_{2N+1}^m(k)} \\ &= \frac{C_{2N+1}}{k \beta^{2N+1} P_{2N+1}^m(k)} \sum_{s=0}^N \left[ a_{s,m} (h^2 x^2)^{N-s} (x^2 - \beta^2 y^2)^s \right] (x^2 - k^2 y^2)^{1/2} \\ &\equiv \frac{C_{2N+1}}{k \beta^{2N+1} P_{2N+1}^m(k)} \sum_{s=0}^N \left[ A_s x^{2N-2s} y^{2s} \right] (x^2 - k^2 y^2)^{1/2} \quad \dots \quad \dots \quad \dots \quad (16) \end{aligned}$$

where  $A_s$  is a function of  $(\beta, h, a_{1,m}, a_{2,m}, \dots, a_{N,m})$ , and  $a_{0,m} = 1$ .

By constructing a potential

$$\phi_{2N+1} = \sum_{m=1}^{N+1} (\lambda_m \varphi_m)$$

where the  $\lambda$ 's are constants determined by equating corresponding coefficients, we can obtain any potential of the form (16), where the constant coefficients  $A_s$  are given, and hence, by using equations (12) and (3), we can determine the shape of the surface corresponding to the given flow.

In practice, it is simplest to determine the  $(N+1)$  surfaces on which the induced velocity potentials are of the form

$$\begin{aligned} \phi_{2N+1}^s &= D_{2N+1} x^{2N-2s+2} y^{2s-2} (x^2 - k^2 y^2)^{1/2} \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (17) \\ s &= 1, 2, \dots (N+1), \end{aligned}$$

$D_{2N+1}$  being a constant, and then to combine these solutions.

To determine the shape of the surface, we require the value of  $\left(\frac{\partial\varphi_m}{\partial z}\right)_{\mu=k}$ . Using (12),

$$\left(\frac{\partial\varphi_m}{\partial z}\right)_{\mu=k} = C_{2N+1} \nu^{2N} P_{2N+1}^m(\nu) \beta k P_{2N+1}^m(k) \times \int_k^\infty \frac{d}{dt} \left[ \frac{1}{t [P_{2N+1}^m(t)]^2 (t^2 - h^2)^{1/2}} \right] \frac{dt}{(t^2 - k^2)^{1/2}} \quad \dots \quad \dots \quad \dots \quad (18)$$

It is shown in Appendix III that the integral in (18) can be evaluated in terms of the complete elliptic integrals of the first and second kind of modulus  $h/k$ . Hence

$$\left(\frac{\partial\varphi_m}{\partial z}\right)_{\mu=k} = \sum_{s=1}^{N+1} \left[ B_s x^{2N-2s+2} y^{2s-2} \right], \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (19)$$

$B_s$  being constant, and, using (3),

$$z_m = \frac{1}{V} \sum_{s=1}^{N+1} \left[ \frac{B_s}{2N - 2s + 3} x^{2N-2s+3} y^{2s-2} \right] + f(y), \quad \dots \quad \dots \quad \dots \quad (20)$$

where  $f(y)$  is a (small) arbitrary function of  $y$ .

The equation of the surface whose induced velocity potential is given by (17) is

$$z = \sum_{m=1}^{N+1} (\lambda_m z_m), \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (21)$$

the  $\lambda$ 's having been chosen to give the correct potential.

From (16),

$$\left(\frac{\partial\varphi_m}{\partial x}\right)_{\mu=k} = \frac{C_{2N+1}}{k \beta^{2N+1} P_{2N+1}^m(k)} \sum_{s=0}^N \left[ A_s x^{2N-2s-1} y^{2s} \left\{ \frac{x^2}{X} + (2N - 2s)X \right\} \right] \quad \dots \quad (22)$$

where  $X \equiv (x^2 - k^2 y^2)^{1/2}$ .

The pressure coefficient for the surface (20) can be evaluated from the formula

$$C_p = -\frac{2}{V} \left( \frac{\partial\phi_{2N+1}^s}{\partial x} \right)_{\mu=k} = -\frac{2}{V} \sum_{m=1}^{N+1} \left[ \lambda_m \left( \frac{\partial\varphi_m}{\partial x} \right)_{\mu=k} \right] \quad \dots \quad \dots \quad \dots \quad (23)$$

4. *Solutions for  $n = 2N$ , where  $N$  is a Positive Integer.*—For  $n = 2N$ , there are  $N$   $M$ -functions of the form

$$M_{2N}^m(\mu) = (|\mu^2 - k^2|)^{1/2} P_{2N}^m(\mu) \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (24)$$

$$\text{where } P_{2N}^m(\mu) = \mu^{2N-1} + b_{1,m} \mu^{2N-3} + \dots + b_{N-1,m} \mu, \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (25)$$

$m = 1, 2, \dots, N$ .

We consider the solution

$$\varphi_m = C_{2N} \nu^{2N} F_{2N}^m(\mu) E_{2N}^m(\nu).$$

Using (11) and (15), it can be shown that

$$\begin{aligned} \lim_{\mu \rightarrow k} \varphi_m &= \frac{C_{2N} \nu^{2N} (k^2 - \nu^2)^{1/2} P_{2N}^m(\nu)}{\beta k P_{2N}^m(k)} \\ &= \frac{C_{2N}}{k \beta^{2N} P_{2N}^m(k)} \sum_{s=0}^{N-1} \left[ A_s' x^{2N-1-2s} y^{2s} \right] (x^2 - k^2 y^2)^{1/2} \quad \dots \quad \dots \quad \dots \quad (26) \end{aligned}$$

where  $A_s'$  is a function of  $\beta, h, b_{1,m}, b_{2,m}, \dots, b_{N-1,m}$ .

By constructing a potential

$$\phi_{2N} = \sum_{m=1}^N (\lambda_m \varphi_m)$$

where the  $\lambda$ 's are constants to be determined, we can obtain any potential of the form (26), where the constant coefficients  $A_s'$  are given, and hence we can determine the shape of the corresponding surface as in section 3. In particular, we can determine the  $N$  'basic' surfaces on which the induced velocity potentials are of the form

$$\phi_{2N}^s = D_{2N} x^{2N-2s+1} y^{2s-2} (x^2 - k^2 y^2)^{1/2} \quad \dots \quad \dots \quad \dots \quad \dots \quad (27)$$

$s = 1, 2, \dots, N$ ,  $D_{2N}$  being a constant. These 'basic' solutions can then be combined to give any solution of the form (26).

Using (12),

$$\left( \frac{\partial \varphi_m}{\partial z} \right)_{\mu=k} = C_{2N} v^{2N-1} P_{2N}^m(v) \beta k P_{2N}^m(k) \times \int_k^\infty \frac{dt}{t} \left[ \frac{1}{t [P_{2N}^m(t)]^2 (t^2 - k^2)^{1/2}} \right] \frac{dt}{(t^2 - k^2)^{1/2}} \quad \dots \quad \dots \quad \dots \quad (28)$$

The value of the integral in (28) is found, in terms of the complete elliptic integrals of the first and second kind of modulus  $h/k$ , in Appendix III.

$$\text{Hence} \quad \left( \frac{\partial \varphi_m}{\partial z} \right)_{\mu=k} = \sum_{s=1}^N \left[ B_s' x^{2N-2s+1} y^{2s-2} \right], \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (29)$$

$B_s'$  being a constant, and, using (3),

$$z_m = \frac{1}{V} \sum_{s=1}^N \left[ \frac{B_s'}{2N - 2s + 2} x^{2N-2s+2} y^{2s-2} \right] + f(y) \quad \dots \quad \dots \quad \dots \quad (30)$$

where  $f(y)$  is a (small) arbitrary function of  $y$ .

The equation of the surface, whose induced velocity potential is given by (27), is

$$z = \sum_{m=1}^N (\lambda_m z_m), \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (31)$$

the  $\lambda$ 's being chosen to give the correct potential.

From (26),

$$\left( \frac{\partial \varphi_m}{\partial x} \right)_{\mu=k} = \frac{C_{2N}}{k \beta^{2N} P_{2N}^m(k)} \sum_{s=0}^{N-1} \left[ A_s' x^{2N-2s-2} y^{2s} \left\{ \frac{x^2}{X} + (2N - 2s - 1) X \right\} \right] \quad \dots \quad (32)$$

The pressure coefficient for surface (30) can be evaluated from the formula

$$C_p = - \frac{2}{V} \left( \frac{\partial \phi_{2N}^s}{\partial x} \right)_{\mu=k} = - \frac{2}{V} \sum_{m=1}^N \left[ \lambda_m \left( \frac{\partial \varphi_m}{\partial x} \right)_{\mu=k} \right] \quad \dots \quad \dots \quad \dots \quad (33)$$

In section 5, the solutions for  $n = 1$  and  $n = 2$  are quoted from Refs. 1 and 2; and in sections 6 and 7, the 'basic' solutions for  $n = 3$  and  $n = 4$  are found. For purposes of reference, the results are tabulated in Appendix VI.

5. *Solutions for  $n = 1$  and  $n = 2$ .*—The solutions for  $n = 1$  and  $n = 2$  are both given in Ref. 2, and the results, which are used later in this report, are quoted below (with a slightly different notation):

For  $n = 1$ , the induced velocity potential is

$$\phi_1 = \frac{\beta V \delta}{E(\kappa)} r(\mu^2 - k^2)^{1/2} (k^2 - v^2)^{1/2} \int_{\mu}^{\infty} \frac{dt}{(t^2 - k^2)^{3/2} (t^2 - h^2)^{1/2}}, \quad \dots \quad (34)$$

where  $E(\kappa)$  is the complete elliptic integral of the second kind, modulus  $\kappa (= h/k)$ , gives the flow past the flat delta wing, at small incidence  $\delta$ , whose equation is

$$z \equiv z_1 = -\delta x + f(y) \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (35)$$

where  $f(y)$  is a (small) arbitrary function of  $y$ .

On the wing,

$$\begin{aligned} (\phi_1)_{\mu=h} &= \frac{V \delta}{k E(\kappa)} (x^2 - k^2 y^2)^{1/2} \\ &\equiv \frac{V \delta}{k E(\kappa)} X, \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \end{aligned} \quad (36)$$

and

$$\left( \frac{\partial \phi_1}{\partial x} \right)_{\mu=h} = \frac{V \delta}{k E(\kappa)} \frac{x}{X} \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (37)$$

For  $n = 2$ , the induced velocity potential is

$$\phi_2 = \frac{\beta^2 V \delta}{d k E(\kappa)} r^2 \mu v (\mu^2 - k^2)^{1/2} (k^2 - v^2)^{1/2} \int_{\mu}^{\infty} \frac{dt}{t^2 (t^2 - k^2)^{3/2} (t^2 - h^2)^{1/2}} \quad (38)$$

where  $\delta, d$  are constants ( $\delta$  small and non-dimensional), gives the flow past the triangular surface whose equation is

$$z \equiv z_2 = -\frac{\delta}{d} f_1 (\tan \gamma / \tan \bar{\mu}) x^2 + f(y), \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (39)$$

$$\text{where } f_1(\tan \gamma / \tan \bar{\mu}) = \frac{1}{2\kappa^2 E(\kappa)} \left[ (2\kappa^2 - 1)E(\kappa) + (1 - \kappa^2)K(\kappa) \right], \quad \dots \quad \dots \quad \dots \quad (40)$$

$\kappa^2 = h^2/k^2 = 1 - \tan^2 \gamma / \tan^2 \bar{\mu}$ ,  $K(\kappa)$ ,  $E(\kappa)$  are the complete elliptic integrals of the first and second kind with modulus  $\kappa$ , and  $f(y)$  is a (small) arbitrary function of  $y$ .

On the surface,

$$(\phi_2)_{\mu=h} = \frac{V \delta}{d k E(\kappa)} x X \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (41)$$

$$\text{and} \quad \left( \frac{\partial \phi_2}{\partial x} \right)_{\mu=h} = \frac{V \delta}{d k E(\kappa)} \left( \frac{x^2}{X} + X \right) \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (42)$$

It can be shown that as  $\kappa \rightarrow 0$ ,  $f_1 \rightarrow 0.75$ . The values of  $f_1$  are given in Appendix II and Fig. 1.

6. *Basic Solutions for  $n = 3$ .*—For  $n = 3$ , there are two  $M$ -functions, and we assume

$$E_3^m(\mu) \equiv M_3^m(\mu) = (|\mu^2 - k^2|)^{1/2} P_3^m(\mu) \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (43)$$

$$\text{where } P_3^m(\mu) = \mu^2 - a_m, \quad m = 1, 2 \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (44)$$

Putting  $N = 1$  and  $c_r = a_m$  in equation (III, 4) of Appendix III, the equation giving the two values of  $a_m$  is

$$5a_m^2 - 2(2h^2 + k^2)a_m + h^2k^2 = 0. \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (45)$$

Therefore

$$a_1 + a_2 = \frac{2(2h^2 + k^2)}{5} \quad \text{and} \quad a_1 a_2 = \frac{h^2 k^2}{5} \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (46)$$



We first consider the solution

$$\begin{aligned}\varphi_m &= C_3 r^3 F_3^m(\mu) E_3^m(\nu), \quad (m = 1, 2) \\ &= C_3 r^3 (\mu^2 - k^2)^{1/2} (k^2 - \nu^2)^{1/2} (\mu^2 - a_m)(\nu^2 - a_m) \times \\ &\quad \int_{\mu}^{\infty} \frac{dt}{(t^2 - a_m)^2 (t^2 - k^2)^{3/2} (t^2 - h^2)^{1/2}}, \quad m = 1, 2. \quad \dots \quad \dots \quad (47)\end{aligned}$$

At the plane  $z = 0$ ,  $\mu \rightarrow k$ , and

$$r^2 = (x^2 - \beta^2 y^2)/\beta^2, \quad r^2 \nu^2 = h^2 x^2/\beta^2. \quad \dots \quad \dots \quad \dots \quad \dots \quad (48)$$

Hence, using equation (11), it can be shown that

$$\begin{aligned}\lim_{\mu \rightarrow h} \varphi_m &= \frac{C_3 r^3 (k^2 - \nu^2)^{1/2} (\nu^2 - a_m)}{\beta k (k^2 - a_m)} \\ &= \frac{C_3 [(h^2 - a_m)x^2 + \beta^2 a_m y^2] (x^2 - k^2 y^2)^{1/2}}{\beta^3 k (k^2 - a_m)} \quad \dots \quad \dots \quad \dots \quad (49)\end{aligned}$$

Our two basic solutions of the form (17) are

$$\phi_3^1 = D_3 x^2 X \text{ and } \phi_3^2 = D_3' y^2 X$$

where  $X \equiv (x^2 - k^2 y^2)^{1/2}$ , and  $D_3, D_3'$  are constants.

We construct a potential

$$\phi_3^s = \lambda_1 \varphi_1 + \lambda_2 \varphi_2, \quad s = 1, 2$$

where  $\lambda_1, \lambda_2$  are constants to be determined.

It is slightly easier to construct the potential  $\phi_3^2$  first.

For the solution  $\phi_3^2$ , equating the corresponding coefficients, and using (46), we find that

$$\frac{\lambda_1}{\lambda_2} = - \frac{6h^2 k^2 - 5a_2 k^2 - 5a_1 h^2}{6h^2 k^2 - 5a_1 k^2 - 5a_2 h^2}.$$

We therefore construct the potential

$$\phi_3^2 = 6h^2 k^2 (\varphi_1 - \varphi_2) - 5h^2 (a_2 \varphi_1 - a_1 \varphi_2) - 5h^2 (a_1 \varphi_1 - a_2 \varphi_2) \quad \dots \quad (50)$$

which gives

$$(\phi_3^2)_{\mu=h} = \frac{5C_3 h^2 (a_1 - a_2)}{k\beta} y^2 X. \quad \dots \quad \dots \quad \dots \quad \dots \quad (51)$$

For the solution  $\phi_3^1$ , we construct the potential

$$\phi_3^1 = k^2 \phi_3^2 - 3\beta^2 h^2 k^2 (\varphi_1 - \varphi_2) \quad \dots \quad \dots \quad \dots \quad \dots \quad (52)$$

which gives

$$(\phi_3^1)_{\mu=h} = \frac{5C_3 (a_1 - a_2) h^2}{k\beta} x^2 X \quad \dots \quad \dots \quad \dots \quad \dots \quad (53)$$

The values of  $\varphi_1 - \varphi_2$ ,  $a_2 \varphi_1 - a_1 \varphi_2$ ,  $a_1 \varphi_1 - a_2 \varphi_2$ , when  $\mu \rightarrow k$ , are given in Appendix IV.

We choose the arbitrary constant  $C_3$  so that

$$\frac{5C_3 (a_1 - a_2) h^2}{\beta} = \frac{V\delta}{d^2 E(\kappa)}$$

where  $\delta, d$  are constants,  $\delta$  being small and non-dimensional, and  $E(\kappa)$  is the complete elliptic integral of the second kind, with modulus  $\kappa = h/k$ . ( $C_3$  is written in this form for the purpose of later constructions.)



where  $P_4^m(\mu) = \mu(\mu^2 - a_m)$ ,  $m = 1, 2$ . .. .. . (61)

Putting  $N = 2$  and  $d_r = a_m$  in equation (III,5) of Appendix III, the equation giving the two values of  $a_m$  is

$$7a_m^2 - (6h^2 + 4k^2)a_m + 3h^2k^2 = 0 \quad \dots \dots \dots (62)$$

therefore

$$a_1 + a_2 = \frac{6h^2 + 4k^2}{7}, \quad a_1a_2 = \frac{3h^2k^2}{7} \quad \dots \dots \dots (63)$$

We first consider the solution

$$\begin{aligned} \varphi_m &= C_4 r^4 F_4^m(\mu) E_4^m(\nu) \quad (m = 1, 2) \\ &= C_4 r^4 (\mu^2 - k^2)^{1/2} (k^2 - \nu^2)^{1/2} \mu \nu (\mu^2 - a_m)(\nu^2 - a_m) \times \\ &\quad \int_{\mu}^{\infty} \frac{dt}{t^2(t^2 - a_m)^2(t^2 - k^2)^{3/2}(t^2 - h^2)^{1/2}} \quad \dots \dots \dots (64) \end{aligned}$$

Using (11) and (48), it can be shown that

$$\begin{aligned} \lim_{\mu \rightarrow k} \varphi_m &= \frac{C_4 r^4 (k^2 - \nu^2)^{1/2} \nu (\nu^2 - a_m)}{\beta k^2 (k^2 - a_m)} \\ &= \frac{C_4 h x [(h^2 - a_m)x^2 + \beta^2 a_m y^2] (x^2 - k^2 y^2)^{1/2}}{\beta^4 k^2 (k^2 - a_m)} \quad \dots \dots \dots (65) \end{aligned}$$

Our two basic solutions of the form (27) are  $\phi_4^1 = D_4 x^3 X$ , and  $\phi_4^2 = D_4' xy^2 X$ , where  $X = (x^2 - k^2 y^2)^{1/2}$ , and  $D_4, D_4'$  are constants.

We construct a potential

$$\phi_4^s = \lambda_1 \varphi_1 + \lambda_2 \varphi_2, \quad s = 1, 2$$

where  $\lambda_1, \lambda_2$  are constants to be determined.

For the solution  $\phi_4^2$ , equating the corresponding coefficients and using (63), we find that

$$\frac{\lambda_1}{\lambda_2} = -\frac{10h^2k^2 - 7a_2k^2 - 7a_1h^2}{10h^2k^2 - 7a_1k^2 - 7a_2h^2}$$

We therefore construct the potential

$$\phi_4^2 = 10h^2k^2(\varphi_1 - \varphi_2) - 7k^2(a_2\varphi_1 - a_1\varphi_2) - 7h^2(a_1\varphi_1 - a_2\varphi_2) \quad \dots (66)$$

which gives

$$(\phi_4^2)_{\mu=k} = \frac{7C_4 h^3 (a_1 - a_2)}{\beta^2 k^2} xy^2 X \quad \dots \dots \dots (67)$$

For the solution  $\phi_4^1$ , we construct the potential

$$\phi_4^1 = k^2 \phi_4^2 - 3\beta^2 h^2 k^2 (\varphi_1 - \varphi_2), \quad \dots \dots \dots (68)$$

which gives

$$(\phi_4^1)_{\mu=k} = \frac{7C_4 h^3 (a_1 - a_2)}{\beta^2 k^2} x^3 X \quad \dots \dots \dots (69)$$

The values of  $\varphi_1 - \varphi_2$ ,  $a_2\varphi_1 - a_1\varphi_2$ ,  $a_1\varphi_1 - a_2\varphi_2$ , when  $\mu \rightarrow k$ , are given in Appendix IV.

We choose the arbitrary constant  $C_4$  so that

$$\frac{7C_4 (a_1 - a_2) h^3}{\beta^2 k} = \frac{V \delta}{d^2 E(\kappa)}$$

where  $\delta, d$  are constants,  $\delta$  being small and non-dimensional. (cf. choice of  $C_3$  in section 6.)

Therefore, from (67) and (69),

$$\left(\frac{\partial\phi_4^2}{\partial x}\right)_{\mu=h} = \frac{V\delta}{kd^3E(\kappa)} y^2 \left(\frac{x^2}{X} + X\right) \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (70)$$

and

$$\left(\frac{\partial\phi_4^1}{\partial x}\right)_{\mu=h} = \frac{V\delta}{kd^3E(\kappa)} x^2 \left(\frac{x^2}{X} + 3X\right) \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (71)$$

The values of  $\frac{\partial}{\partial z}(\varphi_1 - \varphi_2)$ ,  $\frac{\partial}{\partial z}(a_2\varphi_1 - a_1\varphi_2)$ ,  $\frac{\partial}{\partial z}(a_1\varphi_1 - a_2\varphi_2)$ ,

when  $\mu \rightarrow h$ , are given in Appendix V. Hence it can be shown that

$$\left(\frac{\partial\phi_4^2}{\partial z}\right)_{\mu=h} = \frac{V\delta}{d^3k^2} \left[ f_8 \left(\frac{\tan \gamma}{\tan \bar{\mu}}\right) x^3 - f_9 \left(\frac{\tan \gamma}{\tan \bar{\mu}}\right) xy^2 \right] \quad \dots \quad \dots \quad \dots \quad \dots \quad (72)$$

where

$$f_8 \left(\frac{\tan \gamma}{\tan \bar{\mu}}\right) = [(8 - 3\kappa^2 - 2\kappa^4)E(\kappa) - (1 - \kappa^2)(8 + \kappa^2)K(\kappa)] / (6\kappa^6E(\kappa)),$$

and

$$f_9 \left(\frac{\tan \gamma}{\tan \bar{\mu}}\right) = [(1 - \kappa^2)(8 - 13\kappa^2 + 2\kappa^4)K(\kappa) - (8 - 17\kappa^2 + 7\kappa^4 - 4\kappa^6)E(\kappa)] / (2\kappa^6E(\kappa))$$

$f_8, f_9$  are  $> 0$  for  $0 \leq \kappa \leq 1$ , and when  $\kappa \rightarrow 0$ ,  $f_8 \rightarrow 0.15625$ ,  $f_9 \rightarrow 2.34375$ .

The values of  $f_8, f_9$  are given in Appendix II and Figs. 2 and 3.

Therefore, from (3) and (72), the velocity potential  $\phi_4^2$  gives the flow over the surface

$$z \equiv z_{4,2} = \frac{\delta}{d^3k^2} \left(\frac{1}{4}f_8x^4 - \frac{1}{2}f_9k^2x^2y^2\right) + f(y) \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (73)$$

where  $f(y)$  is a (small) arbitrary function of  $y$ .

Similarly

$$\left(\frac{\partial\phi_4^1}{\partial z}\right)_{\mu=h} = -\frac{V\delta}{d^3} \left[ f_{12} \left(\frac{\tan \gamma}{\tan \bar{\mu}}\right) x^3 - f_{13} \left(\frac{\tan \gamma}{\tan \bar{\mu}}\right) k^2xy^2 \right] \quad \dots \quad \dots \quad \dots \quad \dots \quad (74)$$

where

$$f_{12} \left(\frac{\tan \gamma}{\tan \bar{\mu}}\right) = [(1 - \kappa^2)(8 + 7\kappa^2 + 12\kappa^4)K(\kappa) - (8 + 3\kappa^2 + 7\kappa^4 - 24\kappa^6)E(\kappa)] / (6\kappa^6E(\kappa))$$

and

$$f_{13} \left(\frac{\tan \gamma}{\tan \bar{\mu}}\right) = [(8 - 11\kappa^2 + \kappa^4 + 2\kappa^6)E(\kappa) - (1 - \kappa^2)(8 - 7\kappa^2 - \kappa^4)K(\kappa)] / (2\kappa^6E(\kappa)).$$

$f_{12}, f_{13}$  are  $\geq 0$  for  $0 \leq \kappa \leq 1$ , and when  $\kappa \rightarrow 0$ ,  $f_{12} \rightarrow 2.65625$ ,  $f_{13} \rightarrow 0.46875$ .

From (3) and (74), the velocity potential  $\phi_4^1$  gives the induced flow over the surface

$$z \equiv z_{4,1} = -\frac{\delta}{d^3} \left( \frac{1}{4} f_{12} x^4 - \frac{1}{2} f_{13} k^2 x^2 y^2 \right) + f(y) \quad \dots \quad \dots \quad \dots \quad \dots \quad (75)$$

where  $f(y)$  is a (small) arbitrary function of  $y$ .

The basic solutions found in sections 5, 6, 7 will now be combined to determine the shape of a surface with swept-back leading edges, such that either:

- (i) there are no pressure singularities, the pressure becoming zero on the leading edges; or
- (ii) although the pressure, in general, becomes infinite on the leading edges, the strength of the pressure singularity increases from zero at the apex to a maximum value at some point on the leading edge, and then decreases to zero at a point on the leading edge further downstream.

There are five independent solutions giving surfaces of the two types considered. It will be shown how these five solutions can be combined to give the shapes of swept-back wings of type (ii), satisfying certain requirements with respect to camber and twist, or with respect to the aerodynamic characteristics.

8. *Two Wings Having no Pressure Singularities, at Design Incidence.*—By combining the two solutions given in section 6, or those given in section 7, it is possible to determine the shape of a thin wing with swept-back leading edges, which, at design incidence, has no pressure singularities, the pressure becoming zero at the leading edges.

- (i) Using the basic solutions for  $n = 3$ , we construct the velocity potential

$$\psi_3 = \phi_3^1 - k^2 \phi_3^2 = -3\beta^2 k^2 k^2 (\varphi_1 - \varphi_2)_{n=3} \quad \dots \quad \dots \quad \dots \quad \dots \quad (76)$$

Therefore, from Appendix IV, (IV,1),

$$(\psi_3)_{\mu=k} = \frac{V\delta}{d^2 k E(x)} X^3 \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (77)$$

where  $X \equiv (x^2 - k^2 y^2)^{1/2}$ ; and

$$\left( \frac{\partial \psi_3}{\partial x} \right)_{\mu=k} = \frac{3V\delta}{d^2 k E(x)} xX \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (78)$$

Using (59) and (57), the shape of the wing is given by

$$z = z_{3,1} - k^2 z_{3,2} = -\frac{\delta}{d^2} \left[ f_4 \left( \frac{\tan \gamma}{\tan \bar{\mu}} \right) x^3 - f_5 \left( \frac{\tan \gamma}{\tan \bar{\mu}} \right) k^2 x y^2 \right] + f(y) \quad \dots \quad \dots \quad (79)$$

where  $f_4 = \frac{1}{3}(f_6 + f_2)$  and  $f_5 = f_7 + f_3$ .

Using (5), the pressure coefficient for the upper surface of the wing (79) at design incidence is

$$C_{p0} = \frac{-6\delta}{d^2 k E(x)} xX \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (80)$$

The spanwise lift distribution  $l(y)$  is obtained by integrating  $-\rho V^2 C_{p0}$  along the chords of the wing. Thus for all chords lying outside the Mach cones of the trailing edge,

$$\begin{aligned} l(y) &= \int_{k y}^{x_1} -\rho V^2 C_{p0} dx = 2\rho V [\psi_3(x, y)]_{z=0} \\ &= \frac{2\rho V^2 \delta}{d^2 k E(x)} (x_1^2 - k^2 y^2)^{3/2} \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \end{aligned} \quad (81)$$

where  $x = x_1(y)$  defines the trailing edge.









and for a triangular wing of maximum chord  $c$ , the design lift coefficient is

$$C_{L0} = \frac{2\pi\delta}{kE(\kappa)} (1 - \sigma^2). \quad \dots \quad (104)$$

(v) Using the basic solutions  $\phi_1, \phi_4^1$ , we construct the induced velocity potential

$$\Phi_4^1 = \phi_1 - \phi_4^1 \quad \dots \quad (105)$$

for which

$$(\Phi_4^1)_{\mu=k} = \frac{Vc\delta}{\sigma kE(\kappa)} (1 - x'^3)X' \quad \dots \quad (106)$$

and the pressure coefficient is

$$C_{p0} = - \frac{2\delta}{kE(\kappa)} \left[ \frac{x'(1 - x'^3)}{X'} - 3x'^2X' \right]. \quad \dots \quad (107)$$

The strength of the pole on a leading edge is

$$P = \frac{V\delta}{kE(\kappa)} (1 - x'^3) \left( \frac{x'}{2} \right)^{1/2} \quad \dots \quad (108)$$

and  $P$  increases from 0 to a maximum as  $x'$  increases from 0 to  $(\frac{1}{7})^{1/3}$ , and decreases to 0 as  $x'$  increases to 1.

Using (35) and (75), the shape of the wing, at design incidence, is given by

$$z' = z_1' - z_{4,1}' = \delta(-x' + \frac{1}{4}f_{12}x'^4 - \frac{1}{2}f_{13}k^2x'^2y'^2) + f(y'). \quad \dots \quad (109)$$

The spanwise lift distribution is given by

$$l(y) = \frac{2\rho V^2 c \delta}{\sigma kE(\kappa)} (1 - x_1'^3)X_1' \quad \dots \quad (110)$$

and, for a triangular wing of maximum chord  $c$ , the design lift coefficient is

$$C_{L0} = \frac{2\pi\delta}{kE(\kappa)} (1 - \sigma^3). \quad \dots \quad (111)$$

Some further simple examples of wings of this type will now be given. These can be obtained directly from the 'basic' solutions, or by combining some of the solutions (i) to (v) given above.

(vi) The velocity potential

$$\Phi_3^2 = \Phi_3^1 + \psi_3 = \phi_1 - k^2\phi_3^2 \quad \dots \quad (112)$$

gives

$$(\Phi_3^2)_{\mu=k} = \frac{Vc\delta}{\sigma kE(\kappa)} (1 - k^2y'^2)X' \quad \dots \quad (113)$$

$$C_{p0} = \frac{-2\delta}{kE(\kappa)} \frac{x'(1 - k^2y'^2)}{X'} \quad \dots \quad (114)$$

$$z' = \delta(-x' - \frac{1}{3}f_2x'^3 + f_3k^2x'y'^2) + f(y'). \quad \dots \quad (115)$$

(vii) The velocity potential

$$\Phi_4^2 = \Phi_4^1 + \psi_4 = \phi_1 - k^2\phi_4^2 \quad \dots \quad (116)$$

gives

$$(\Phi_4^2)_{\mu=k} = \frac{Vc\delta}{\sigma kE(\kappa)} (1 - k^2x'y'^2)X' \quad \dots \quad (117)$$

$$C_{p_0} = -\frac{2\delta}{kE(\kappa)} \left[ \frac{x'(1 - k^2x'y'^2)}{X'} - k^2y'X' \right] \quad \dots \quad \dots \quad \dots \quad (118)$$

$$z' = \delta(-x' - \frac{1}{4}f_8x'^4 + \frac{1}{2}f_9k^2x'^2y'^2) + f(y'). \quad \dots \quad \dots \quad \dots \quad (119)$$

(viii) The velocity potential

$$\Phi_{3,4}^{1,2} = \psi_4 + \Phi_4^1 - \Phi_3^1 = \phi_3^1 - k^2\phi_4^2 \quad \dots \quad \dots \quad \dots \quad (120)$$

gives

$$(\Phi_{3,4}^{1,2})_{\mu=k} = \frac{Vc\delta}{\sigma kE(\kappa)} x'(x' - k^2y'^2)X' \quad \dots \quad \dots \quad \dots \quad (121)$$

$$C_{p_0} = \frac{-2\delta}{kE(\kappa)} \left[ \frac{x'^2(x' - k^2y'^2)}{X'} + (2x' - k^2y'^2)X' \right] \quad \dots \quad \dots \quad \dots \quad (122)$$

$$z' = \delta(-\frac{1}{3}f_6x'^3 + f_7k^2x'y'^2 - \frac{1}{4}f_8x'^4 + \frac{1}{2}f_9k^2x'^2y'^2) + f(y'). \quad \dots \quad (123)$$

In each case, the effect on the pressure distribution, of a (small) additional incidence  $\alpha$ , can be found by superposing the solution for a flat delta wing at incidence  $\alpha$  (see section 5), that is by adding the terms

$$\left. \begin{aligned} \Delta(C_p) &= -\frac{2\alpha x'}{kE(\kappa)X'} \\ \Delta(C_L) &= \frac{2\pi\alpha}{kE(\kappa)} \end{aligned} \right\} \quad \dots \quad \dots \quad \dots \quad \dots \quad (124)$$

to  $C_{p_0}$  and  $C_{L_0}$  respectively.

Some examples of the shape of and pressure distribution on wings of shape (iii), (vi), (vii), (viii) are shown in Figs. 14, 9, 10, 15.

9.1. *General Solution.*—Since we are using the linear theory of supersonic flow, a general solution for wings of the type considered can be obtained by combining the five independent solutions (i) to (v). In practice, it may be necessary to satisfy certain requirements with respect to the shape of the wing, and it is therefore useful to write down the following five solutions:

<i>Induced velocity potential</i>	<i>Shape of surface</i>
$\Omega_1 = \Phi_2$	$z' = \delta[-x' + f_1x'^2]$
$\Omega_2 = f_5\Phi_3^1 + f_7\psi_3$	$z' = \delta[-f_5x' + (\frac{1}{3}f_6f_5 - f_4f_7)x'^3]$
$\Omega_3 = f_{11}\Phi_4^1 + f_{13}\psi_4$	$z' = \delta[-f_{11}x' + \frac{1}{4}(f_{11}f_{12} - f_{10}f_{13})x'^4]$
$\Omega_4 = f_4\Phi_3^1 + \frac{1}{3}f_6\psi_3$	$z' = \delta[-f_4x' + (\frac{1}{3}f_6f_5 - f_4f_7)k^2x'y'^2]$
$\Omega_5 = f_{10}\Phi_4^1 + f_{12}\psi_4$	$z' = \delta[-f_{10}x' + \frac{1}{2}(f_{11}f_{12} - f_{10}f_{13})k^2x'^2y'^2]. \quad \dots \quad \dots \quad \dots \quad (125)$

In each case, a (small) arbitrary function of  $y'$  can be added to the expression for  $z'$ .

We shall take as a general solution

$$\Omega = \sum_{s=1}^5 (A_s\Omega_s), \quad \dots \quad \dots \quad \dots \quad \dots \quad (126)$$

where  $A_s$  is an arbitrary constant.

Regarding  $A_1$  as a scale factor, the solution contains the four arbitrary parameters  $A_s/A_1$ ,  $s = 2, 3, 4, 5$ .

The shape of the corresponding surface is given by

$$z' = ax' + bx'^2 + d_1x'^3 + fx'^4 + gk^2x'y'^2 + h_1k^2x'^2y'^2 + f(y') \quad \dots \quad (127)$$

where

$$\left. \begin{aligned} a &= -\delta(A_1 + A_2f_5 + A_3f_{11} + A_4f_4 + A_5f_{10}) \\ b &= \delta A_1f_1 \\ \frac{d_1}{A_2} &= \frac{g}{A_4} = \delta(\frac{1}{3}f_6f_5 - f_4f_7) \\ \frac{4f}{A_3} &= \frac{2h_1}{A_5} = \delta(f_{11}f_{12} - f_{10}f_{13}) \end{aligned} \right\} \dots \quad (128)$$

(126) may also be written

$$\Omega = A\Phi_2 + B\Phi_3^1 + C\psi_3 + D\Phi_4^1 + E\psi_4 \quad \dots \quad (129)$$

where

$$\left. \begin{aligned} A &= A_1 \\ B &= A_2f_5 + A_4f_4 \\ C &= A_2f_7 + \frac{1}{3}A_4f_6 \\ D &= A_3f_{11} + A_5f_{10} \\ E &= A_3f_{13} + A_5f_{12} \end{aligned} \right\} \dots \quad (130)$$

Hence, using the results (i) to (v), it can be shown that the corresponding pressure coefficient  $C_{p0}$ , the local spanwise lift coefficient  $C_{l0}$ , and the design lift coefficient  $C_{L0}$  for a triangular wing of maximum chord  $c$  are given by:

$$\begin{aligned} -C_{p0} &= \frac{2\delta}{kE(x)} A \left[ \left\{ \frac{x'(1-x')}{X'} - X' \right\} + B \left\{ \frac{x'(1-x'^2)}{X'} - 2x'X' \right\} \right. \\ &\quad + C(3x'X') + D \left\{ \frac{x'(1-x'^3)}{X'} - 3x'^2X' \right\} \\ &\quad \left. + E \left\{ X'^3 + 3x'^2X' \right\} \right]; \quad \dots \quad (131) \end{aligned}$$

$$\begin{aligned} C_{l0} &= \frac{4\delta}{kE(x)} \left( \frac{\sigma + ky'}{\sigma - ky'} \right)^{1/2} \left[ A(1-\sigma) + B(1-\sigma^2) + D(1-\sigma^3) \right. \\ &\quad \left. + (C + E\sigma)(\sigma^2 - k^2y'^2) \right], \quad (y' \geq 0); \quad \dots \quad (132) \end{aligned}$$

$$C_{L0} = \frac{2\pi\delta}{kE(x)} \left[ A(1-\sigma) + B(1-\sigma^2) + D(1-\sigma^3) + \frac{3}{4}(C + E\sigma)\sigma^2 \right]. \quad (133)$$

10. *Formulae for the Pitching-Moment Coefficients.*—The centre of pressure for a flat delta wing is at two-thirds the maximum chord from the vertex. For the wings considered in this report (maximum chord  $c$ ), the pitching moment is taken about this chordwise position. The corresponding moment coefficient is given by

$$\begin{aligned}
 C_{M0} &= -\frac{8k}{c^3} \int_0^c \int_0^{x/k} C_{p0} \left(\frac{2}{3}c - x\right) dy dx \\
 &= -\frac{8k}{\sigma^3} \int_0^\sigma \int_0^{x'/k} C_{p0} \left(\frac{2}{3}\sigma - x'\right) dy' dx' \dots \dots \dots (134)
 \end{aligned}$$

The formulae for surfaces (i) to (v) are as follows :

<i>Surface</i>	<i>Velocity Potential</i>	$\frac{kE(\kappa)}{2\pi\delta} C_{M0}$
(i)	$\psi_3$	$-\frac{1}{5}\sigma^2$
(ii)	$\psi_4$	$-\frac{1}{4}\sigma^3$
(iii)	$\Phi_2$	$\frac{1}{6}\sigma$
(iv)	$\Phi_3^1$	$\frac{4}{15}\sigma^2$
(v)	$\Phi_4^1$	$\frac{1}{3}\sigma^3$

The general formula is :

$$C_{M0} = \frac{2\pi\delta}{kE(\kappa)} \left[ A\left(\frac{1}{6}\sigma\right) + \left(\frac{4}{15}B - \frac{1}{5}C\right)\sigma^2 + \left(\frac{1}{3}D - \frac{1}{4}E\right)\sigma^3 \right] \dots \dots (135)$$

where  $A \dots E$  are given by (130).

It is thus possible to choose the constants  $A \dots E$ , so that, as one condition,  $C_{M0}$  has any given value.

11. *The Formulae for the Induced Drag at Design Incidence (Refs. 2 and 4).*—The drag on a body in fluid flow is the resultant in the free-stream direction of all the pressure forces acting on the body. In the linearised theory of supersonic (inviscid) flow the total drag, due to lift (usually termed the 'induced drag') is taken as the resultant axial force due to the lifting pressure distribution.

For a wing with no pressure singularities on the leading edges, the induced drag  $D_i$  is equal to the axial component of the pressure integral,  $D_p$ , and is given by

$$D_i = D_p = \rho V^2 \int \int C_{p0} \frac{\partial z}{\partial x} dx dy \dots \dots \dots (136)$$

where the integral is taken over the surface of the wing. The corresponding drag coefficient

is 
$$C_{Di} = \frac{D_i}{\left(\frac{1}{2}\rho V^2 S\right)}, \text{ where } S \text{ is the area of the wing.}$$

But, for a wing with pressure singularities on the leading edges, according to the linear theory, there is an infinite suction force or leading-edge thrust, determined by the strength of the singularity, as in subsonic flow. The component  $D_s$  of this suction force in the free-stream direction tends to reduce the induced drag, and the resultant induced drag is given by

$$D_i = D_p - D_s, \dots \dots \dots (137)$$

the corresponding drag coefficient being given by

$$C_{Di} = \frac{D_i}{(\frac{1}{2}\rho V^2 S)} = C_{Dp} - C_{Ds} \dots \dots \dots (138)$$

Using the result given in Appendix IV, Ref. 2, the longitudinal component of the suction force per unit length of a leading edge is :

$$\begin{aligned} T &= \pi\rho P^2(\cot^2\gamma - \cot^2\bar{\mu})^{1/2} \sin\gamma \\ &= \pi\rho P^2(k^2 - \beta^2)^{1/2} \sin\gamma \dots \dots \dots (139) \end{aligned}$$

where  $P$  is the strength of the singularity in the axial velocity on the leading edge (*cf.* after (93)) ; and hence

$$D_s = 2 \int_0^{x_1} T \frac{dx}{\cos\gamma} = 2\pi\rho \frac{(k^2 - \beta^2)^{1/2}}{k} \int_0^{x_1} P^2 dx \dots \dots \dots (140)$$

where  $x_1$  is the chordwise distance of the wing tip from the apex.

For a given spanwise lift distribution, the trailing vortex field in regions far behind the aerofoil is the same in supersonic as in subsonic flow (Ref. 2). It is therefore convenient to subdivide the induced drag into vortex drag, which is the same for supersonic as for subsonic flow, and induced wave drag, which appears only in supersonic flow. Thus the vortex-drag coefficient  $C_{Dv}$ , for a wing of aspect ratio  $A$ , is  $\varepsilon C_L^2/\pi A$  (Ref. 5), where  $\varepsilon$  depends upon the spanwise lift distribution of the aerofoil ; and the induced wave-drag coefficient is :

$$\begin{aligned} C_{Dw} &= C_{Di} - \varepsilon C_L^2/(\pi A) \\ &= C_{Dp} - C_{Ds} - \varepsilon C_L^2/(\pi A) \dots \dots \dots (141) \end{aligned}$$

To find the value of  $\varepsilon$ , the spanwise lift distribution  $l(y)$  must be expressed as a Fourier series of the form  $\sum_{n=1}^{\infty} (A_n \sin n\theta)$ , by putting  $ky = -c \cos\theta$ , ( $0 \leq |\theta| \leq \pi$ ,  $-c \leq ky \leq +c$ ).

Then

$$\varepsilon = \frac{\Sigma(nA_n^2)}{A_1^2} \dots \dots \dots (142)$$

(Ref. 5)

Note: The integrands in (136) and (140) are not linear, and therefore the drag coefficients for the separate surfaces (i) to (v) cannot be linearly superimposed to obtain a general solution.

If the velocity potential  $\Omega$  is given by (129), and the corresponding surface by (127), the general formulae for the drag coefficients are as follows : (Using the non-dimensional co-ordinates  $x' = x\sigma/c$ ,  $y' = y\sigma/c$ ,  $z' = z\sigma/c$ )

The pressure drag coefficient is :

$$\begin{aligned} C_{Dp} &= \frac{4k}{\sigma^2} \int_{y'=0}^{\frac{\sigma}{k}} \int_{x'=ky'}^{\sigma} C_{p0}(a + 2bx' + 3d_1x'^2 + 4fx'^3 + gk^2y'^2 + 2h_1k^2x'y'^2) dx' dy' \\ &= \frac{8\pi\delta}{kE(\kappa)} \left[ AP_1 + BP_2 + CP_3 + DP_4 + EP_5 \right] \dots \dots \dots (143) \end{aligned}$$

where  $A \dots \dots E$  are given by (130), and

$$\begin{aligned} P_1 &= - \left[ \frac{1}{4}a - \left( \frac{1}{4}a - \frac{1}{3}b \right) \sigma - \left( \frac{3}{8}b - \frac{3}{8}d_1 - \frac{1}{16}g \right) \sigma^2 \right. \\ &\quad \left. - \left( \frac{9}{20}d_1 - \frac{2}{5}f + \frac{1}{16}g - \frac{1}{10}h_1 \right) \sigma^3 - \left( \frac{1}{2}f + \frac{5}{48}h_1 \right) \sigma^4 \right], \end{aligned}$$

$$\begin{aligned}
P_2 &= - \left[ \frac{1}{4}a + \frac{1}{3}b\sigma - \left( \frac{1}{4}a - \frac{3}{8}d_1 - \frac{1}{16}g \right) \sigma^2 - \left( \frac{2}{5}b - \frac{2}{5}f - \frac{1}{10}h_1 \right) \sigma^3 \right. \\
&\quad \left. - \left( \frac{1}{2}d_1 + \frac{1}{16}g \right) \sigma^4 - \left( \frac{4}{7}f + \frac{3}{28}h_1 \right) \sigma^5 \right], \\
P_3 &= - 3\sigma^2 \left[ \frac{1}{16}a + \frac{1}{10}b\sigma + \left( \frac{1}{8}d_1 + \frac{1}{96}g \right) \sigma^2 + \left( \frac{1}{7}f + \frac{1}{36}h_1 \right) \sigma^3 \right], \\
P_4 &= - \left[ \frac{1}{4}a + \frac{1}{3}b\sigma + \left( \frac{3}{8}d_1 + \frac{1}{16}g \right) \sigma^2 - \left( \frac{1}{4}a - \frac{2}{5}f - \frac{1}{10}h_1 \right) \sigma^3 \right. \\
&\quad \left. - \frac{5}{12}b\sigma^4 - \left( \frac{1}{2}d_1 + \frac{1}{16}g \right) \sigma^5 - \left( \frac{5}{8}f + \frac{7}{24}h_1 \right) \sigma^6 \right], \\
P_5 &= - \sigma^3 \left[ \frac{3}{16}a + \frac{5}{16}b\sigma + \left( \frac{4}{112}d_1 + \frac{1}{32}g \right) \sigma^2 \right. \\
&\quad \left. + \left( \frac{1}{2}f + \frac{7}{28}h_1 \right) \sigma^3 \right]. \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \dots \quad (144)
\end{aligned}$$

The suction-drag coefficient is :

$$-C_{D_s} = - \frac{2\pi\delta^2(k^2 - \beta^2)^{1/2}}{\sigma^2 k^2 [E(\kappa)]^2} \int_0^\sigma x' [A(1 - x') + B(1 - x'^2) + D(1 - x'^3)]^2 dx'. \quad (145)$$

The total induced-drag coefficient is

$$C_{D_i} = C_{D_p} - C_{D_s}.$$

The vortex-drag coefficient is

$$C_{D_v} = \varepsilon C_L^2 / (\pi A), \quad \text{where}$$

$$\varepsilon = 1 + \frac{\frac{3}{16}\sigma^4(C + E\sigma)^2}{[A(1 - \sigma) + B(1 - \sigma^2) + D(1 - \sigma^3) + \frac{3}{4}\sigma^2(C + E\sigma)]^2}. \quad \dots \quad (146)$$

The induced wave-drag coefficient is

$$C_{D_w} = C_{D_i} - C_{D_v} = C_{D_p} - C_{D_s} - C_{D_v}.$$

The above formulae give the drag coefficients at design incidence. A formula for the total induced drag coefficient at any incidence is given at the end of section 12.

When  $\sigma \rightarrow 0$  (that is  $d/c \rightarrow \infty$ ), camber and twist tend to vanish, and the wing tends to become a flat delta wing, at incidence. It has been verified that, when  $\sigma \rightarrow 0$  (expressing the results in a form not involving the scale factor  $\delta$ ),

$$\begin{aligned}
C_{D_p} / (C_{L_0}^2 / \pi A) &\longrightarrow 2E(\kappa), \\
C_{D_p} / (C_{L_0}^2 / \pi A) &\longrightarrow (k^2 - \beta^2)^{1/2} / k = (1 - \tan^2 \gamma \cdot \cot^2 \bar{\mu})^{1/2}, \\
C_{D_v} / (C_{L_0}^2 / \pi A) &\longrightarrow 1
\end{aligned}$$

which are the results for the flat delta wing.

Some numerical examples of the total induced drag and the induced wave drag, for different values of  $\sigma$ , are shown in Figs. 6 to 17.

12. *Numerical Examples.*—Some numerical results, for specified values of  $\gamma$  and  $M$ , for wings of triangular plan form, are shown in Figs. 6 to 17. Formulae giving the shape of the wing, and the pressure distribution on the wing, are given below. Some notes on the choice of the arbitrary constants in the general solutions are given in examples (xiv), (xv), (xvi) at the end of this section.

The *non-dimensional co-ordinates*  $x' = x\sigma/c$ ,  $y' = y\sigma/c$ ,  $z' = z\sigma/c$  are used, where  $\sigma = c/d$ , and  $c$  is the maximum chord of the wing ( $1/\sigma$  measures the distance in maximum chord lengths, of the position of zero leading-edge pressure from the apex of the wing, except in examples (i) and (ii), where  $\sigma = 1$ . See Fig. 5). Since these co-ordinates are used throughout the numerical examples, the *dashes are dropped* in this section and in the figures. In each case ( $y$ ) is chosen so that  $z = 0$  on the leading edges.

Some numerical values of the pitching-moment coefficients and the drag coefficients for different values of  $\sigma$  or for a given  $\sigma$  and different lift coefficients, are given. When  $\sigma \rightarrow 0$ , these values tend to those for the corresponding flat delta wing, at incidence.

The formulae for the local spanwise lift, total lift, and drag coefficients are given in Appendix VII; the spanwise lift coefficient, for given  $\sigma$  and  $C_{L0}$ , are plotted against  $y$ , and the total induced-drag and wave-drag coefficients (in a form not involving the scale factor  $\delta$ ), against  $1/\sigma$ .

The examples given below, and shown in Figs. 6 to 17, are grouped under the headings :

- (1) wings with no leading-edge singularities ;
- (2) mainly twisted wings ;
- (3) mainly cambered wings ;
- (4) cambered and twisted wings.

Figs. 6 and 7 show the effect of removing the leading-edge pressure singularities ; Figs. 8 to 11 are cases of almost pure twist ; Figs. 12 and 13 are cases of camber and small twist ; and Figs. 14 to 17 show the effect of combined camber and twist.

Figs. 18 and 19 show application to wings of the solutions given in Figs. 8 and 14 respectively. These are constructed by selecting a definite plan form, which is then regarded as the front part of one of the curved plates. No allowance is made for tip loss in these calculations.

Figs. 20 to 22 show examples of wings which satisfy the following additional conditions : (for given  $\gamma$  and  $M$ , and  $\sigma = 1$ ):

In Fig. 20,  $C_{L0} = 0.1$ ,  $C_{M0} = 0$  (only one of a number of solutions which would satisfy these conditions).

In Fig. 21,  $C_{L0} = 0.1$ , zero camber and positive incidence at the root, positive camber elsewhere (not the only solution).

In Fig. 22,  $C_{L0} = 0.1$ , zero camber and positive incidence at the root, minimum induced drag (using the solutions for  $n = 1, 2, 3, 4$  given in this report). The solution is completely determined by these conditions.

The numbers (i), (ii) . . . . . (viii) of the examples correspond to those in sections 8, 9 of the report. For each example, a short table showing the values of the drag coefficients  $C_{Dw}$ ,  $C_{Dv}$ ,  $C_{Di}$  for given  $\sigma$  (taken as 1 in most cases), and different values of  $C_{L0}$ , and also those for the corresponding flat delta wing, at incidence, is given.

(1) *Wings with no leading-edge singularities*

(i) (cf. equations (76) to (83)) (Fig. 6)

$$\gamma = 45^\circ, \quad M = 1.166, \quad (\sigma = 1)$$

$$z = \delta[-0.658x^3 + 2.525xy^2] + f(y);$$

(in non-dimensional co-ordinates)

$$-C_{p0} = 4.7011\delta x(x^2 - y^2)^{1/2}$$

$$C_{M0}/C_{L0}$$

$$C_{Dv}/(C_{L0}^2/\pi A)$$

$$C_{Dw}/(C_{L0}^2/\pi A)$$

$$C_{Di}/(C_{L0}^2/\pi A)$$

$$-4/15$$

$$4/3$$

$$1.717$$

$$3.050$$

For the corresponding flat delta wing, at any incidence.

$$0$$

$$1$$

$$0.753$$

$$1.753$$

Drag coefficients, at design incidence				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dw}$	$C_{Dv}$	$C_{Di}$	$C_{Dw}$	$C_{Dv}$	$C_{Di}$
0.025	0.000085	0.000066	0.00015	0.000037	0.00005	0.000087
0.05	0.00034	0.00027	0.00061	0.00015	0.0002	0.00035
0.075	0.00077	0.00060	0.0014	0.00034	0.00044	0.00078
0.1	0.0014	0.0010	0.0024	0.00060	0.0008	0.0014
0.15	0.0031	0.0024	0.0055	0.0013	0.0018	0.0031
0.2	0.0054	0.0043	0.0097	0.0024	0.0032	0.0056

(ii) (cf. equations (84) to (90)) (Fig. 7)

$$\gamma = 30^\circ, \quad M = 1.852, \quad (\sigma = 1)$$

$$z = \delta[-0.678x^4 + 4.223x^2y^2] + f(y);$$

$$-C_{p0} = 0.7732\delta(4x^2 - 3y^2)(x^2 - 3y^2)^{1/2}$$

$$\frac{C_{M0}}{C_{L0}} \quad \frac{C_{Dv}}{(C_{L0}^2/\pi A)} \quad \frac{C_{Dw}}{(C_{L0}^2/\pi A)} \quad \frac{C_{Di}}{(C_{L0}^2/\pi A)}$$

$$-1/3 \quad 4/3 \quad 3.783 \quad 5.116$$

For the flat delta wing at any incidence

$$0 \quad 1 \quad 1.550 \quad 2.550$$

Drag coefficients, at design incidence				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dw}$	$C_{Dv}$	$C_{Di}$	$C_{Dw}$	$C_{Dv}$	$C_{Di}$
0.025	0.00033	0.00011	0.00044	0.00013	0.00009	0.00022
0.05	0.0013	0.00045	0.0018	0.00053	0.00035	0.00088
0.075	0.0029	0.0011	0.0040	0.0012	0.0008	0.0020
0.1	0.0052	0.0019	0.0071	0.0021	0.0014	0.0035
0.15	0.012	0.004	0.016	0.0048	0.0031	0.0079
0.2	0.021	0.007	0.028	0.0086	0.0055	0.0141

(2) Twisted wings (small camber)

(vi) (cf. equations (112) to (115))

(vi a)  $\gamma = 45^\circ, \quad M = 1.345$

$$z = \delta[-x - 0.069x^3 + 2.141xy^2] + f(y);$$

$$-C_{p0} = 1.3393\delta x(1 - y^2)(x^2 - y^2)^{-1/2}$$

$$\frac{1}{\sigma} \quad \frac{C_{M0}}{C_{L0}} \quad \frac{C_{Dv}}{(C_{L0}^2/\pi A)} \quad \frac{C_{Dw}}{(C_{L0}^2/\pi A)} \quad \frac{C_{Di}}{(C_{L0}^2/\pi A)}$$

$$1/2 \quad \quad \quad C_{L0} = 0$$

$$3/4 \quad 0.214 \quad 2.920 \quad 1.771 \quad 4.691$$

$$1 \quad 0.088 \quad 1.333 \quad 1.337 \quad 2.670$$

$$5/4 \quad 0.050 \quad 1.109 \quad 1.375 \quad 2.484$$

$$3/2 \quad 0.034 \quad 1.047 \quad 1.419 \quad 2.466$$

Flat delta wing at any incidence

$$0 \quad 1 \quad 1.550 \quad 2.550$$



Drag coefficients, at design incidence, when $\sigma = 1$				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$
0.025	0.000066	0.000066	0.00013	0.000050	0.000075	0.000125
0.05	0.00026	0.00027	0.00053	0.00020	0.00030	0.00050
0.075	0.00060	0.00060	0.0012	0.00045	0.00068	0.00113
0.1	0.0010	0.0011	0.0021	0.0008	0.0012	0.0020
0.15	0.0024	0.0024	0.0048	0.0018	0.0027	0.0045
0.2	0.0042	0.0043	0.0085	0.0032	0.0048	0.0080

(vi b)  $\gamma = 45^\circ$ ,  $M = 1.281$  (Fig. 9)

$$z = \delta(-x - 0.0767x^3 + 2.227xy^2) + f(y);$$

$$-C_{p0} = 1.4103\delta x(1 - y^2)(x^2 - y^2)^{-1/2}$$

$1/\sigma$	$C_{M0}/C_{L0}$	$C_{Dv}/(C_{L0}^2/\pi A)$	$C_{Dw}/(C_{L0}^2/\pi A)$	$C_{Di}/(C_{L0}^2/\pi A)$
1/2		$C_{L0} = 0$		
3/4	0.214	2.920	1.405	4.325
1	0.088	1.333	1.076	2.409
5/4	0.050	1.109	1.104	2.213
3/2	0.034	1.047	1.137	2.184
Flat delta wing at any incidence	0	1	1.236	2.236

Drag coefficients at design incidence, when $\sigma = 1$				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$
0.025	0.00007	0.00005	0.00012	0.000050	0.000061	0.00011
0.05	0.00027	0.00020	0.00047	0.00020	0.00024	0.00044
0.075	0.0006	0.0005	0.0011	0.00045	0.00055	0.0010
0.1	0.0010	0.0008	0.0019	0.00080	0.00098	0.0018
0.15	0.0024	0.0019	0.0043	0.0018	0.0022	0.0040
0.2	0.004	0.003	0.007	0.0032	0.0039	0.0071

(vii) (cf. equations (116) to (119)) (Fig. 10)

$$\gamma = 60^\circ, \quad M = 1.13$$

$$z = \delta[-x - 0.044x^4 + 0.398x^2y^2] + f(y);$$

$$-C_{p0} = 2.3198\delta[x(1 - \frac{1}{3}xy^2)(x^2 - \frac{1}{3}y^2)^{-1/2} - \frac{1}{3}y^2(x^2 - \frac{1}{3}y^2)^{1/2}]$$

$1/\sigma$	$C_{M0}/C_{L0}$	$C_{Dv}/(C_{L0}^2/\pi A)$	$C_{Dw}/(C_{L0}^2/\pi A)$	$C_{Di}/(C_{L0}^2/\pi A)$
3/4	0.484	7.347	4.900	12.247
1	0.110	1.333	1.381	2.714
5/4	0.048	1.065	1.406	2.471
3/2	0.026	1.019	1.459	2.478
2	0.010	1.003	1.510	2.513
Flat delta wing at any incidence	0	1	1.550	2.550

Drag coefficients at design incidence, for $\sigma = 1$				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$
0.025	0.000038	0.000040	0.000078	0.000029	0.000044	0.000073
0.05	0.00015	0.00016	0.00031	0.00011	0.00018	0.00029
0.075	0.00034	0.00036	0.00070	0.00026	0.00040	0.00066
0.1	0.00061	0.00063	0.0012	0.00046	0.00071	0.0012
0.15	0.0014	0.0014	0.0028	0.0010	0.0016	0.0026
0.2	0.0025	0.0025	0.0050	0.0018	0.0029	0.0047

(xii) [General solution (126), with  $A_1 = A_2 = A_3 = 0$ ,  $A_4 = 1$ ,  $A_5 = -0.1$ ]

$$\gamma = 45^\circ, \quad M = 1.281 \quad (\text{Fig. 11})$$

$$z = \delta[-0.4481x + 1.3956xy^2 - 0.2896x^2y^2] + f(y);$$

$$-C_{p0} = 1.41034\delta \left[ (0.4481x - 0.7085x^3 + 0.2604x^4) \frac{1}{X} + (0.4782x - 0.1815x^2 + 0.2407y^2)X \right], \text{ where } X \equiv (x^2 - y^2)^{1/2}$$

$1/\sigma$	$C_{M0}/C_{L0}$	$C_{Dv}/(C_{L0}^2/\pi A)$	$C_{Dw}/(C_{L0}^2/\pi A)$	$C_{Di}/(C_{L0}^2/\pi A)$
1	0.122	1.333	1.052	2.385
5/4	0.078	1.129	1.078	2.207
3/2	0.054	1.061	1.111	2.172
2	0.030	1.019	1.158	2.177
Flat delta wing at any incidence	0	1	1.236	2.236

Drag coefficients at design incidence, for $\sigma = 1$				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$
0.025	0.00007	0.00005	0.00012	0.00005	0.00006	0.00011
0.05	0.00026	0.00021	0.00047	0.0002	0.00024	0.00044
0.075	0.00060	0.00047	0.00107	0.00045	0.00055	0.0010
0.1	0.00106	0.00084	0.00190	0.0008	0.00098	0.0018
0.15	0.00239	0.00188	0.00427	0.0018	0.0022	0.0040
0.2	0.00424	0.00335	0.00759	0.0032	0.0039	0.0071

(3) *Cambered wings* (with small twist)

(ix) [General solution (126), with  $A_1 = A_2 = A_3 = -1$ ,  $A_4 = 4$ ,  $A_5 = 1.3$ ]

$$\gamma = 45^\circ, \quad M = 1.281 \quad (\text{Fig. 12})$$

$$z = \delta[-0.0279x - 0.7085x^2 - 1.3956x^3 - 1.4482x^4 + 5.5824xy^2 + 3.7653x^2y^2] + f(y);$$

$$-C_{p0} = 1.41034\delta \left[ (0.02794x + x^2 - 0.4597x^3 - 0.5682x^4) \frac{1}{X} + (1 + 6.2194x + 9.2952x^2 - 2.7500y^2)X \right], \text{ where}$$

$$X \equiv (x^2 - y^2)^{1/2}$$

$1/\sigma$	$C_{M0}/C_{L0}$	$C_{Dv}/(C_{L0}^2/\pi A)$	$C_{Dw}/(C_{L0}^2/\pi A)$	$C_{Di}/(C_{L0}^2/\pi A)$
1/2	-0.298	1.501	3.726	5.227
3/4	-0.280	1.411	2.780	4.191
1	-0.264	1.333	2.547	3.880
5/4	-0.250	1.270	2.393	3.663
3/2	-0.240	1.221	2.272	3.493
2	-0.224	1.151	2.103	3.254
Flat delta wing at any incidence	0	1	1.236	2.236

Drag coefficients at design incidence, for $\sigma = 1$				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$
0.025	0.00007	0.00012	0.00019	0.00005	0.00006	0.00011
0.05	0.00026	0.00051	0.00077	0.00020	0.00024	0.00044
0.075	0.0006	0.0011	0.0017	0.00045	0.00055	0.0010
0.1	0.0011	0.0020	0.0031	0.0008	0.00098	0.0018
0.15	0.0023	0.0046	0.0069	0.0018	0.0022	0.0040
0.2	0.0042	0.0081	0.0123	0.0032	0.0039	0.0071

The camber at 4 different spanwise positions, when  $\sigma = 1$ , is given by :

$y$	0	1/4	1/2	3/4
Camber per cent	138 $\delta$	128 $\delta$	99 $\delta$	56 $\delta$

In Fig. 12,  $\delta$  is taken equal to 0.01 ( $C_{L0} = 0.17$  when  $\sigma = 1$ ).

The relation between twist, camber and lift (at design incidence) is  
Twist/camber at root - camber at  $\frac{3}{4}$  semi-span/ $C_{L0} = 0.012/0.48/0.1$ .

(x) [General solution (126), with  $A_1=A_2=A_3 = -1$ ,  $A_4=10$ ,  $A_5 = -0.2$ ]

$$\gamma = 45^\circ, \quad M = 1.281 \quad (\text{Fig. 13})$$

$$z = \delta[-0.3739x - 0.7085x^2 - 1.3956x^3 - 1.4482x^4 + 13.956xy^2 - 0.5793x^2y^2] + f(y),$$

$$-C_{p0} = 1.41034\delta \left[ 0.3732 \frac{x}{X} + \frac{x^2}{X} - 4.7107 \frac{x^3}{X} + 3.3375 \frac{x^4}{X} + X + 9.0886xX + 7.4326x^2X - 0.8599X^3 \right]$$

$1/\sigma$	$C_{M0}/C_{L0}$	$C_{Dv}/(C_{L0}^2/\pi A)$	$C_{Dw}/(C_{L0}^2/\pi A)$	$C_{Di}/(C_{L0}^2/\pi A)$
1		1.333	2.553	3.886
3/2		1.358	2.124	3.482
1.69	-0.190	1.35	1.95	3.30
2	-0.160	1.273	1.805	3.078
Flat delta wing at any incidence	0	1	1.236	2.236

For this wing (x), on the leading edges at  $x = 1$ , and at  $x = 0.59$ ,  $C_{p0} = 0$ , and

$$\begin{aligned} 0 < x < 0.59, & \quad -C_{p0} = +\infty; \\ 0.59 < x < 1, & \quad -C_{p0} = -\infty; \\ x > 1, & \quad -C_{p0} = +\infty. \end{aligned}$$

Drag coefficients at design incidence, for $\sigma = 0.59$				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$
0.025	0.000067	0.000097	0.000164	0.00005	0.000061	0.00011
0.05	0.00026	0.00039	0.00065	0.0002	0.00024	0.00044
0.075	0.00060	0.00087	0.00147	0.00045	0.00055	0.0010
0.1	0.0011	0.0015	0.0026	0.00080	0.00098	0.0018
0.15	0.0024	0.0035	0.0059	0.0018	0.0022	0.0040
0.2	0.0043	0.0062	0.0105	0.0032	0.0039	0.0071

The camber at 4 different spanwise positions, when  $\sigma = 0.59$  (*i.e.*,  $1/\sigma = 1.69$ ), is given by:

$y$	0	1/8	1/4	3/8
Camber per cent	42 $\delta$	77 $\delta$	35 $\delta$	26 $\delta$

In Fig. 13,  $\delta$  is taken equal to 0.01 ( $C_{L0} = 0.066$  when  $\sigma = 0.59$ ).

The relation between twist, camber and lift is:

Twist/camber at root — camber at  $\frac{3}{4}$  semi-span/ $C_{L0} = 0.01/0.2/0.1$ .

(4) *Wings with camber and twist*

(iii) (*cf.* equations (91) to (97)) (Fig. 14)

$$\gamma = 45^\circ, \quad M = 1.166$$

$$z = \delta [-x + 0.658x^2] + f(y);$$

$$-C_{p0} = 1.56703\delta[x(1-x)(x^2-y^2)^{-1/2} - (x^2-y^2)^{1/2}]$$

$1/\sigma$	$C_{M0}/C_{L0}$	$C_{Dv}/(C_{L0}^2/\pi A)$	$C_{Dw}/(C_{L0}^2/\pi A)$	$C_{Di}/(C_{L0}^2/\pi A)$
1		$C_{L0} = 0$		
5/4	0.66	1	2.210	3.210
3/2	0.34	1	0.895	1.895
2	0.16	1	0.677	1.677
Flat delta wing at any incidence	0	1	0.752	1.752

Drag coefficients at design incidence, when $\sigma = 2/3$				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$
0.025	0.00005	0.000044	0.000094	0.00005	0.000037	0.000087
0.05	0.0002	0.00018	0.00038	0.0002	0.00015	0.00035
0.075	0.00045	0.00040	0.00085	0.00045	0.00033	0.00078
0.1	0.0008	0.00071	0.0015	0.0008	0.00060	0.0014
0.15	0.0018	0.0016	0.0034	0.0018	0.0013	0.0031
0.2	0.0032	0.0028	0.0060	0.0032	0.0024	0.0056

(viii) *cf.* equations (120) to (123)

$$\gamma = 30^\circ, \quad M = 1.852 \quad (\text{Fig. 15})$$

$$z = \delta[-0.661x^3 + 0.505xy^2 - 0.044x^4 + 3.575x^2y^2]$$

$$-C_{p0} = 0.7732\delta[x^2(x-3y^2)(x^2-3y^2)^{-1/2} + (2x-3y^2)(x^2-3y^2)^{1/2}]$$

$1/\sigma$	$C_{M0}/C_{L0}$	$C_{Dv}/(C_{L0}^2/\pi A)$	$C_{Dw}/(C_{L0}^2/\pi A)$	$C_{Di}/(C_{L0}^2/\pi A)$
1	-0.244	1.333	16.030	17.363
5/4	-0.250	1.188	11.840	13.028
3/2	-0.254	1.120	9.396	10.516
2	-0.256	1.061	6.405	7.466
Flat delta wing at any incidence	0	1	1.551	2.551

Drag coefficients at design incidence, for $\sigma = 1$				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$
0.025	0.0001	0.0014	0.0015	0.00009	0.00013	0.00022
0.05	0.0005	0.0055	0.0060	0.000344	0.000534	0.00088
0.075	0.001	0.012	0.013	0.00078	0.0012	0.0020
0.1	0.002	0.022	0.024	0.0014	0.0021	0.0035
0.15	0.004	0.050	0.054	0.0031	0.0048	0.0079
0.2	0.0073	0.0883	0.096	0.0055	0.0086	0.0141

(xiii) [General solution (129), with  $C = 4, B = 3, A = D = E = 0$ ]

$$\begin{aligned} \gamma &= 45^\circ, & M &= 1.281 & (\text{Fig. 16}) \\ z &= \delta[-3x - 0.9388x^3 + 9.0553xy^2] + f(y); \\ -C_{p0} &= 4.23102\delta[x(1-x^2)(x^2-y^2)^{-1/2} + 2x(x^2-y^2)^{1/2}] \end{aligned}$$

$1/\sigma$	$C_{M0}/C_{L0}$	$C_{Dv}/(C_{L0}^2/\pi A)$	$C_{Dw}/(C_{L0}^2/\pi A)$	$C_{Di}/(C_{L0}^2/\pi A)$
1/2	0	6.333	3.282	9.615
1	0	1.333	1.207	2.540
3/2	0	1.066	1.179	2.245
2	0	1.021	1.195	2.216
Flat delta wing at any incidence	0	1	1.236	2.236

The camber at 4 different spanwise positions, when  $\sigma = 1$ , is given by :

$y$	0	1/4	1/2	3/4
Camber per cent	36 $\delta$	33 $\delta$	26 $\delta$	15 $\delta$

In Fig. 16,  $\delta$  is taken equal to 0.01 ( $C_{L0} = 0.13$  for  $\sigma = 1$ ).

The relation between twist, camber and lift is :  
Twist/camber at root — camber at  $\frac{3}{4}$  semi-span /  $C_{L0} = 0.029/0.155/0.1$ .

Drag coefficients at design incidence, for $\sigma = 1$				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$
0.025	0.00007	0.00006	0.00013	0.00005	0.00006	0.00011
0.05	0.00026	0.00024	0.0005	0.00020	0.00024	0.00044
0.075	0.00060	0.00054	0.0011	0.00045	0.00055	0.0010
0.1	0.00106	0.00096	0.0020	0.00080	0.00098	0.0018
0.15	0.00239	0.00216	0.0045	0.0018	0.0022	0.0040
0.2	0.0424	0.00384	0.0081	0.0032	0.0039	0.0071

(xi) [General solution (126) with  $A_1 = A_2 = A_3 = 0$ ,  $A_4 = 5$ ,  $A_5 = -1$ ]

$$\gamma = 45^\circ, \quad M = 1.281 \quad (\text{Fig. 17})$$

$$z = \delta [-0.9387x + 6.978xy^2 - 2.8964x^2y^2] + f(y)$$

$$-C_{p0} = 1.41034\delta \left[ (0.9387x - 3.5425x^3 + 2.6038x^4) \frac{1}{X} + (2.391x - 1.815x^2 + 2.4066y^2)X \right], \quad X \equiv (x^2 - y^2)^{1/2}$$

$1/\sigma$	$C_{M0}/C_{L0}$	$C_{Dv}/(C_{L0}^2/\pi A)$	$C_{Dw}/(C_{L0}^2/\pi A)$	$C_{Di}/(C_{L0}^2/\pi A)$
3/4	-0.1	1.003	1.895	2.898
1	+0.082	1.333	1.108	2.441
5/4	+0.106	1.328	1.052	2.380
Flat delta wing at any incidence	0	1	1.236	2.236

Drag coefficients at design incidence, for $\sigma = 1$				For the corresponding flat delta wing, at incidence		
$C_{L0}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$	$C_{Dv}$	$C_{Dw}$	$C_{Di}$
0.025	0.00007	0.00005	0.00012	0.00005	0.00006	0.00011
0.05	0.00027	0.00022	0.00049	0.00020	0.00024	0.00044
0.075	0.0006	0.0005	0.0011	0.00045	0.00055	0.0010
0.1	0.0010	0.0009	0.0019	0.00080	0.00098	0.0018
0.15	0.0024	0.0020	0.0044	0.0018	0.0022	0.0040
0.2	0.0042	0.0036	0.0078	0.0032	0.0039	0.0071

The camber at 4 different spanwise positions, when  $\sigma = 1$ , is given by :

$y$	0	1/4	1/2	3/4
Camber per cent	0	3.39 $\delta$	9.05 $\delta$	10.18 $\delta$

In Fig. 17,  $\delta$  is taken equal to 0.1 ( $C_{L0} = 0.25$  for  $\sigma = 1$ ).

The relation between twist, camber and lift is :

$$\text{Twist/camber at } \frac{3}{4} \text{ semi-span} - \text{camber at root}/C_{L0} = 0.08/0.41/0.1.$$

### Three wings satisfying given conditions

In each of the following three examples,  $\sigma \equiv c/d = 1$ ,  $\gamma = 30^\circ$ ,  $M = 1.442$ .

(xiv) (Fig. 20)

Given conditions :  $C_{L0} = 0.1$ ,  $C_{M0} = 0$ .

[Other conditions could be also satisfied, cf. (133), (135)].

One possible solution is found by putting  $A = D = E = 0$ ,  $C = 4$ ,  $B = 3$  in the general solution (129). (cf. (135).)

$$C_{L0} = 0.1 \text{ gives } \delta = 0.0117277, \text{ and hence}$$

$$z = \delta [-3x - 0.9446x^3 + 29.3694xy^2] + f(y), \text{ and}$$

$$-C_{p0} = 0.0318309 \left[ (x - x^3) \frac{1}{X} + 2xX \right], \quad X \equiv (x^2 - 3y^2)^{1/2}$$

*Drag coefficients at  
design incidence*

$$\begin{aligned} C_{Dv} &= 0.00184 \\ C_{Dw} &= 0.00106 \\ C_{Di} &= 0.00290 \end{aligned}$$

*For the corresponding flat  
delta wing, at incidence*

$$\begin{aligned} C_{Dv} &= 0.00138 \\ C_{Dw} &= 0.00104 \\ C_{Di} &= 0.00242 \end{aligned}$$

The camber at 3 different spanwise positions is :

$y$	0	1/4	1/2
Camber per cent	0.426	0.339	0.104

The relation between twist, camber and lift is :

Twist/Camber at root — camber at  $\frac{3}{4}$  semi-span/ $C_{L0} = 0.05/0.24/0.1$ .

(xv) (Fig. 21)

Given conditions :

- (1) zero camber at the root,
- (2) positive (or approximately zero) camber elsewhere,
- (3) positive incidence at the root,
- (4)  $C_{L0} = 0.1$ .

Using (126), (127), (128), condition (1) gives  $A_1 = A_2 = A_3 = 0$ . The curvature of a section parallel to the  $x$ -axis is approximately equal to  $\partial^2 z / \partial x^2 = 2hk^2y^2$ . Hence, for positive camber,  $h < 0$ , and therefore  $A_5 < 0$ .

Condition (3) gives  $a < 0$ , or, taking  $A_5 = -1$ ,  $A_4 f_4 > f_{10}$ .

We should also ensure that the strength of the pressure singularity on a leading edge is  $\geq 0$  for  $x \leq 1$ . This leads to a second inequality to be satisfied by  $A_4$ . A value satisfying both inequalities is  $A_4 = 5.5$

$$C_{L0} = 0.1 \text{ then gives } \delta = 0.0467782.$$

Hence

$$\begin{aligned} C_{M0} &= 0.012 \quad \text{and} \\ z &= \delta[-1.2741x + 22.3396xy^2 - 7.9396x^2y^2] + f(y), \\ -C_{p0} &= 0.04232 \left[ (1.2741x - 3.6217x^3 + 2.3476x^4) \frac{1}{X} \right. \\ &\quad \left. + (2.0482x - 1.3348x^2 + 6.2832y^2)X \right], \quad X \equiv (x^2 - 3y^2)^{1/2} \end{aligned}$$

*Drag coefficients at  
design incidence*

$$\begin{aligned} C_{Dv} &= 0.00184 \\ C_{Dw} &= 0.00087 \\ C_{Di} &= 0.00271 \end{aligned}$$

*For the corresponding flat  
delta wing, at incidence*

$$\begin{aligned} C_{Dv} &= 0.00138 \\ C_{Dw} &= 0.00104 \\ C_{Di} &= 0.00242 \end{aligned}$$

The camber at 3 different spanwise positions is :

$y$	0	$1/(2\sqrt{3})$	$3/(4\sqrt{3})$
Camber per cent	0	0.387	0.435

The relation between twist, camber and lift is :  
Twist/Camber at  $\frac{3}{4}$  semi-span — camber at root/ $C_{L0} = 0.07/0.43/0.1$ .

(xvi) (Fig. 22)

Given conditions :

- (1) zero camber at the root,
- (2)  $C_{L0} = 0.1$ ,
- (3) minimum induced drag, with conditions (1), (2), (using the solutions for  $n = 1, 2, 3, 4$ ).

Using (126), (127), (128), condition (1) gives  $A_1 = A_2 = A_3 = 0$ . The condition  $C_{L0} = 0.1$  gives a relation between  $A_4\delta$  and  $A_5\delta$ , and hence the drag coefficient  $C_{Di}$  can be expressed as a function of  $A_5\delta$  or of  $A_4\delta$ . It is found that  $C_{Di}$  is least when  $A_4\delta = 0.171378$ ,  $A_5\delta = -0.023669$ .

For these values,  $C_{M0} = 0.013$ , and

$$z = -0.0573x + 0.6961xy^2 - 0.1879x^2y^2 + f(y),$$

$$-C_{p0} = 0.904725 \left[ (0.0573x - 0.1129x^2 + 0.0556x^3) \frac{1}{X} \right. \\ \left. + (0.0638x - 0.0316x^2 + 0.1487y^2)X \right], \quad X \equiv (x^2 - 3y^2)^{1/2}$$

*Drag coefficients at  
design incidence*

$$C_{Dv} = 0.00184$$

$$C_{Dw} = 0.00085$$

$$C_{Di} = 0.00269$$

*For the corresponding flat  
delta wing, at incidence*

$$C_{Dv} = 0.00138$$

$$C_{Dw} = 0.00104$$

$$C_{Di} = 0.00242$$

*The total induced-drag coefficient at any (small) incidence*

The total induced-drag coefficient, at any incidence, can be expressed in terms of the design lift coefficient  $C_{L0}$  and the lift coefficient  $\Delta C_L$  due to additional incidence  $\alpha$ .

If  $C_p, C_{p0}$  are the pressure coefficients, and  $C_L, C_{L0}$  the lift coefficients at additional incidence  $\alpha$  and design incidence respectively,

$$\Delta C_p \equiv C_p - C_{p0} = -\frac{2\alpha}{kE(\kappa)} \frac{x}{X},$$

$$\Delta C_L \equiv C_L - C_{L0} = \frac{2\pi}{kE(\kappa)} \alpha,$$

and, for a chosen wing, the scale factor  $\delta$  is proportional to  $C_{L0}$ , the relation between  $\delta$  and  $C_{L0}$  being given by (133).

The total induced-drag coefficient at additional incidence  $\alpha$  is

$$C_D \equiv C_{Di} + \Delta C_{Di} = \frac{4k}{\sigma^2} \int_{y=0}^{\sigma/h} \int_{x=ky}^{\sigma} (C_{p0} + \Delta C_p) \left( \frac{\partial z}{\partial x} - \alpha \right) dx dy \\ - \frac{2\pi(k^2 - \beta^2)^{1/2}}{\sigma^2 k^2 [E(\kappa)]^2} \int_0^{\sigma} x \left[ \delta \{A(1-x) + B(1-x^2) + D(1-x^3)\} + \alpha \right]^2 dx \\ = p_1 C_{L0}^2 + p_2 C_{L0} \Delta C_L + p_3 (\Delta C_L)^2, \dots \dots \dots (147)$$



where

$$\begin{aligned}
 p_1 &= \frac{C_{Di}}{C_{L0}^2}, \\
 p_2 &= \frac{kE(\kappa)}{2\pi} - \left[ \frac{kE(\kappa)}{2\pi} \left\{ a' + \frac{4}{3}b'\sigma + \frac{3}{2}d_1'\sigma^2 + \frac{8}{5}f'\sigma^3 + \frac{1}{4}g'\sigma^2 + \frac{2}{5}h_1'\sigma^3 \right\} \right. \\
 &\quad \left. + \frac{(k^2 - \beta^2)^{1/2}}{2\pi} \left\{ (A + B + D) - \frac{2}{3}A\sigma - \frac{1}{2}B\sigma^2 - \frac{2}{3}D\sigma^3 \right\} \right] / [A(1 - \sigma) \\
 &\quad + B(1 - \sigma^2) + D(1 - \sigma^3) + \frac{3}{4}(C + E\sigma)\sigma^2],
 \end{aligned}$$

where  $a' = a/\delta$ ,  $b' = b/\delta$ , etc.,

$$p_3 = \frac{kE(\kappa)}{2\pi} - \frac{k\kappa}{4\pi} \quad [\text{Since } (k^2 - \beta^2)^{1/2} = h = k\kappa]$$

(147) may also be written in the form

$$\frac{C_D}{C_L^2} = p_1 \frac{C_{L0}^2}{C_L^2} + p_2 \frac{C_{L0}}{C_L} \left( 1 - \frac{C_{L0}}{C_L} \right) + p_3 \left( 1 - \frac{C_{L0}}{C_L} \right)^2 \quad \dots \quad (148)$$

The values of  $p_1$ ,  $p_2$ ,  $p_3$  have been calculated for surfaces (i) to (xvi) for specified  $\gamma$  and  $M$ ; in each case  $\sigma$  is chosen so that the point of zero pressure on a leading edge is at the wing tip, that is  $\sigma = 1$ , except for surface (x), where  $\sigma = 0.59$ . The resulting formulae for the induced-drag coefficients are given below:

Surface	$C_D \equiv C_{Di} + \Delta C_{Di}$
(i)	$0.2427C_{L0}^2 + 0.2995C_{L0}(\Delta C_L) + 0.1395(\Delta C_L)^2$
(ii)	$0.7052C_{L0}^2 + 0.6980C_{L0}(\Delta C_L) + 0.3516(\Delta C_L)^2$
(vi a)	$0.2125C_{L0}^2 + 0.2722C_{L0}(\Delta C_L) + 0.1395(\Delta C_L)^2$
(vi b)	$0.3628C_{L0}^2 + 0.3300C_{L0}(\Delta C_L) + 0.1780(\Delta C_L)^2$
(vii)	$0.1247C_{L0}^2 + 0.2136C_{L0}(\Delta C_L) + 0.1172(\Delta C_L)^2$
(xii)	$0.1898C_{L0}^2 + 0.3267C_{L0}(\Delta C_L) + 0.1780(\Delta C_L)^2$
(ix)	$0.3087C_{L0}^2 + 0.3654C_{L0}(\Delta C_L) + 0.1780(\Delta C_L)^2$
(x) ( $\sigma = 0.59$ )	$0.2629C_{L0}^2 + 0.3586C_{L0}(\Delta C_L) + 0.1780(\Delta C_L)^2$
(iii)	$0.5403\delta^2 - 0.0863\delta(\Delta C_L) + 0.1395(\Delta C_L)^2$ (for this surface for $\sigma = 1$ , $C_{L0} = 0$ , $\delta$ is proportional to the design incidence)
(viii)	$2.3932C_{L0}^2 + 0.6938C_{L0}(\Delta C_L) + 0.3516(\Delta C_L)^2$
(xiii)	$0.2022C_{L0}^2 + 0.3393C_{L0}(\Delta C_L) + 0.1780(\Delta C_L)^2$
(xi)	$0.1942C_{L0}^2 + 0.3315C_{L0}(\Delta C_L) + 0.1780(\Delta C_L)^2$
(xiv)	$0.2899C_{L0}^2 + 0.4725C_{L0}(\Delta C_L) + 0.2416(\Delta C_L)^2$
(xv)	$0.2713C_{L0}^2 + 0.4542C_{L0}(\Delta C_L) + 0.2416(\Delta C_L)^2$
(xvi)	$0.2694C_{L0}^2 + 0.4505C_{L0}(\Delta C_L) + 0.2416(\Delta C_L)^2$

The above formulae hold for all (small) positive or negative values of  $\Delta C_L$ . It can be verified that the condition  $p_2^2 - 4p_1p_3 < 0$  for positive drag is satisfied in each case. A table of values of  $C_D$ , and the corresponding values for the flat delta wing is given below.

Surface	$C_{L0}$	$C_L$	$C_D \equiv C_{Di} + \Delta C_{Di}$	The corresponding flat delta wing
				$C_D$
(i)	0.1	0.05	0.00128	0.00035
		0.1	0.00243	0.00139
		0.15	0.00427	0.00314
		0.2	0.00682	0.00558
(ii)	0.1	0.05	0.00444	0.00088
		0.1	0.00705	0.00352
		0.15	0.01142	0.00791
		0.2	0.01755	0.01406
(vi a)	0.1	0.05	0.00111	0.00035
		0.1	0.00212	0.00139
		0.15	0.00383	0.00314
		0.2	0.00624	0.00558
(vi b)	0.1	0.05	0.00242	0.00044
		0.1	0.00363	0.00178
		0.15	0.00572	0.00400
		0.2	0.00871	0.00712
(vii)	0.1	0.05	0.00047	0.00029
		0.1	0.00125	0.00117
		0.15	0.00261	0.00264
		0.2	0.00456	0.00469
(xii)	0.1	0.05	0.00071	0.00044
		0.1	0.00190	0.00178
		0.15	0.00398	0.00400
		0.2	0.00695	0.00712
(ix)	0.1	0.05	0.00170	0.00044
		0.1	0.00309	0.00178
		0.15	0.00536	0.00400
		0.2	0.00852	0.00712
(xi)	0.1	0.05	0.00128	0.00044
		0.1	0.00263	0.00178
		0.15	0.00487	0.00400
		0.2	0.00800	0.00712
(iii)	0 ( $\delta=0.01$ )	0.05	0.00532	0.00035
		0.1	0.00593	0.00139
		0.15	0.00725	0.00314
		0.2	0.00926	0.00558
(viii)	0.1	0.05	0.02134	0.00088
		0.1	0.02393	0.00351
		0.15	0.02828	0.00791
		0.2	0.03439	0.01406

				The corresponding flat delta wing
Surface	$C_{L0}$	$C_L$	$C_D \equiv C_{Di} + \Delta C_{Di}$	$C_D$
(xiii)	0.1	0.05	0.00077	0.00044
		0.1	0.00202	0.00178
		0.15	0.00416	0.00400
		0.2	0.00719	0.00712
(xi)	0.1	0.05	0.00073	0.00044
		0.1	0.00194	0.00178
		0.15	0.00404	0.00400
		0.2	0.00704	0.00712
(xiv)	0.1	0.05	0.00114	0.00060
		0.1	0.00290	0.00242
		0.15	0.00587	0.00544
		0.2	0.01004	0.00966
(xv)	0.1	0.05	0.00105	0.00060
		0.1	0.00271	0.00242
		0.15	0.00559	0.00544
		0.2	0.00967	0.00966
(xvi)	0.1	0.05	0.00105	0.00060
		0.1	0.00269	0.00242
		0.15	0.00555	0.00544
		0.2	0.00961	0.00966

For  $\sigma = 1$  and  $C_L > C_{L0}$ , it can be shown that  $C_D$  is less than the induced-drag coefficient  $C_{Di}$  of the same surface (at design incidence) designed for lift coefficient  $C_L$ , *e.g.*, for (xvi), if  $C_{L0} = 0.1$  and  $C_L = 0.2$ ,  $C_D = 0.00961$ ; and if  $C_{L0} = C_L = 0.2$ ,  $C_D = C_{Di} = 0.01076$ .

It can also be shown, that for  $C_L > C_{L0}$  ( $\sigma = 1$ ), if  $p_2 - 2p_3 > 0$ ,  $C_D$  is greater than the corresponding  $C_D$  for the flat delta wing for all  $C_L$ ; and if  $p_2 - 2p_3 < 0$ ,  $C_D$  is less than the corresponding  $C_D$  for the flat delta wing when  $C_L > \frac{p_1 + p_3 - p_2}{2p_3 - p_2} C_{L0}$  ( $p_1 + p_3 - p_2$  is always  $> 0$ ), *e.g.*, for (xvi), when  $C_L > 0.185$ .

13. *Conclusion.*—Solutions of the linearised supersonic flow equations in terms of the Lamé functions of the  $M$ -class, of degree 1, 2, 3, 4 have been found, and have been combined to give a general solution for the velocity potential of the supersonic flow over swept-back wings, with modified pressure singularities on the leading edges. The solutions have been chosen so that the strength of these singularities decreases towards the wing tips. By removing the suction peaks near the leading edges of the outboard sections of the wing, the associated adverse pressure gradients are reduced, thereby reducing the tendency for the boundary layer to separate.

A number of examples for specified values of the apex angle  $\gamma$  and the Mach number  $M$ , have been worked out, and the corresponding lift, induced drag and pitching-moment coefficients calculated. The effect of additional incidence on the total induced drag coefficient has also been calculated (*cf.* end of section 12).

For the wings with no leading-edge singularities, the total induced drag is considerably higher than for the corresponding flat delta wing; but for the wings with leading-edge singularities, decreasing towards the wing tips, in some cases, for  $1/\sigma$  greater than some value ( $> 1$ ) (that

is a value for which the point of zero pressure on a leading edge is downstream of the wing tip), the total induced drag is less than that for the corresponding flat delta wing (*cf.* Figs. 10b, 11b, 14b, 16b). An example is given (Fig. 22) of a wing designed for a given lift coefficient and minimum total induced drag, with the condition that there is no camber at the root.

An attempt was made to find a solution giving a surface with increasing camber towards the wing tips and little or no twist. Examination of the conditions required showed that this is not possible, at any rate with the general solution so far found. But solutions giving surfaces with increasing (or constant) camber and some twist can be found (*cf.* Fig. 17).

By including solutions for higher values of  $n$ , a still more general solution could be found. The complexity of the algebra increases with the value of  $n$ , but the basic solutions, once found, contribute to an unlimited number of other solutions.

The examples of wings given in this report are designed, in each case, for a specified Mach number. The effect of a change of Mach number on the aerodynamic characteristics of the wing is being considered, and the results will be given in another report.

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#### LIST OF SYMBOLS

$\gamma$	Apex semi-angle	
$c$	Maximum chord of a triangular wing	
$d$	Chordwise distance behind the apex of the point of zero pressure on a leading edge	
or $d$	An arbitrary length, for wings with no pressure singularities (i), (ii)	
$1/\sigma \equiv d/c$	Chordwise distance, in maximum chord lengths, behind the apex of the point of zero pressure on a leading edge	
or $1/\sigma \equiv d/c$	An arbitrary constant, for wings with no pressure singularities (i), (ii)	
$S$	Area of triangular wing	
$x$	Chordwise co-ordinate (measured downstream from the apex)	
$y$	Spanwise co-ordinate (positive to starboard)	
$z$	Normal co-ordinate (positive upwards)	
$x' = x\sigma/c$	}	Non-dimensional co-ordinates (The dashes are dropped in the numerical examples)
$y' = y\sigma/c$		
$z' = z\sigma/c$		
$r$	}	<i>cf.</i> equations (1), (2)
$\mu$		
$\nu$		

$\delta$	A small dimensionless constant (proportional to the design lift coefficient $C_{L0}$ )
$\alpha$	Angle of incidence (measured in radians)
$X$	$(x^2 - k^2y^2)^{1/2}$
$X_1$	$(x_1^2 - k^2y^2)^{1/2}$
$x = x_1(y)$	Defines the trailing edge of the wing
$\rho$	Free-stream density
$V$	Free-stream velocity
$\bar{\mu}$	Mach angle
$M$	Mach number
$\beta$	$(M^2 - 1)^{1/2}$
$k$	$\cot \gamma$
$h$	$(\cot^2 \gamma - \cot^2 \bar{\mu})^{1/2} = (k^2 - \beta^2)^{1/2}$
$\varkappa$	$h/k$
$f_1, f_2, \dots, f_{13}$	Functions of $(\tan \gamma / \tan \bar{\mu})$ given in Appendices I, II
$A_s$	<i>cf.</i> equation (126)
$A, B, C, D, E$	<i>cf.</i> equation (130)
$a, b, d, f, g, h$	<i>cf.</i> equations (127), (128)
$E_n(\mu)$	Standard Lamé function of degree $n$
$F_n(\mu)$	Lamé function of the second kind of degree $n$
$M_n(\mu)$	Standard Lamé function of degree $n$ , of the $M$ -class
$P_n(\mu)$	$M_n(\mu) / (\mu^2 - k^2)^{1/2}$
$K(\varkappa)$	Complete elliptic integral of the first kind, modulus $\varkappa$
$E(\varkappa)$	Complete elliptic integral of the second kind, modulus $\varkappa$
$c_r (r = 1, 2, \dots, 2N+1)$	A zero of $P_{2N+1}(\mu)$
$d_r (r = 1, 2, \dots, 2N)$	A zero of $P_{2N}(\mu)$
$H$	$V\delta / (kE(\varkappa))$ (in Appendix VI)
$P$	Strength of singularity in axial velocity on a leading edge
$\varphi$	Velocity potential, <i>cf.</i> equation (3), etc.
$\phi$	Velocity potential, <i>cf.</i> equations (17), (27), and sections 5, 6, 7
$\Phi$	Velocity potential, <i>cf.</i> section 9, etc.
$\psi$	Velocity potential, <i>cf.</i> section 8, etc.
$\Omega$	Velocity potential, <i>cf.</i> equations (126), (129)
$\Delta p$	Pressure on an element of the upper surface of the wing
$C_p$	Pressure coefficient
$C_{p0}$	Design pressure coefficient
$l(y)$	Spanwise lift distribution

$C_{l_0}$	Local spanwise lift coefficient at design incidence
$C_L$	Lift coefficient (based on area)
$C_{L0}$	Design lift coefficient
$C_{M0}$	Pitching-moment coefficient
$D_p$	Pressure integral
$D_s$	Suction force at leading edge
$D_i = D_p - D_s$	Total drag due to lift (induced drag), at design incidence
$C_{Di}$	Total induced-drag coefficient, at design incidence, based on area
$C_{Dv}$	Vortex drag coefficient, at design incidence, based on area
$C_{Dw} = C_{Di} - C_{Dv}$	Induced wave-drag coefficient, at design incidence, based on area
$\Delta C_p$	Pressure coefficient due to additional incidence $\alpha$
$\Delta C_L = C_L - C_{L0}$	Lift coefficient due to additional incidence $\alpha$
$\Delta C_{Di}$	Total induced-drag coefficient due to additional incidence $\alpha$
$\phi_1, \phi_2, \phi_3$	cf. equation (147)
$C_D \equiv C_{Di} + \Delta C_{Di}$	Total induced-drag coefficient at (additional) incidence $\alpha$
$\bar{P}$	cf. Appendix VII.

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APPENDIX I

The functions  $f_1(\tan \gamma/\tan \bar{\mu}), f_2(\tan \gamma/\tan \bar{\mu}), \dots, f_{13}(\tan \gamma/\tan \bar{\mu})$ .  
 $\kappa^2 = 1 - (\tan^2 \gamma/\tan^2 \bar{\mu})$ ;  $K, E$  are written for  $K(\kappa), E(\kappa)$ .

Solutions in which the functions occur are given in brackets [ ].

$$\begin{aligned}
 f_1 &= \{(2\kappa^2 - 1)E + (1 - \kappa^2)K\}/(2\kappa^2 E) && [\phi_3] \\
 f_2 &= \{(2 - \kappa^2)E - 2(1 - \kappa^2)K\}/(2\kappa^4 E) && \\
 f_3 &= \{(1 - \kappa^2)(2 - 5\kappa^2)K - 2(1 - 3\kappa^2 - \kappa^4)E\}/(2\kappa^4 E) && \} [\phi_3^2] \\
 f_4 &= \{(2\kappa^2 - 1)E + (1 - \kappa^2)K\}/(2\kappa^2 E) = f_1 && \\
 f_5 &= 3\{(1 + \kappa^2)E - (1 - \kappa^2)K\}/(2\kappa^2 E) && \} [\psi_3] \\
 f_6 &= \{(1 - \kappa^2)(2 + 3\kappa^2)K - 2(1 + \kappa^2 - 3\kappa^4)E\}/(2\kappa^4 E) && \\
 f_7 &= \{(2 - 3\kappa^2 + \kappa^4)E - 2(1 - \kappa^2)^2 K\}/(2\kappa^4 E) && \} [\phi_3^1] \\
 f_8 &= \{(8 - 3\kappa^2 - 2\kappa^4)E - (1 - \kappa^2)(8 + \kappa^2)K\}/(6\kappa^6 E) && \\
 f_9 &= \{(1 - \kappa^2)(8 - 13\kappa^2 + 2\kappa^4)K && \\
 &\quad - (8 - 17\kappa^2 + 7\kappa^4 - 4\kappa^6)E\}/(2\kappa^6 E) && \} [\phi_4^2] \\
 f_{10} &= \{2(1 - \kappa^2)(1 + 2\kappa^2)K - (2 + 3\kappa^2 - 8\kappa^4)E\}/(2\kappa^4 E) && \\
 f_{11} &= 3\{2(1 - \kappa^2 + \kappa^4)E - (1 - \kappa^2)(2 - \kappa^2)K\}/(2\kappa^4 E) && \} [\psi_4] \\
 f_{12} &= \{(1 - \kappa^2)(8 + 7\kappa^2 + 12\kappa^4) && \\
 &\quad - (8 + 3\kappa^2 + 7\kappa^4 - 24\kappa^6)\}/(6\kappa^6 E) && \\
 f_{13} &= \{(8 - 11\kappa^2 + \kappa^4 + 2\kappa^6)E && \\
 &\quad - (1 - \kappa^2)(8 - 7\kappa^2 - \kappa^4)K\}/(2\kappa^6 E) && \} [\phi_4^1]
 \end{aligned}$$

APPENDIX II

*The Functions  $f_1, f_2, \dots, f_{13}$ . Numerical Values*

$\frac{\tan \gamma}{\tan \bar{\mu}}$	$\kappa^2$	$f_1$	$f_2$	$f_3$	$f_4$	$f_5$	$f_6$	$f_7$	$f_8$	$f_9$	$f_{10}$	$f_{11}$	$f_{12}$	$f_{13}$
0	1	0.5	0.5	3.0	0.5	3.0	1.0	0	0.5	3.0	1.5	3.0	1.0	0
0.1	0.99	0.5135	0.4781	2.9552	0.5135	2.9600	1.0624	0.0048	0.4711	2.9602	1.5751	2.9744	1.1040	0.0142
0.2	0.96	0.5390	0.4396	2.8655	0.5390	2.8831	1.1774	0.0176	0.4234	2.8850	1.7163	2.9358	1.2929	0.0508
0.3	0.91	0.5690	0.3977	2.7570	0.5690	2.7929	1.3093	0.0359	0.3742	2.7992	1.8786	2.9002	1.5044	0.1010
0.4	0.84	0.6000	0.3571	2.6428	0.6000	2.6999	1.4429	0.0571	0.3287	2.7135	2.0430	2.8713	1.7143	0.1578
0.5	0.75	0.6300	0.3197	2.5298	0.6300	2.6097	1.5703	0.0799	0.2884	2.6332	2.2007	2.8495	1.9123	0.2163
0.6	0.64	0.6585	0.2861	2.4217	0.6585	2.5247	1.6894	0.1030	0.2532	2.5603	2.3476	2.8338	2.0944	0.2735
0.7	0.51	0.6845	0.2566	2.3206	0.6845	2.4463	1.7969	0.1257	0.2234	2.4951	2.4817	2.8235	2.2583	0.3284
0.8	0.36	0.7085	0.2303	2.2270	0.7085	2.3743	1.8952	0.1473	0.1972	2.4381	2.6038	2.8167	2.4066	0.3786
0.9	0.19	0.7300	0.2080	2.1408	0.7300	2.3093	1.9820	0.1685	0.1760	2.3850	2.7125	2.8146	2.5365	0.4306
1.0	0	0.7500	0.1875	2.0625	0.7500	2.2500	2.0625	0.1875	0.1562	2.3437	2.8125	2.8125	2.6562	0.4687



APPENDIX III

$$\text{Integration of } I \equiv \int_h^\infty \frac{d}{dt} \left[ \frac{1}{t [P_n(t)]^2 (t^2 - h^2)^{1/2}} \right] \frac{dt}{(t^2 - k^2)^{1/2}}$$

$M_n(\mu) = (|\mu^2 - k^2|)^{1/2} P_n(\mu)$  is a solution of Lamé's equation, and it is easy to show that the differential equation satisfied by  $P_n(\mu)$  is

$$\begin{aligned} & (\mu^2 - h^2)(\mu^2 - k^2) \frac{d^2 P}{d\mu^2} + \mu(4\mu^2 - 3h^2 - k^2) \frac{dP}{d\mu} \\ & + [\rho(h^2 + k^2) - h^2 - (n^2 + n - 2)\mu^2]P = 0. \quad \dots \dots \dots \text{(III,1)} \end{aligned}$$

The roots of  $P_n(\mu) = 0$  are all real and unequal, and not equal to  $\pm h$  or  $\pm k$  (Ref. 3), therefore  $P_n(\mu)$  can be expressed in the form

$$P_n(\mu) \equiv P_{2N+1}(\mu) = \prod_{r=1}^N (\mu^2 - c_r), \text{ if } n \text{ is odd, } \dots \dots \dots \text{(III,2)}$$

where the  $c_r$ 's are real and unequal; and

$$P_n(\mu) \equiv P_{2N}(\mu) = \mu \prod_{r=1}^{N-1} (\mu^2 - d_r), \text{ if } n \text{ is even, } \dots \dots \dots \text{(III,3)}$$

where the  $d_r$ 's are real and unequal,  $N$  being a positive integer.

Substituting (III,2) in (III,1), and putting  $\mu^2 = c_r$ , it can be shown, after some simplification, that

$$\frac{1}{2c_r} \left\{ 5 + \frac{h^2}{c_r - h^2} + \frac{3k^2}{c_r - k^2} \right\} + 2 \sum_{s=1}^N \left( \frac{1}{c_r - c_s} \right) = 0. \quad \dots \dots \text{(III,4)}$$

$s \neq r.$

Similarly, by substituting (III,3) in (III,1), and putting  $\mu^2 = d_r$ , it can be shown that

$$\frac{1}{2d_r} \left\{ 7 + \frac{h^2}{d_r - h^2} + \frac{3k^2}{d_r - k^2} \right\} + 2 \sum_{s=1}^{N-1} \left( \frac{1}{d_r - d_s} \right) = 0. \quad \dots \dots \text{(III,5)}$$

$s \neq r.$

For  $n = 2N+1$ ,

$$\begin{aligned} \frac{1}{[P_n(t)]^2} & \equiv \frac{1}{[P_{2N+1}(t)]^2} = \frac{1}{\prod_{r=1}^N (t^2 - c_r)^2} \\ & = \sum_{r=1}^N \left[ \frac{A_r^2}{(t^2 - c_r)^2} + \frac{2A_r}{t^2 - c_r} \sum_{s=1}^N \left( \frac{A_s}{c_r - c_s} \right) \right], \quad s \neq r \quad \dots \dots \dots \text{(III,6)} \end{aligned}$$

where  $A_r = \frac{1}{P_{2N+1}'(c_r)}$ , the dash indicating differentiation with respect to the argument  $c_r$ , and  $P_{2N+1}(c_r) \equiv [P_{2N+1}(t)]_{t=c_r}$ .

Therefore

$$\begin{aligned} (I)_{n=2N+1} & = \sum_{r=1}^N \left[ A_r^2 \int_h^\infty \frac{d}{dt} \left( \frac{1}{t(t^2 - c_r)^2 (t^2 - h^2)^{1/2}} \right) \frac{dt}{(t^2 - k^2)^{1/2}} \right. \\ & \quad \left. + 2A_r \sum_{s=1}^N \left( \frac{A_s}{c_r - c_s} \right) \left\{ \int_h^\infty \frac{d}{dt} \left( \frac{1}{t(t^2 - c_r)(t^2 - h^2)^{1/2}} \right) \frac{dt}{(t^2 - k^2)^{1/2}} \right\} \right] \\ & \equiv \sum_{r=1}^N \left[ A_r^2 \left\{ I_1 + \frac{2}{A_r} I_2 \sum_{s=1}^N \left( \frac{A_s}{c_r - c_s} \right) \right\} \right], \quad s \neq r. \quad \dots \dots \dots \text{(III,7)} \end{aligned}$$

To evaluate  $I_1$  and  $I_2$ , we put  $t = k \operatorname{ns} u$ , where  $\operatorname{ns} u$  is a Jacobian elliptic function of modulus  $h/k$ , and write  $h/k = \kappa$ ,  $c_r/k^2 = \varepsilon_r^2$ . The first and second complete elliptic integrals, with modulus  $\kappa$ , are denoted by  $K$ ,  $E$  respectively.

It can be shown that

$$\begin{aligned}
 k^2 I_1 &= - \int_0^{K(\kappa)} \frac{d}{du} \left[ \frac{\operatorname{sn}^6 u}{(1 - \varepsilon_r^2 \operatorname{sn}^2 u)^2 \operatorname{dn} u} \right] \frac{\operatorname{sn} u}{\operatorname{cn} u} du \\
 &= \int_0^{K(\kappa)} \frac{\operatorname{sn}^6 u}{(1 - \varepsilon_r^2 \operatorname{sn}^2 u)^2 \operatorname{cn}^2 u} - \left[ \frac{\operatorname{sn}^7 u}{\operatorname{cn} u \operatorname{dn} u (1 - \varepsilon_r^2 \operatorname{sn}^2 u)^2} \right]_{u=K} \\
 &= - \frac{1}{2\varepsilon_r^4(\varepsilon_r^2 - 1)} \left( 5 + \frac{3}{\varepsilon_r^2 - 1} + \frac{\kappa^2}{\varepsilon_r^2 - \kappa^2} \right) \int_0^K \frac{du}{1 - \varepsilon_r^2 \operatorname{sn}^2 u} \\
 &\quad - \left( \frac{2\varepsilon_r^2(\varepsilon_r^2 - \kappa^2) + (1 - \kappa^2)}{2\varepsilon_r^2(\varepsilon_r^2 - 1)^2(1 - \kappa^2)(\varepsilon_r^2 - \kappa^2)} \right) E + \frac{4\varepsilon_r^2 - 1}{2\varepsilon_r^4(\varepsilon_r^2 - 1)^2} K \quad \dots \quad (\text{III,8})
 \end{aligned}$$

and

$$\begin{aligned}
 k^5 I_2 &= - \int_0^{K(\kappa)} \frac{d}{du} \left[ \frac{\operatorname{sn}^4 u}{(1 - \varepsilon_r^2 \operatorname{sn}^2 u) \operatorname{dn} u} \right] \frac{\operatorname{sn} u}{\operatorname{cn} u} du \\
 &= \int_0^K \frac{\operatorname{sn}^4 u du}{(1 - \varepsilon_r^2 \operatorname{sn}^2 u) \operatorname{cn}^2 u} - \left[ \frac{\operatorname{sn}^5 u}{\operatorname{cn} u \operatorname{dn} u} \left( \frac{1}{1 - \varepsilon_r^2 \operatorname{sn}^2 u} \right) \right]_{u=K} \\
 &= \frac{1}{\varepsilon_r^2(\varepsilon_r^2 - 1)} \int_0^K \frac{du}{1 - \varepsilon_r^2 \operatorname{sn}^2 u} - \frac{1}{\varepsilon_r^2(\varepsilon_r^2 - 1)} K + \frac{1}{(\varepsilon_r^2 - 1)(1 - \kappa^2)} E. \quad (\text{III,9})
 \end{aligned}$$

Substituting (III,8), (III,9) in (III,7), the coefficient of

$$\begin{aligned}
 &\frac{A_r^2}{k^2 \varepsilon_r^2 (\varepsilon_r^2 - 1)} \int_0^K \frac{du}{1 - \varepsilon_r^2 \operatorname{sn}^2 u}, \text{ in the expression for } I, \text{ is} \\
 &- \frac{1}{2\varepsilon_r^2} \left( 5 + \frac{3}{\varepsilon_r^2 - 1} + \frac{\kappa^2}{\varepsilon_r^2 - \kappa^2} \right) + \frac{2k^2}{A_r} \sum_{s=1}^N \frac{A_s}{c_r - c_s} \quad (s \neq r) \\
 &= - k^2 \left[ \frac{1}{2c_r} \left( 5 + \frac{3k^2}{c_r - k^2} + \frac{h^2}{c_r - h^2} \right) + 2 \sum_{s=1}^N \left( \frac{1}{c_r - c_s} \right) \right] \\
 &= 0, \text{ by (III,4).}
 \end{aligned}$$

Hence it can be shown that

$$\begin{aligned}
 (I)_{n=2N+1} &= \frac{1}{k} \sum_{r=1}^N \left[ \frac{1}{[P_{2N+1}'(c_r)]^2} \left\{ \frac{k^2 \beta^2 - 2c_r(h^2 - c_r)}{2\beta^2 c_r (k^2 - c_r)^2 (h^2 - c_r)} E \right. \right. \\
 &\quad \left. \left. + \frac{4c_r - k^2}{2c_r^2 (k^2 - c_r)^2} K - 2 \sum_{s=1}^N \left( \frac{1}{c_r - c_s} \right) \left( \frac{1}{k^2 - c_r} \right) \left( \frac{1}{c_r} K - \frac{1}{\beta^2} E \right) \right\} \right]_{s \neq r} \\
 &= \frac{1}{k} \sum_{r=1}^N \left[ \frac{1}{[P_{2N+1}'(c_r)]^2 2c_r} \left( \frac{1}{k^2 - c_r} \right) \left\{ \frac{k^2 \beta^2 - 2c_r(h^2 - c_r)}{\beta^2 (k^2 - c_r) (h^2 - c_r)} E \right. \right. \\
 &\quad \left. \left. + \frac{4c_r - k^2}{c_r (k^2 - c_r)} K + \left( 5 - \frac{h^2}{h^2 - c_r} - \frac{3k^2}{k^2 - c_r} \right) \left( \frac{1}{c_r} K - \frac{1}{\beta^2} E \right) \right\} \right], \quad \dots \quad (\text{III,10})
 \end{aligned}$$

using the relation (III,4).

For  $n = 2N$ ,

$$\frac{1}{[P_n(t)]^2} = \frac{1}{[P_{2N}(t)]^2} = \frac{1}{t^2 \prod_{r=1}^{N-1} (t^2 - d_r)^2}$$

Therefore

$$(I)_{n=2N} = \sum_{r=1}^{N-1} \left[ B_r^2 \left\{ I_3 + \frac{2I_4}{B_r} \sum_{s=1}^{N-1} \left( \frac{B_s}{d_r - d_s} \right) \right\} \right], \quad s \neq r \quad \dots \quad (III,11)$$

where

$$B_r = \frac{1}{\left( \frac{P_{2N}}{t} \right)'(d_r)}, \quad I_3 = \int_k^\infty \frac{d}{dt} \left( \frac{1}{t^3(t^2 - d_r)^2(t^2 - h^2)^{1/2}} \right) \frac{dt}{(t^2 - k^2)^{1/2}}$$

and

$$I_4 = \int_k^\infty \frac{d}{dt} \left( \frac{1}{t^3(t^2 - d_r)(t^2 - h^2)^{1/2}} \right) \frac{dt}{(t^2 - k^2)^{1/2}}.$$

$$\left[ \left( \frac{P_{2N}}{t} \right)'(d_r) \text{ is written for } \left\{ \frac{d}{d(t^2)} \frac{P_{2N}(t)}{t} \right\}_{t=d_r} \right].$$

Again using the substitution  $t = k \operatorname{ns} u$ , and writing  $d_r/k = \delta_r^2$ , it can be shown that

$$k^9 I_3 = -\frac{1}{2\delta_r^9(\delta_r^2 - 1)} \left( 7 + \frac{3}{\delta_r^2 - 1} + \frac{\kappa^2}{\delta_r^2 - \kappa^2} \int_0^K \frac{du}{1 - \delta_r^2 \operatorname{sn}^2 u} \right.$$

$$+ \frac{3\kappa^2(2\delta_r^2 - 1) - 2\delta_r^2(\delta_r^2 - 1)^2}{2\delta_r^9 \kappa^2(\delta_r^2 - 1)^2} K + \left( \frac{1}{\delta_r^4 \kappa^2} - \frac{1}{(1 - \kappa^2)(\delta_r^2 - 1)^2} \right.$$

$$\left. \left. - \frac{1}{2\delta_r^4(\delta_r^2 - 1)^2(\delta_r^2 - \kappa^2)} \right) E \quad \dots \quad (III,12)$$

and

$$k^7 I_4 = \frac{\kappa^2(2\delta_r^2 - 1) - (\delta_r^2 - 1)}{\kappa^2 \delta_r^2(\delta_r^2 - 1)(1 - \kappa^2)} E + \frac{\delta_r^2(\delta_r^2 - 1) - \kappa^2}{\kappa^2 \delta_r^4(\delta_r^2 - 1)} K$$

$$+ \frac{1}{\delta_r^4(\delta_r^2 - 1)} \int_0^K \frac{du}{1 - \delta_r^2 \operatorname{sn}^2 u} \quad \dots \quad (III,13)$$

Substituting (III,12) and (III,13) in (III,11), the coefficient of

$$\frac{B_r^2}{k^9 \delta_r^4(\delta_r^2 - 1)} \int_0^K \frac{du}{1 - \delta_r^2 \operatorname{sn}^2 u}, \text{ in the expression for } I, \text{ is}$$

$$-\frac{1}{2\delta_r^2} \left( 7 + \frac{3}{\delta_r^2 - 1} + \frac{\kappa^2}{\delta_r^2 - \kappa^2} \right) - 2 \sum_{s=1}^{N-1} \left( \frac{1}{\delta_r^2 - \delta_s^2} \right), \quad s \neq r$$

$$= 0 \quad \text{by (III,5).}$$

Hence it can be shown that

$$\begin{aligned}
 (I)_{n=2N} = & \frac{1}{k^3} \sum_{r=1}^{N-1} \left[ \frac{1}{\left[ \left( \frac{P_{2N}}{t} \right)' (d_r) \right]^2} \left\{ \left( \frac{1}{h^2 d_r^2} - \frac{1}{\beta^2 (k^2 - d_r)^2} \right. \right. \right. \\
 & + \left. \left. \frac{k^4}{2d_r^2 (k^2 - d_r)^2 (h^2 - d_r)} \right) E - \frac{3h^2 k^2 (k^2 - 2d_r) + 2d_r (k^2 - d_r)^2}{2h^2 d_r^3 (k^2 - d_r)^2} K \right. \\
 & + \left. \frac{1}{2d_r} \left( 7 + \frac{h^2}{d_r - h^2} + \frac{3k^2}{d_r - k^2} \right) \left( \frac{h^2 + d_r (k^2 - d_r)}{h^2 d_r^2 (k^2 - d_r)} K \right. \right. \\
 & \left. \left. + \frac{h^2 (k^2 - 2d_r) - (k^2 - d_r)}{\beta^2 h^2 d_r (k^2 - d_r)} E \right) \right\} \dots \dots \dots \dots \quad \text{(III,14)}
 \end{aligned}$$

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#### APPENDIX IV

The values of  $\varphi_1 - \varphi_2$ ,  $a_2 \varphi_1 - a_1 \varphi_2$ ,  $a_1 \varphi_1 - a_2 \varphi_2$ , when  $\mu \longrightarrow k$ , for  $n = 3$  and  $n = 4$ .  
(Cartesian co-ordinates  $x, y, z$ )

For  $n = 3$ , when  $\mu \longrightarrow k$ ,

$$\varphi_1 - \varphi_2 = - \frac{V\delta}{3\beta^2 d^2 h^2 k^3 E(x)} (x^2 - k^2 y^2)^{3/2} \dots \dots \dots \dots \quad \text{(IV,1)}$$

$$a_2 \varphi_1 - a_1 \varphi_2 = - \frac{V\delta}{15\beta^2 d^2 h^2 k^3 E(x)} (4x^2 - k^2 y^2)(x^2 - k^2 y^2)^{1/2} \dots \dots \dots \dots \quad \text{(IV,2)}$$

$$a_1 \varphi_1 - a_2 \varphi_2 = - \frac{V\delta}{15\beta^2 d^2 h^2 k^3 E(x)} [2x^2 - (2k^2 + 3h^2)y^2](x^2 - k^2 y^2)^{1/2} \dots \dots \dots \dots \quad \text{(IV,3)}$$

For  $n = 4$ , when  $\mu \longrightarrow k$ ,

$$\varphi_1 - \varphi_2 = \frac{-V\delta}{3\beta^2 d^3 h^2 k^3 E(x)} x(x^2 - k^2 y^2)^{3/2} \dots \dots \dots \dots \quad \text{(IV,4)}$$

$$a_2 \varphi_1 - a_1 \varphi_2 = \frac{-V\delta}{7\beta^2 d^3 h^2 k^3 E(x)} (2x^2 - k^2 y^2)(x^2 - k^2 y^2)^{1/2} \dots \dots \dots \dots \quad \text{(IV,5)}$$

$$a_1 \varphi_1 - a_2 \varphi_2 = \frac{-V\delta}{21\beta^2 d^3 h^2 k^3 E(x)} [4x^2 - (3h^2 + 4k^2)y^2](x^2 - k^2 y^2)^{1/2} \dots \dots \dots \dots \quad \text{(IV,6)}$$


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APPENDIX V

The values of  $\frac{\partial}{\partial z} (\varphi_1 - \varphi_2)$ ,  $\frac{\partial}{\partial z} (a_2\varphi_1 - a_1\varphi_2)$ ,  $\frac{\partial}{\partial z} (a_1\varphi_1 - a_2\varphi_2)$ , when  $\mu \longrightarrow k$ , for  $n = 3$  and  $n = 4$ .  
(Cartesian co-ordinates  $x, y, z$ )

For  $n = 3$ , when  $\mu \longrightarrow k$ ,

$$\begin{aligned} \frac{\partial}{\partial z} (\varphi_1 - \varphi_2) &= \frac{V\delta}{2\beta^2 d^2 h^4 k^2 E(\kappa)} \left[ \{(2h^2 - k^2)E(\kappa) + \beta^2 K(\kappa)\} x^2 \right. \\ &\quad \left. - \{(k^2 + h^2)E(\kappa) - \beta^2 K(\kappa)\} k^2 y^2 \right] \\ \frac{\partial}{\partial z} (a_2\varphi_1 - a_1\varphi_2) &= \frac{V\delta}{10\beta^2 d^2 h^4 k^2 E(\kappa)} \left[ \{2\beta^2(2h^2 + k^2)K(\kappa) \right. \\ &\quad \left. - (2k^4 + 3k^2h^2 - 8h^4)E(\kappa)\} x^2 + \{\beta^2(2k^2 - h^2)K(\kappa) \right. \\ &\quad \left. - 2(k^4 - k^2h^2 + h^4)E(\kappa)\} k^2 y^2 \right] \\ \frac{\partial}{\partial z} (a_1\varphi_1 - a_2\varphi_2) &= \frac{V\delta}{10\beta^2 d^2 h^2 E(\kappa)} \left[ 3E(\kappa)x^2 - \{2(4k^2 + h^2)E(\kappa) - 5\beta^2 K(\kappa)\} y^2 \right]. \end{aligned}$$

For  $n = 4$ , when  $\mu \longrightarrow k$ ,

$$\begin{aligned} \frac{\partial}{\partial z} (\varphi_1 - \varphi_2) &= \frac{V\delta}{6\beta^2 d^3 h^6 k^2 E(\kappa)} \left[ \{2\beta^2(k^2 + 2h^2)K(\kappa) + (8h^4 - 3h^2k^2 - 2k^4)E(\kappa)\} x^3 \right. \\ &\quad \left. - 3\{\beta^2(h^2 - 2k^2)K(\kappa) + 2(k^4 - h^2k^2 + h^4)E(\kappa)\} k^2 xy^2 \right] \\ \frac{\partial}{\partial z} (a_2\varphi_1 - a_1\varphi_2) &= \frac{V\delta}{42\beta^2 d^3 h^6 k^2 E(\kappa)} \left[ \{\beta^2(24h^4 + 13h^2k^2 + 8k^4)K(\kappa) \right. \\ &\quad \left. + (48h^6 - 16h^4k^2 - 9h^2k^4 - 8k^6)E(\kappa)\} x^3 + 3\{\beta^2(8k^4 - h^2k^2 - 4h^4)K(\kappa) \right. \\ &\quad \left. - (8k^6 - 5h^2k^2 - 5h^4k^2 + 8h^6)E(\kappa)\} k^2 xy^2 \right] \\ \frac{\partial}{\partial z} (a_1\varphi_1 - a_2\varphi_2) &= \frac{V\delta}{14\beta^2 d^3 h^4 E(\kappa)} \left[ \{5\beta^2 K(\kappa) + 5(2h^2 - k^2)E(\kappa)\} x^3 \right. \\ &\quad \left. + \{\beta^2(9k^2 - 2h^2)K(\kappa) - (9k^4 + h^2k^2 + 4h^4)E(\kappa)\} xy^2 \right]. \end{aligned}$$

APPENDIX VI

Basic solutions for  $n = 1, 2, 3, 4, (5, 6)$ .  $H \equiv \frac{V\delta}{kE(x)}$ ,  $X \equiv (x^2 - k^2y^2)^{1/2}$ ,  $\kappa = h/k$

Non-dimensional co-ordinates,  $x' = x\sigma/c$ , etc. (The dashes are dropped)

$n$	No. of $M$ solutions	$\varphi_m$	$(\phi_n^s)_{\mu=k}$	$\frac{1}{H} \left( \frac{\partial \phi_n^s}{\partial x} \right)_{\mu=k}$	$z_{n,s}$
1	1	$C_1 r F_1(\mu) E_1(\nu)$	$\phi_1 = HX$	$\frac{x}{X}$	$-\delta x$
2	1	$C_2 r^2 F_2(\mu) E_2(\nu)$	$\phi_2 = HxX$	$\frac{x^2}{X} + X$	$-\delta f_1 x^2$
3	2	$C_3 r^3 F_3^m(\mu) E_3^m(\nu)$	$\phi_3^1 = Hx^2X$ $\phi_3^2 = Hy^2X$	$\frac{x^3}{X} + 2xX$ $\frac{y^2x}{X}$	$-\delta(\frac{1}{3}f_6x^3 - f_7k^2xy^2)$ $\frac{\delta}{k^2}(\frac{1}{3}f_2x^3 - f_3k^2xy^2)$
4	2	$C_4 r^4 F_4^m(\mu) E_4^m(\nu)$	$\phi_4^1 = Hx^3X$ $\phi_4^2 = Hxy^2X$	$\frac{x^4}{X} + 3x^2X$ $y^2\left(\frac{x^2}{X} + X\right)$	$-\delta(\frac{1}{4}f_{12}x^4 - \frac{1}{2}f_{13}k^2x^2y^2)$ $\frac{\delta}{k^2}(\frac{1}{4}f_8x^4 - \frac{1}{2}f_9k^2x^2y^2)$
5	3	$C_5 r^5 F_5^m(\mu) E_5^m(\nu)$	$\phi_5^1 = Hx^4X$ $\phi_5^2 = Hx^2y^2X$ $\phi_5^3 = Hy^4X$	$\frac{x^5}{X} + 4x^3X$ $y^2x\left(\frac{x^2}{X} + 2X\right)$ $\frac{xy^4}{X}$	

APPENDIX VI—continued

Basic solutions for  $n = 1, 2, 3, 4, (5, 6)$ .  $H \equiv \frac{V\delta}{kE(\kappa)}$ ,  $X \equiv (x^2 - k^2y^2)^{1/2}$ ,  $\kappa = h/k$   
 Non-dimensional co-ordinates,  $x' = x\sigma/c$ , etc. (The dashes are dropped)

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$n$	No. of $M$ solutions	$\varphi_m$	$(\phi_n^s)_{\mu=k}$	$\frac{1}{H} \left( \frac{\partial \phi_n^s}{\partial x} \right)_{\mu=k}$	$z_{n,s}$
6	3	$C_6 \nu^6 F_6^m(\mu) E_6^m(\nu)$	$\phi_6^1 = Hx^5X$ $\phi_6^2 = Hx^3y^2X$ $\phi_6^3 = Hxy^4X$	$\frac{x^6}{X} + 5x^4X$ $x^2y^2 \left( \frac{x^2}{X} + 3X \right)$ $y^4 \left( \frac{x^2}{X} + X \right)$	

## APPENDIX VII

*Formulae for the Local Spanwise Lift, the Total Lift, the Induced Drag, and the Pitching-Moment Coefficients for the Surfaces Shown in Figs. 6 to 17*

The numbers (i), (ii), . . . . . of the surfaces correspond to those in the text (section 12).

Non-dimensional co-ordinates  $x' = x\sigma/c$ ,  $y' = y\sigma/c$ ,  $z' = z\sigma/c$ . The dashes are dropped.

$$(i) \quad C_{l_0} = \frac{4\delta}{kE(\kappa)} (1 - ky)^{1/2} (1 + ky)^{3/2} \quad (\text{Fig. 6})$$

$$C_{L_0} = \frac{3\pi\delta}{2kE(\kappa)}, \quad C_{M_0} = \frac{-2}{5} \frac{\pi\delta}{kE(\kappa)}$$

$$C_{D_p}/(C_{L_0}^2/\pi A) = \frac{4}{5}E(\kappa)(12f_4 - f_5)$$

$$C_{D_s} = 0, \quad \varepsilon \equiv C_{D_v}/(C_{L_0}^2/\pi A) = \frac{4}{3}$$

$$(ii) \quad C_{l_0} = \frac{4\delta}{kE(\kappa)} (1 - ky)^{1/2} (1 + ky)^{3/2} \quad (\text{Fig. 7})$$

$$C_{L_0} = \frac{3\pi\delta}{2kE(\kappa)}, \quad C_{M_0} = -\frac{1}{2} \frac{\pi\delta}{kE(\kappa)}$$

$$C_{D_p}/(C_{L_0}^2/\pi A) = \frac{1}{18}E(\kappa)(30f_{10} - 7f_{11})$$

$$C_{D_s} = 0, \quad C_{D_v}/(C_{L_0}^2/\pi A) = \frac{4}{3}$$

$$(vi) \quad C_{l_0} = \frac{4\delta}{kE(\kappa)} \left( \frac{\sigma + ky}{\sigma - ky} \right)^{1/2} (1 - k^2y^2) \quad (\text{Figs. 8, 9})$$

$$C_{L_0} = \frac{2\pi\delta}{kE(\kappa)} (1 - \frac{1}{4}\sigma^2), \quad C_{M_0} = \frac{2}{15} \frac{\pi\delta}{kE(\kappa)} \sigma^2$$

$$C_{D_p}/(C_{L_0}^2/\pi A) = 2E(\kappa)[1 - (\frac{1}{4} - \frac{1}{2}f_2 + \frac{1}{4}f_3)\sigma^2 - (\frac{1}{6}f_2 - \frac{1}{8}f_3)\sigma^4]/(1 - \frac{1}{4}\sigma^2)^2$$

$$C_{D_s}/(C_{L_0}^2/\pi A) = \frac{(k^2 - \beta^2)^{1/2}}{k} (1 - \sigma^2 + \frac{1}{3}\sigma^4)/(1 - \frac{1}{4}\sigma^2)^2$$

$$C_{D_v}/(C_{L_0}^2/\pi A) \equiv \varepsilon = 1 + 3\sigma^4/(4 - \sigma^2)^2$$

$$(vii) \quad C_{l_0} = \frac{4\delta}{kE(\kappa)} \left( \frac{\sigma + ky}{\sigma - ky} \right)^{1/2} (1 - \sigma k^2 y^2) \quad (\text{Fig. 10})$$

$$C_{L_0} = \frac{2\pi\delta}{kE(\kappa)} (1 - \frac{1}{4}\sigma^3), \quad C_{M_0} = \frac{1}{12} \frac{\pi\delta}{kE(\kappa)} \sigma^3$$

$$C_{D_p}/(C_{L_0}^2/\pi A) = 2E(\kappa) \frac{[1 - (\frac{1}{4} - \frac{2}{5}f_3 + \frac{1}{5}f_9)\sigma^3 - (\frac{5}{32}f_3 - \frac{7}{64}f_9)\sigma^6]}{(1 - \frac{1}{4}\sigma^3)^2}$$

$$C_{D_s}/(C_{L_0}^2/\pi A) = \frac{(k^2 - \beta^2)^{1/2}}{k} (1 - \frac{4}{5}\sigma^3 + \frac{1}{4}\sigma^6)(1 - \frac{1}{4}\sigma^3)^2$$

$$C_{D_v}/(C_{L_0}^2/\pi A) \equiv \varepsilon = 1 + 3\sigma^6/(4 - \sigma^3)^2$$



$$(xii) \quad \gamma = 45^\circ \quad , \quad M = 1.281 \quad (Fig. 11)$$

$$C_{l_0} = \frac{4\delta}{E(\kappa)} \left( \frac{\sigma + y}{\sigma - y} \right)^{1/2} [0.7085(1 - \sigma^2) - 0.2604(1 - \sigma^3) \\ + (0.6317 - 0.2407\sigma)(\sigma^2 - y^2)]$$

$$C_{L_0} = \frac{2\pi\delta}{E(\kappa)} [0.4481 - 0.2347\sigma^2 + 0.0799\sigma^3]$$

$$C_{M_0} = -\frac{2\pi\delta}{E(\kappa)} [0.06260\sigma^2 - 0.02662\sigma^3]$$

$$C_{D_p}/(C_{L_0}^2/\pi A) = 11.3448\bar{P}/C^2, \quad \text{where :}$$

$$\bar{P} = 0.7085P_2 + 0.6317P_3 - 0.2604P_4 - 0.2407P_5$$

$$P_2 = 0.11203 - 0.19925\sigma^2 + 0.02896\sigma^3 + 0.08722\sigma^4 - 0.03103\sigma^5$$

$$P_3 = 3\sigma^2[0.02801 - 0.01454\sigma^2 + 0.00517\sigma^3]$$

$$P_4 = 0.11203 - 0.08722\sigma^2 - 0.08307\sigma^3 + 0.08722\sigma^5 - 0.03168\sigma^6$$

$$P_5 = \sigma^3[0.08402 - 0.04361\sigma^2 + 0.01584\sigma^3]$$

$$C \equiv \frac{E(\kappa)}{2\pi\delta} C_{L_0}$$

$$C_{D_s}/(C_{L_0}^2/\pi A) = \frac{0.6}{C^2} [0.200811 - 0.317493\sigma^2 + 0.093345\sigma^3 \\ + 0.167324\sigma^4 - 0.105417\sigma^5 + 0.016949\sigma^6]$$

$$C_{D_v}/(C_{L_0}^2/\pi A) \equiv \varepsilon = 1 + \frac{3(0.157925\sigma^2 - 0.060165\sigma^3)^2}{(0.44812 - 0.234725\sigma^2 + 0.079885\sigma^3)^2}$$

$$(ix) \quad \gamma = 45^\circ \quad , \quad M = 1.281 \quad (Fig. 12)$$

$$C_{l_0} \equiv \frac{4\delta}{E(\kappa)} \left( \frac{\sigma + y}{\sigma - y} \right)^{1/2} [-(1 - \sigma) + 0.4597(1 - \sigma^2) \\ + 0.56824(1 - \sigma^3) + (2.3796 + 2.7500\sigma)(\sigma^2 - y^2)]$$

$$C_{L_0} = \frac{2\pi\delta}{E(\kappa)} [0.02794 + \sigma + 1.325\sigma^2 + 1.4942\sigma^3]$$

$$C_{M_0} = \frac{2\pi\delta}{E(\kappa)} [-\frac{1}{8}\sigma - 0.353334\sigma^2 - 0.498082\sigma^3]$$

$$C_{D_p}/(C_{L_0}^2/\pi A) = 11.3448\bar{P}/C^2, \quad \text{where :}$$

$$\bar{P} = -P_1 + 0.4597P_2 + 2.3796P_3 + 0.5682P_4 + 2.7500P_5$$

$$P_1 = 0.00697 + 0.22920\sigma - 0.09124\sigma^2 - 0.07637\sigma^3 - 0.33188\sigma^4$$

$$P_2 = 0.00697 + 0.23617\sigma + 0.16748\sigma^2 - 0.08065\sigma^3 - 0.34890\sigma^4 \\ - 0.42412\sigma^5$$

$$\begin{aligned}
P_3 &= 3\sigma^2[0.00174 + 0.07085\sigma + 0.11630\sigma^2 + 0.13965\sigma^3] \\
P_4 &= 0.00697 + 0.23617\sigma + 0.17445\sigma^2 + 0.19578\sigma^3 - 0.29521\sigma^4 \\
&\quad - 0.39874\sigma^5 - 0.49329\sigma^6 \\
P_5 &= \sigma^3[0.00523 + 0.22141\sigma + 0.38628\sigma^2 + 0.47293\sigma^3]
\end{aligned}$$

$$C = \frac{E(\kappa)}{2\pi\delta} C_{L0}$$

$$\begin{aligned}
C_{Ds}/(C_{L0}^2/\pi A) &= \frac{0.6}{C^2} [0.000781 + 0.037253\sigma + 0.487156\sigma^2 \\
&\quad - 0.380461\sigma^3 - 0.308385\sigma^4 + 0.149269\sigma^5 + 0.080724\sigma^6]
\end{aligned}$$

$$C_{Dv}/(C_{L0}^2/\pi A) \equiv \varepsilon = 1 + \frac{3}{C^2} (0.5949\sigma^2 + 0.6875\sigma^3)^2$$

$$(x) \quad \gamma = 45^\circ, \quad M = 1.281 \quad (\text{Fig. 13})$$

$$\begin{aligned}
C_{l0} &= \frac{4\delta}{E(\kappa)} \left( \frac{\sigma + y}{\sigma - y} \right)^{1/2} [-(1 - \sigma) + 4.7107(1 - \sigma^2) - 3.3375(1 - \sigma^3) \\
&\quad + (6.17 - 0.8599\sigma)(\sigma^2 - y^2)]
\end{aligned}$$

$$C_{L0} = \frac{2\pi\delta}{E(\kappa)} [0.3732 + \sigma - 0.0832\sigma^2 + 2.6925\sigma^3]$$

$$C_{M0} = \frac{2\pi\delta}{E(\kappa)} \left[ -\frac{1}{8}\sigma + 0.2219\sigma^2 + 0.8975\sigma^3 \right]$$

$$C_{Dp}/(C_{L0}^2/\pi A) = 11.3448\bar{P}/C^2, \quad \text{where:}$$

$$\bar{P} = -P_1 + 4.7107P_2 + 6.17P_3 - 3.3375P_4 - 0.8599P_5$$

$$P_1 = 0.09347 + 0.1427\sigma - 0.61459\sigma^2 + 0.88144\sigma^3 - 0.78444\sigma^4$$

$$P_2 = 0.09347 + 0.23617\sigma - 0.44237\sigma^2 + 0.35381\sigma^3 + 0.17445\sigma^4 - 0.88960\sigma^5$$

$$P_3 = 3\sigma^2[0.02337 + 0.07085\sigma + 0.02908\sigma^2 + 0.21723\sigma^3]$$

$$P_4 = 0.09347 + 0.23617\sigma - 0.34890\sigma^2 + 0.54374\sigma^3 - 0.29521\sigma^4 + 0.12461\sigma^5 - 0.96849\sigma^6$$

$$P_5 = \sigma^3[0.07011 + 0.22141\sigma + 0.12461\sigma^2 + 0.71052\sigma^3]$$

$$C = \frac{E(\kappa)}{2\pi\delta} C_{L0}$$

$$\begin{aligned}
C_{Ds}/(C_{L0}^2/\pi A) &= \frac{0.6}{C^2} [0.139308 + 0.497653\sigma - 1.258220\sigma^2 \\
&\quad - 2.772021\sigma^3 + 9.621871\sigma^4 - 8.983870\sigma^5 + 2.784650\sigma^6]
\end{aligned}$$

$$C_{Dv}/(C_{L0}^2/\pi A) \equiv \varepsilon = 1 + \frac{3}{C^2} (1.5425\sigma^2 - 0.2150\sigma^3)^2$$

$$(iii) \quad \gamma = 45^\circ, \quad M = 1.166 \quad (I)$$

$$C_{I_0} = \frac{4\delta}{E(\kappa)} \left( \frac{\sigma + y}{\sigma - y} \right)^{1/2} (1 - \sigma)$$

$$C_{L_0} = \frac{2\pi\delta}{E(\kappa)} (1 - \sigma) \quad , \quad C_{M_0} = \frac{1}{3} \frac{\pi\delta}{E(\kappa)} \sigma$$

$$C_{D_p}/(C_{L_0}^2/\pi A) = 2E(\kappa)[1 - (1 + \frac{4}{3}f_1)\sigma + \frac{3}{2}f_1\sigma^2]/(1 - \sigma)^2$$

$$C_{D_s}/(C_{L_0}^2/\pi A) = (2 - M^2)^{1/2}(1 - \frac{4}{3}\sigma + \frac{1}{2}\sigma^2)/(1 - \sigma)^2$$

$$C_{D_v}/(C_{L_0}^2/\pi A) \equiv \varepsilon = 1$$

$$(viii) \quad \gamma = 30^\circ, \quad M = 1.852 \quad (I)$$

$$C_{I_0} = \frac{4\delta}{kE(\kappa)} \sigma \left( \frac{\sigma + ky}{\sigma - ky} \right)^{1/2} (\sigma - k^2y^2)$$

$$C_{L_0} = \frac{2\pi\delta}{kE(\kappa)} \sigma^2 (1 - \frac{1}{4}\sigma)$$

$$C_{M_0} = -\frac{2\pi\delta}{kE(\kappa)} \sigma^2 (\frac{4}{15} - \frac{1}{12}\sigma)$$

$$C_{D_p}/(C_{L_0}^2/\pi A) = 2E(\kappa)[(\frac{2}{3}f_6 - \frac{1}{4}f_7) + (\frac{1987}{1792}f_6 - \frac{1}{56}f_7 + \frac{29}{56}f_8 - \frac{3}{14}f_9)\sigma + (\frac{7}{64}f_9 - \frac{5}{32}f_8)\sigma^2]/(1 - \frac{1}{4}\sigma)^2$$

$$C_{D_s}/(C_{L_0}^2/\pi A) = \left( \frac{4 - M^2}{3} \right)^{1/2} [1 - \frac{4}{5}\sigma - \frac{1}{3}\sigma^2 + \frac{1}{4}\sigma^4]/[\sigma^2(1 - \frac{1}{4}\sigma)^2]$$

$$C_{D_v}/(C_{L_0}^2/\pi A) \equiv \varepsilon = 1 + 3\sigma^2/(4 - \sigma)^2$$

$$(xiii) \quad \gamma = 45^\circ, \quad M = 1.281 \quad (I)$$

$$C_{I_0} = \frac{4\delta}{E(\kappa)} \left( \frac{\sigma + y}{\sigma - y} \right)^{1/2} (3 + \sigma^2 - 4y^2)$$

$$C_{L_0} = \frac{2\pi\delta}{E(\kappa)} (3) = 13.29214\delta, \quad C_{M_0} = 0$$

$$C_{D_p}/(C_{L_0}^2/\pi A) = 1.26053[2.25 - 0.641718\sigma^2 + 0.565956\sigma^4]$$

$$C_{D_s}/(C_{L_0}^2/\pi A) = 0.6(1 - \sigma^2 + \frac{1}{3}\sigma^4)$$

$$C_{D_v}/(C_{L_0}^2/\pi A) \equiv \varepsilon = 1 + \frac{1}{3}\sigma^4$$

$$(xi) \quad \gamma = 45^\circ \quad , \quad M = 1.281 \quad (H)$$

$$C_{I_0} = \frac{4\delta}{E(\kappa)} \left( \frac{\sigma + y}{\sigma - y} \right)^{1/2} [3.5425(1 - \sigma^2) - 2.6038(1 - \sigma^3)$$

$$+ (3.1587 - 2.4066\sigma)(\sigma^2 - y^2)]$$

$$C_{L0} = \frac{2\pi\delta}{E(\kappa)} [0.9387 - 1.1735\sigma^2 + 0.7988\sigma^3]$$

$$C_{M0} = \frac{2\pi\delta}{E(\kappa)} [0.3129\sigma^2 - 0.2662\sigma^3]$$

$$C_{Dp}/(C_{L0}^2/\pi A) = \frac{2.8362}{C^2} [0.88116 - 2.73910\sigma^2 + 1.83742\sigma^3 \\ + 3.42474\sigma^4 - 4.88008\sigma^5 + 1.77468\sigma^6]$$

$$C_{Ds}/(C_{L0}^2/\pi A) = \frac{0.6}{C^2} [0.88116 - 3.32534\sigma^2 + 1.95535\sigma^3 \\ + 4.18310\sigma^4 - 5.27083\sigma^5 + 1.69495\sigma^6]$$

$$C_{Dv}/(C_{L0}^2/\pi A) \equiv \varepsilon = 1 + \frac{3}{16C^2} \sigma^4 (3.1587 - 2.4066\sigma)^2,$$

where

$$C = \frac{E(\kappa)}{2\pi\delta} C_{L0}$$

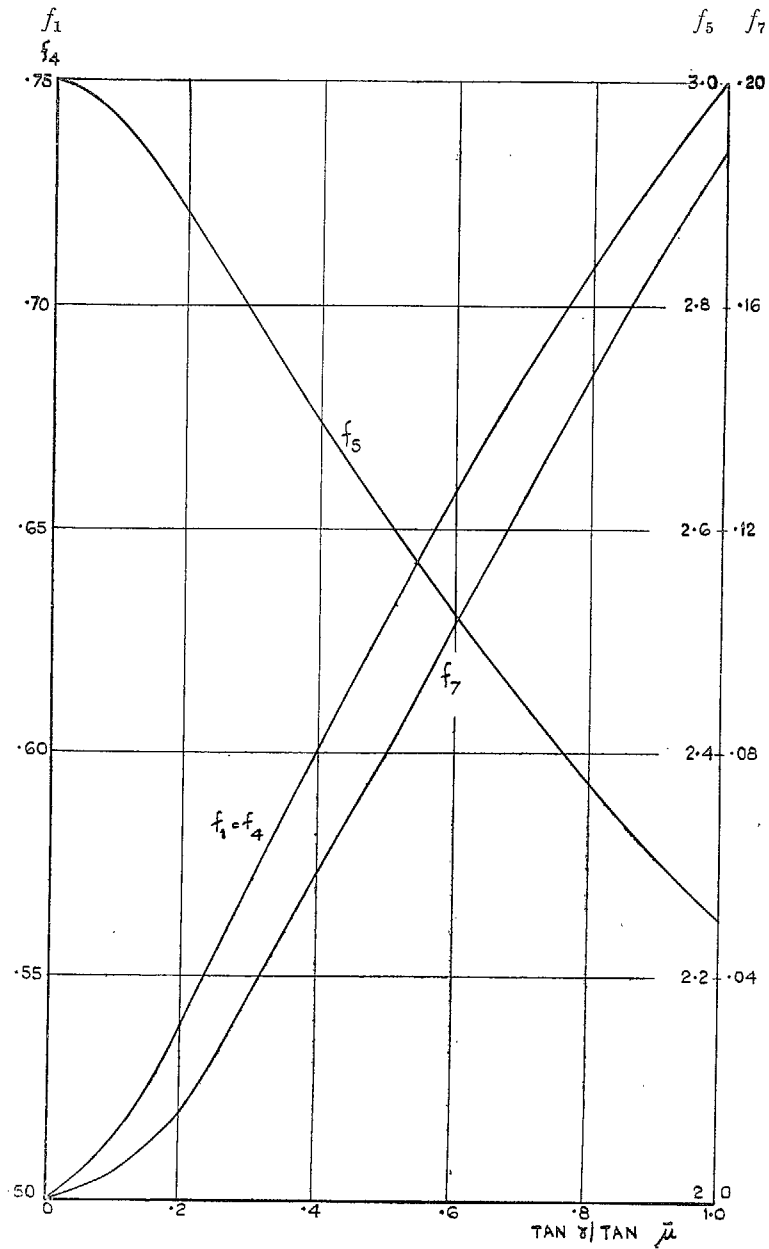


FIG. 1. The functions  $f_1(\tan \gamma / \tan \bar{\mu}), f_4(\tan \gamma / \tan \bar{\mu}), f_5(\tan \gamma, \tan \bar{\mu}), f_7(\tan \gamma / \tan \bar{\mu})$ .

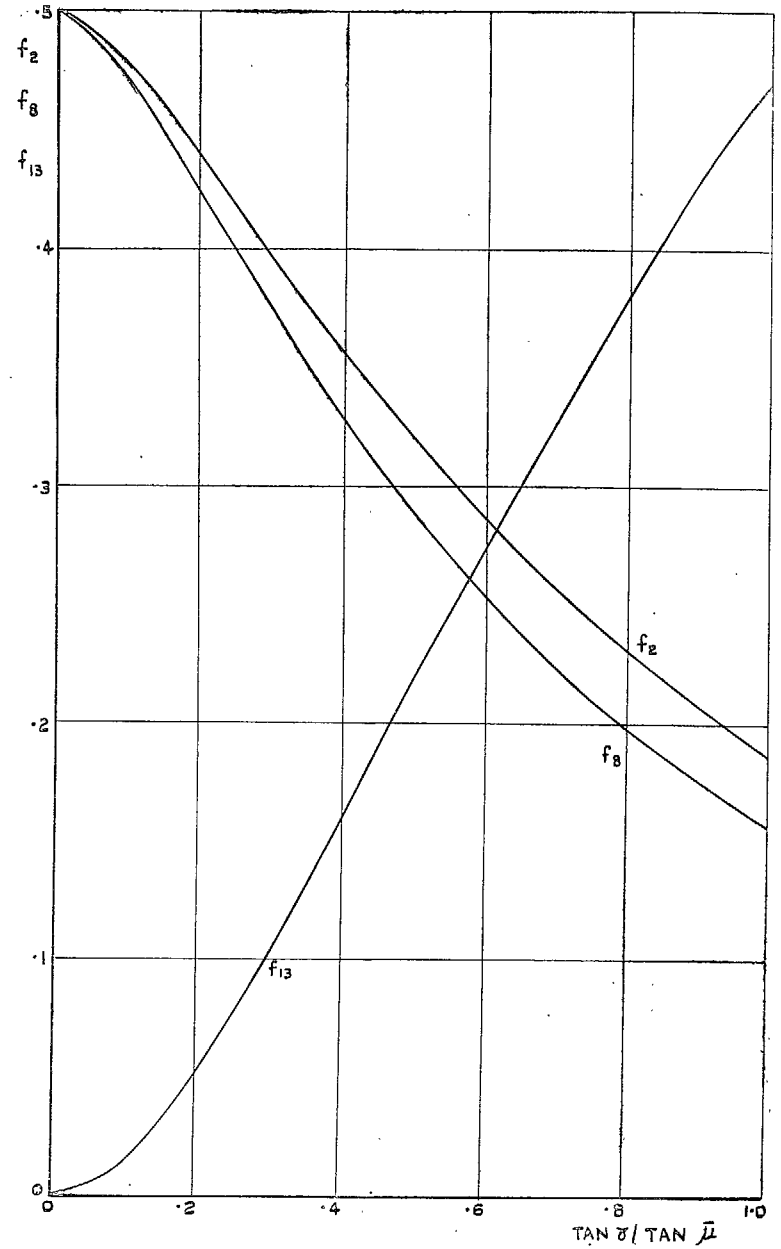


FIG. 2. The functions  $f_2(\tan \gamma / \tan \bar{\mu}), f_8(\tan \gamma / \tan \bar{\mu}), f_{13}(\tan \gamma / \tan \bar{\mu})$ .

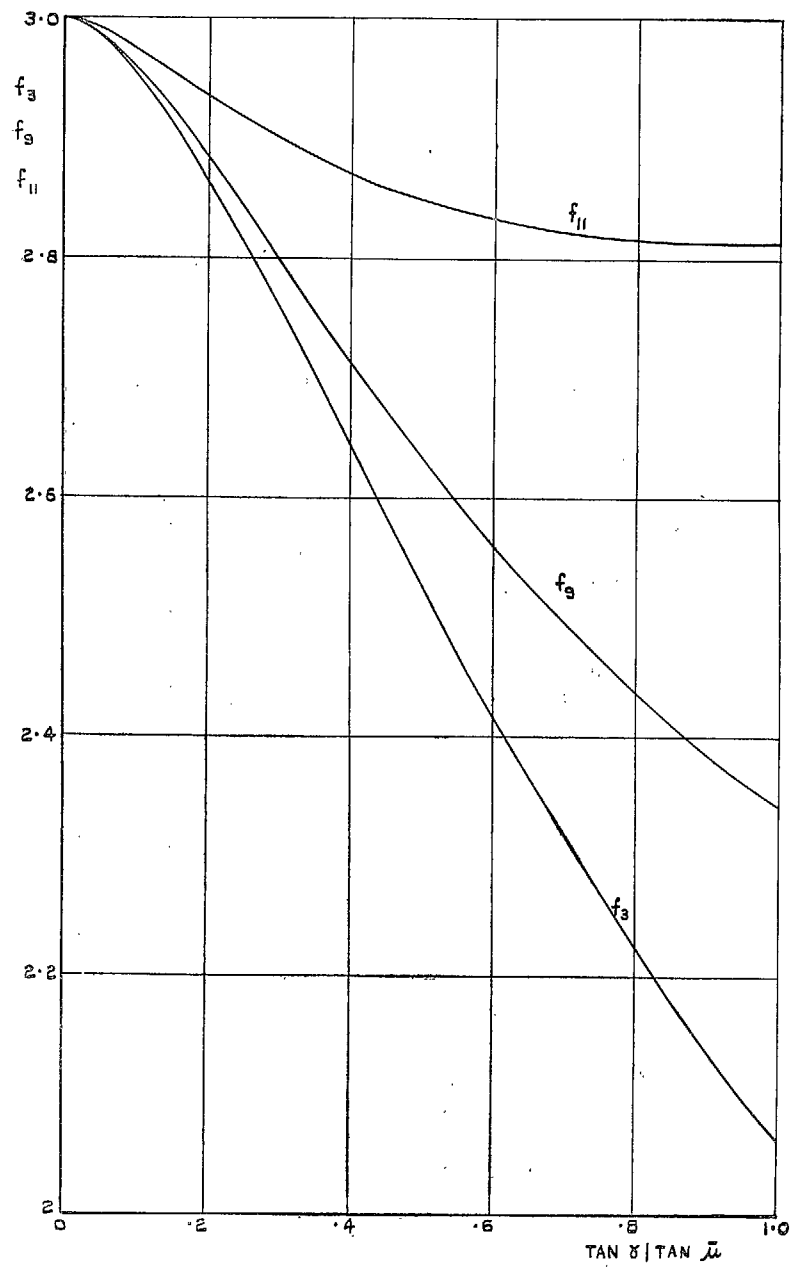


FIG. 3. The functions  $f_3(\tan \gamma / \tan \bar{\mu})$ ,  $f_9(\tan \gamma / \tan \bar{\mu})$ ,  $f_{11}(\tan \gamma / \tan \bar{\mu})$ .

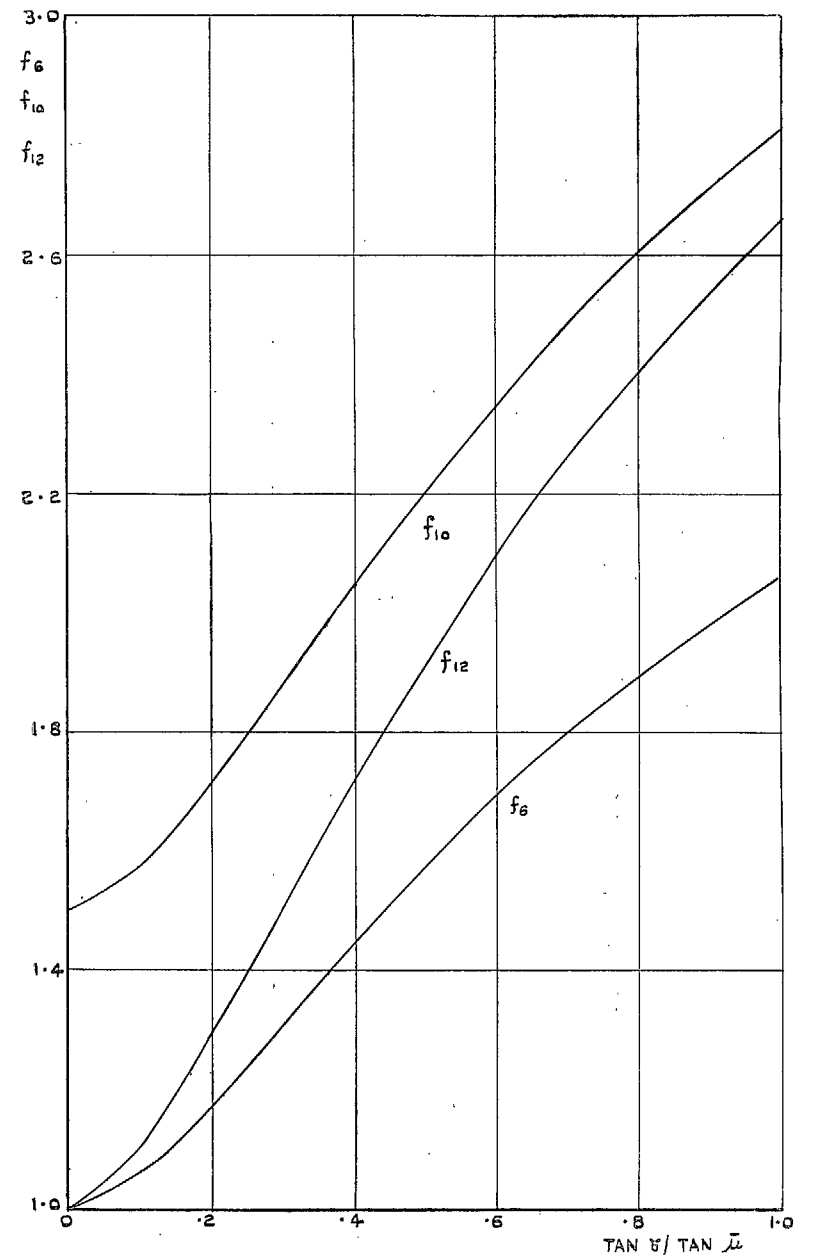


FIG. 4. The functions  $f_6(\tan \gamma / \tan \bar{\mu})$ ,  $f_{10}(\tan \gamma / \tan \bar{\mu})$ ,  $f_{12}(\tan \gamma / \tan \bar{\mu})$ .

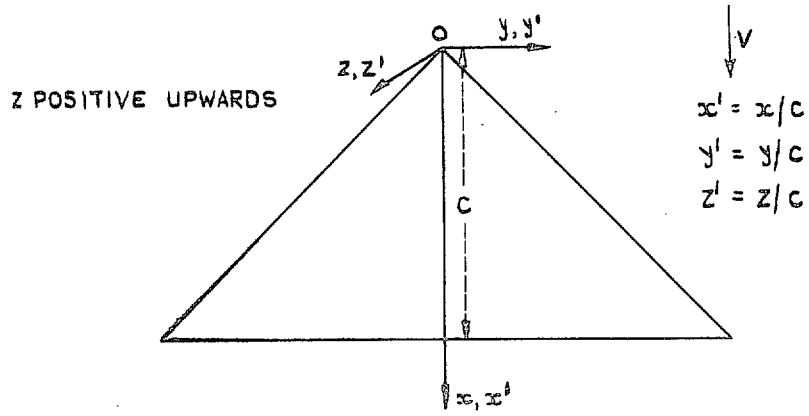
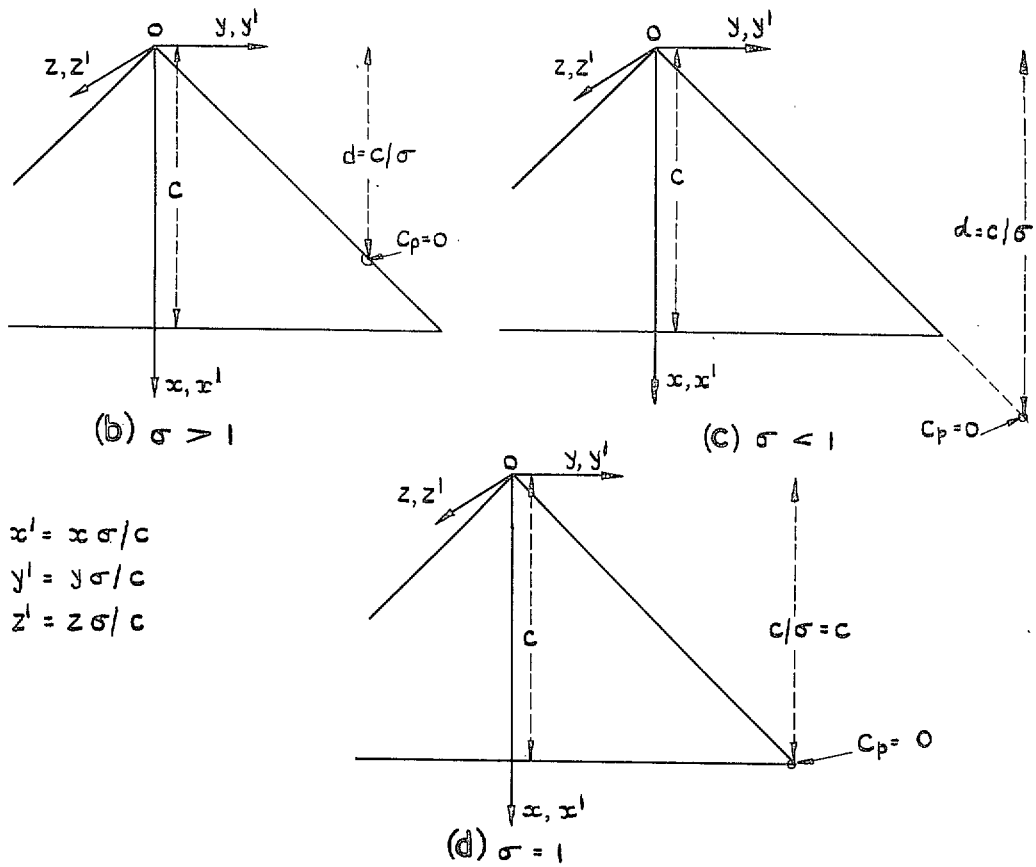


FIG. 5a. Notation for surfaces (i) and (ii) (Figs. 6 and 7).



FIGS. 5b, 5c and 5d. Notation for surfaces (iii) to (xvi) (Figs. 8 to 22).

Note : In FIGS. 6-22,  $x'$ ,  $y'$ ,  $z'$ , are written  $x$ ,  $y$ ,  $z$ .

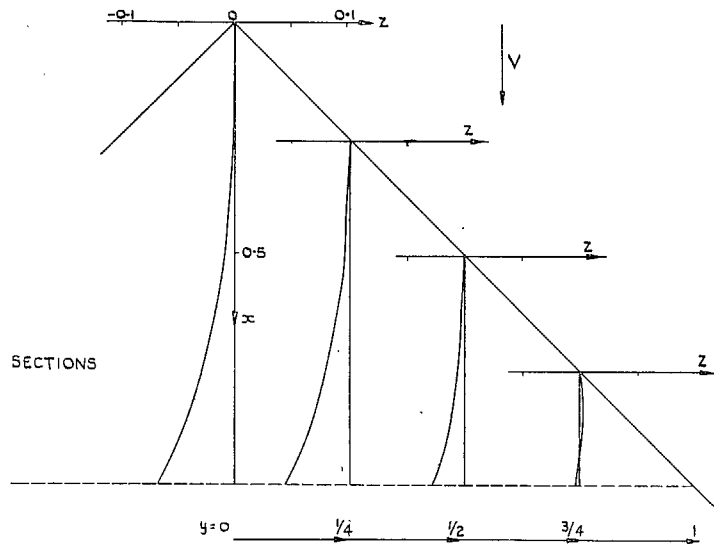


FIG. 6. Surface (i) for  $\gamma = 45$  deg.  $M = 1.166$ . Shape and pressure distribution.

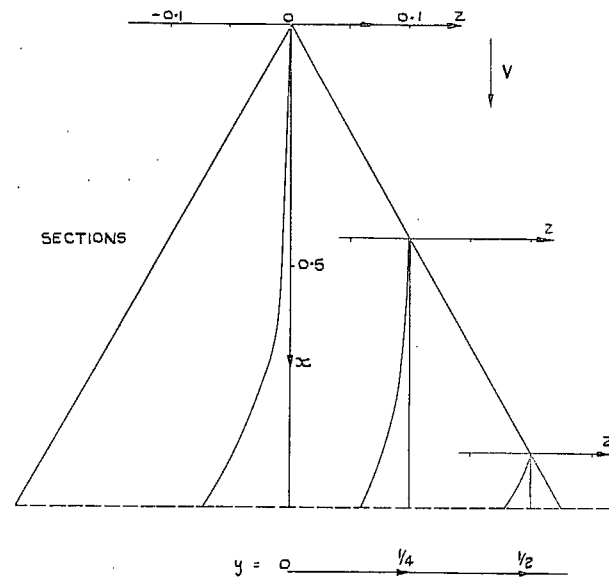


FIG. 7. Surface (ii) for  $\gamma = 30$  deg.  $M = 1.852$ . Shape and pressure distribution.





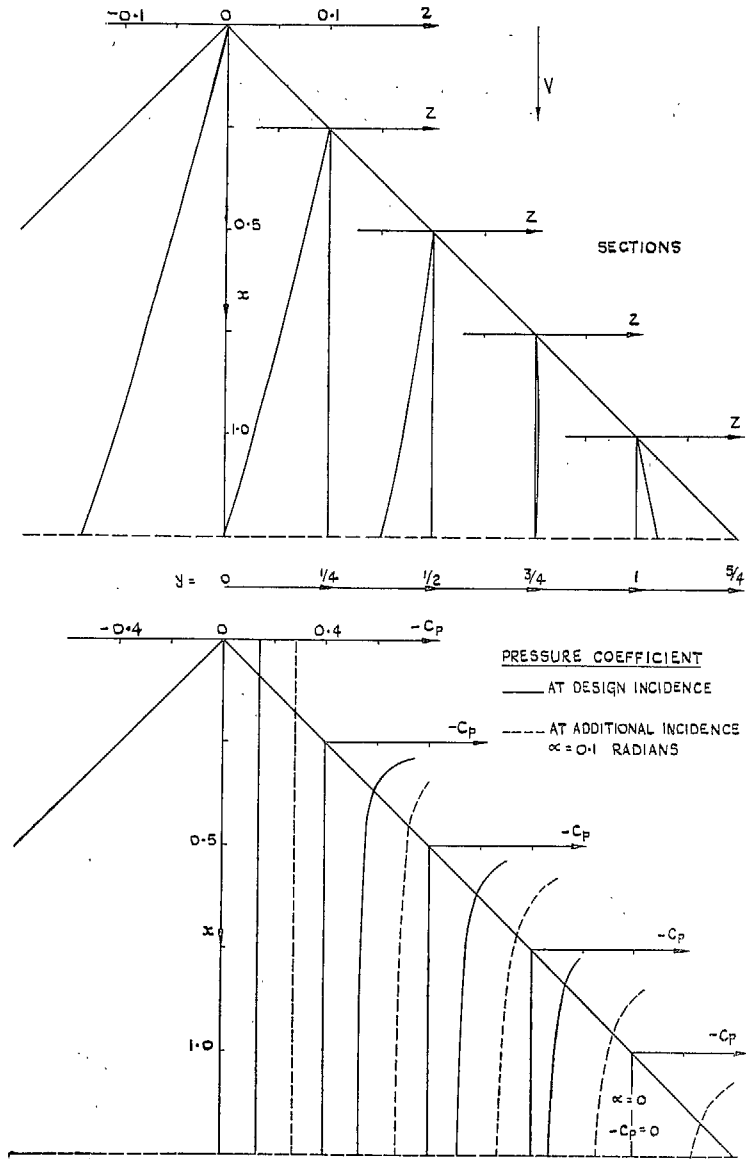
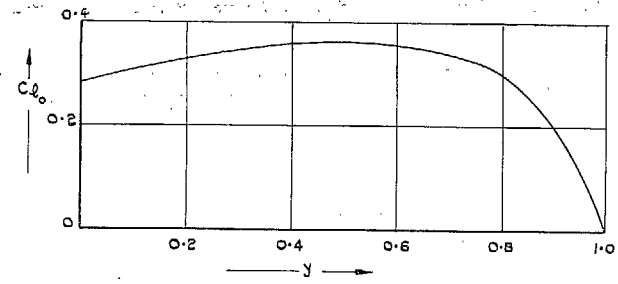
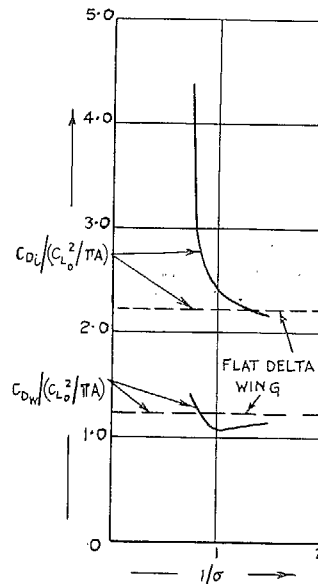


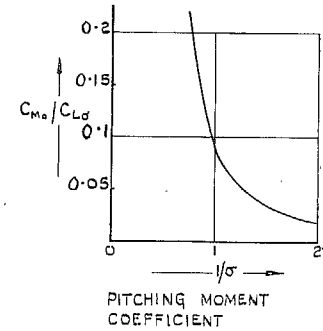
FIG. 9a. Surface (vib) for  $\gamma = 45$  deg.  $M = 1.281$ .  
Shape and pressure distribution.



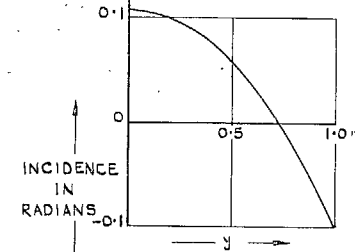
VARIATION OF LIFT COEFFICIENT ACROSS THE SEMI-SPAN FOR  $C_{L_0} = 0.33, \sigma = 1$



TOTAL INDUCED DRAG & INDUCED WAVE DRAG AT DESIGN INCIDENCE (WHEN  $1/\sigma = 1/2, C_{L_0} = 0$ )



PITCHING MOMENT COEFFICIENT



VARIATION OF INCIDENCE ACROSS THE SEMI-SPAN, FOR  $\sigma = 1, C_{L_0} = 0.33$

FIG. 9b. Delta wing (vib) for  $\gamma = 45$  deg.  $M = 1.281$ .

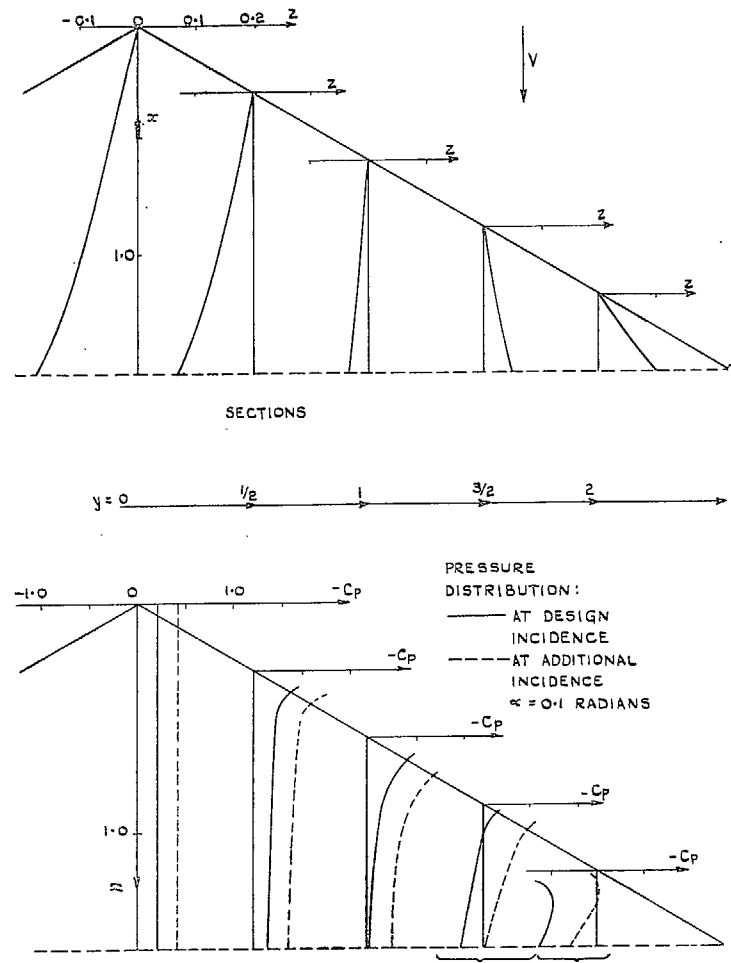


FIG. 10a. Surface (vii) for  $\gamma = 60$  deg.  $M = 1.13$ .  
 Shape and pressure distribution.

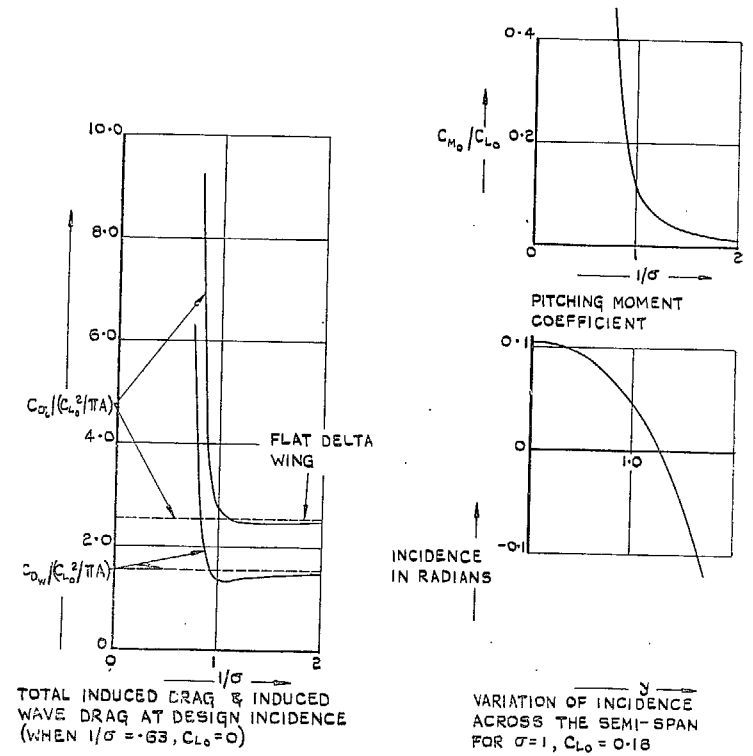
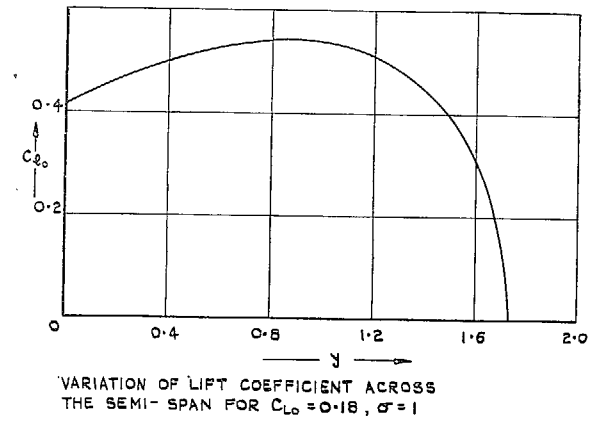


FIG. 10b. Delta wing (vii) for  $\gamma = 60$  deg.  $M = 1.13$ .

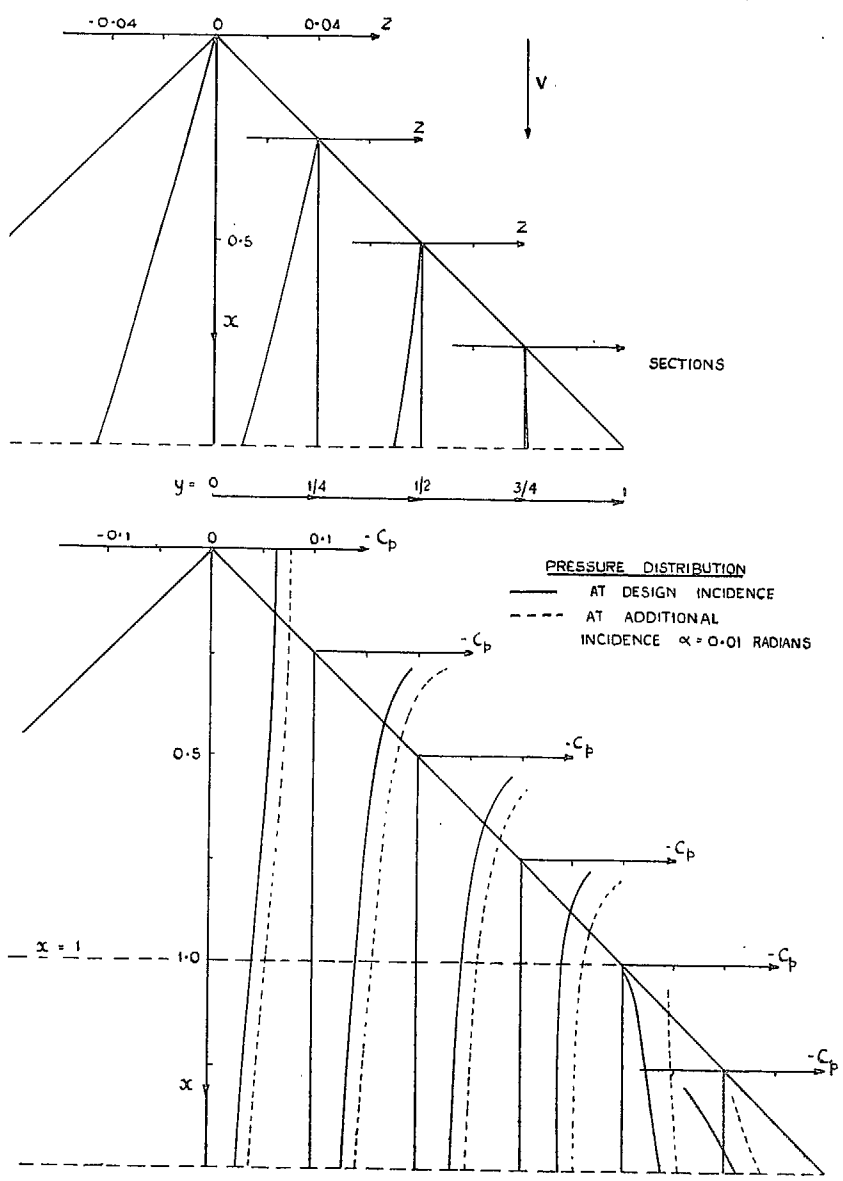


FIG. 11a. Surface (xii) for  $\gamma = 45$  deg.  $M = 1.281$ . Shape and pressure distribution.

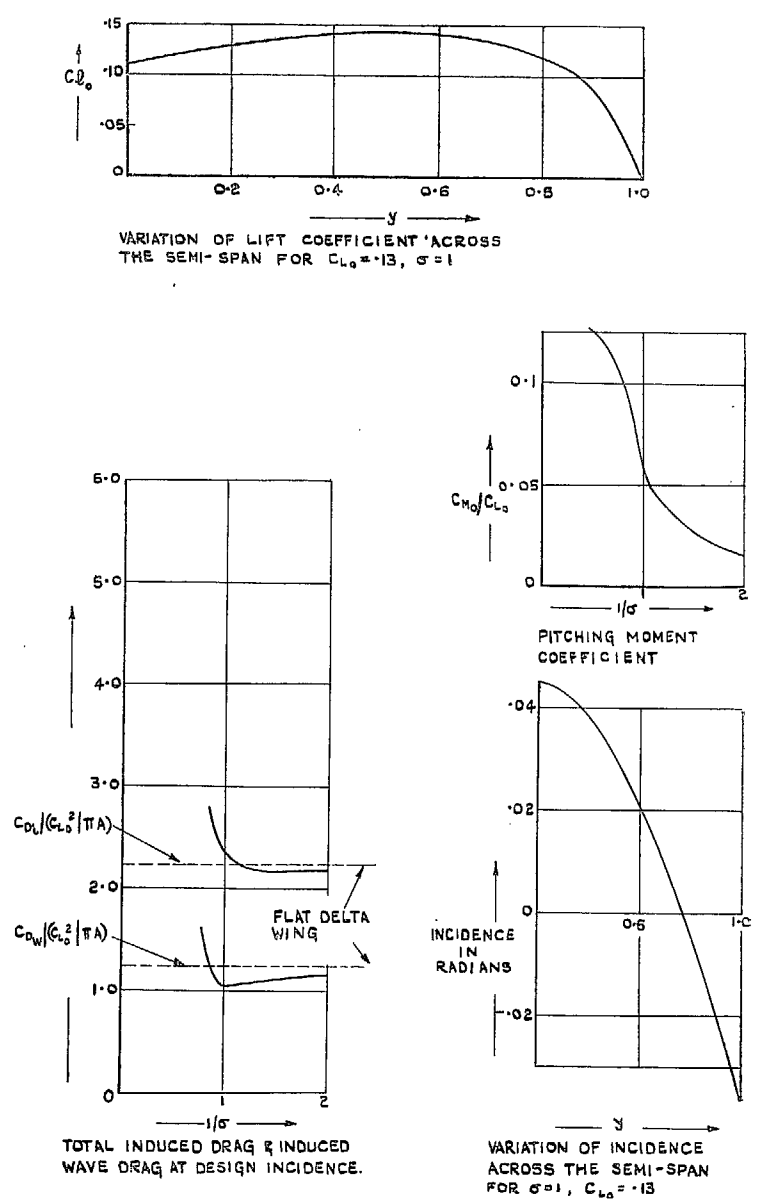


FIG. 11b. Delta wing (xii) for  $\gamma = 45$  deg.  $M = 1.281$ .

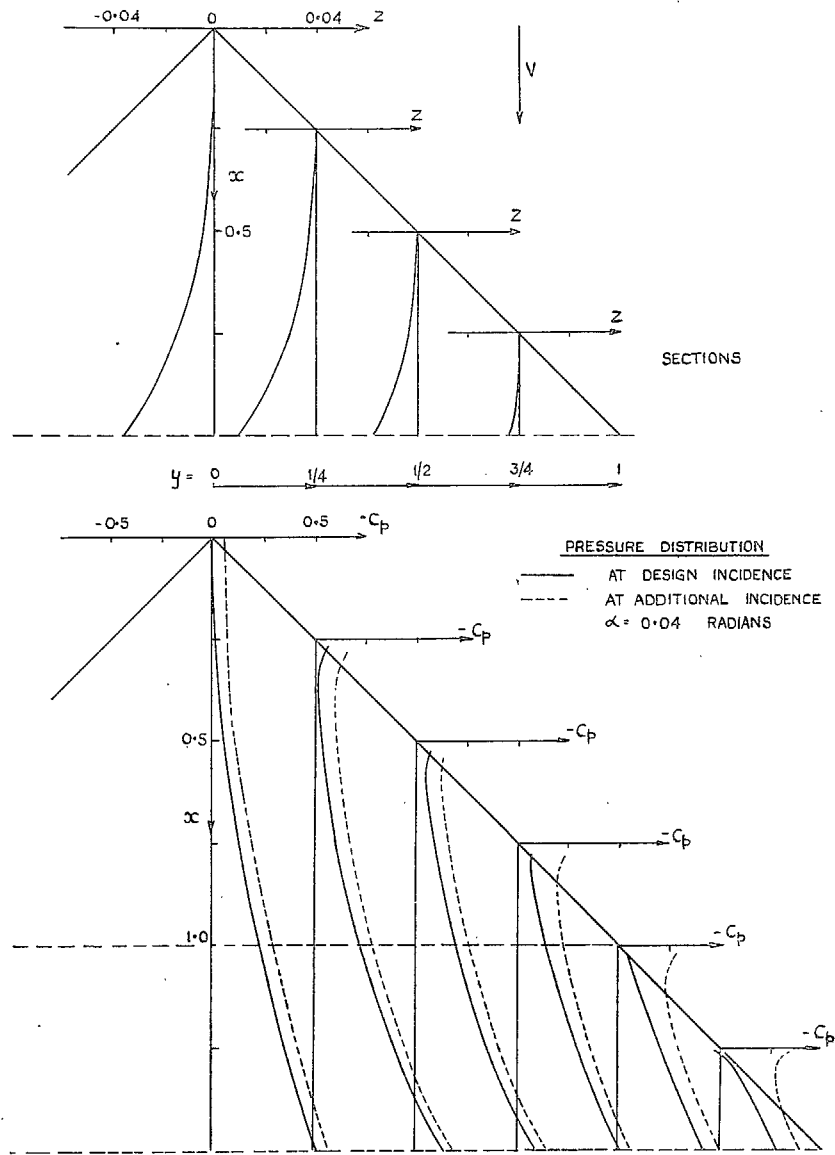


FIG. 12a. Surface (ix) for  $\gamma = 45$  deg.  $M = 1.281$ . Shape and pressure distribution.

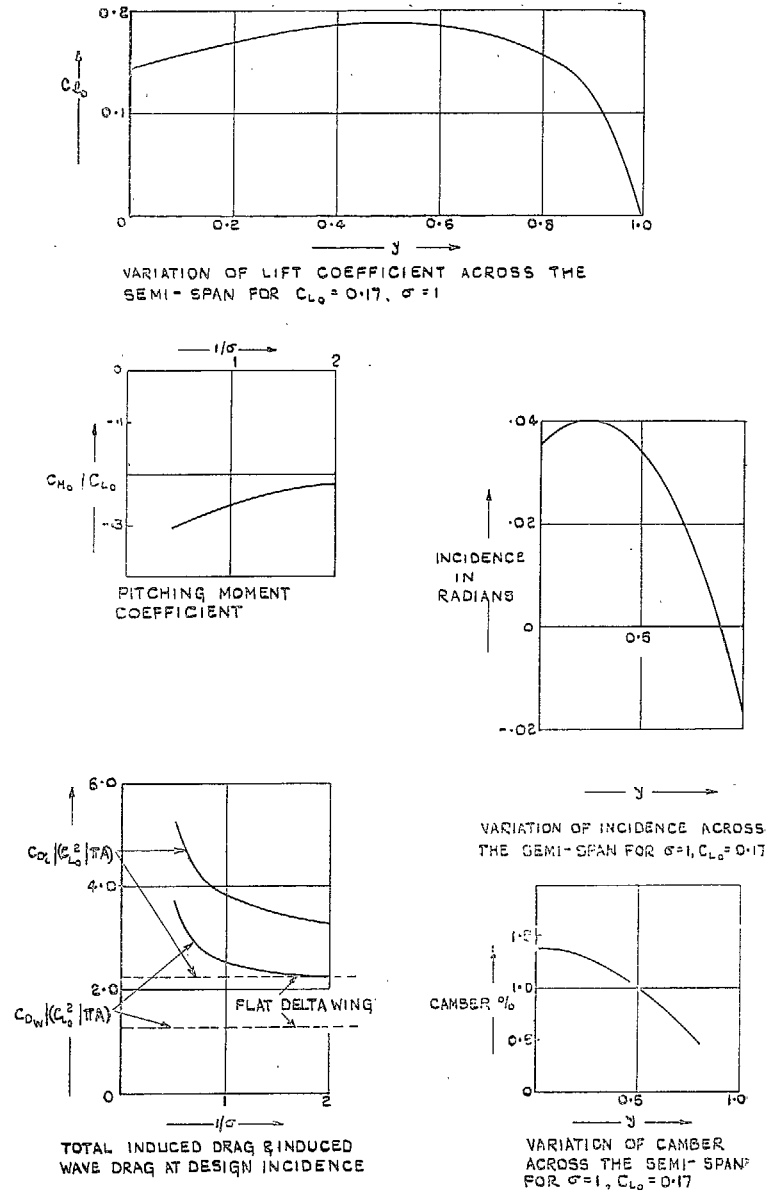


FIG. 12b. Delta wing (ix) for  $\gamma = 45$  deg.  $M = 1.281$ .

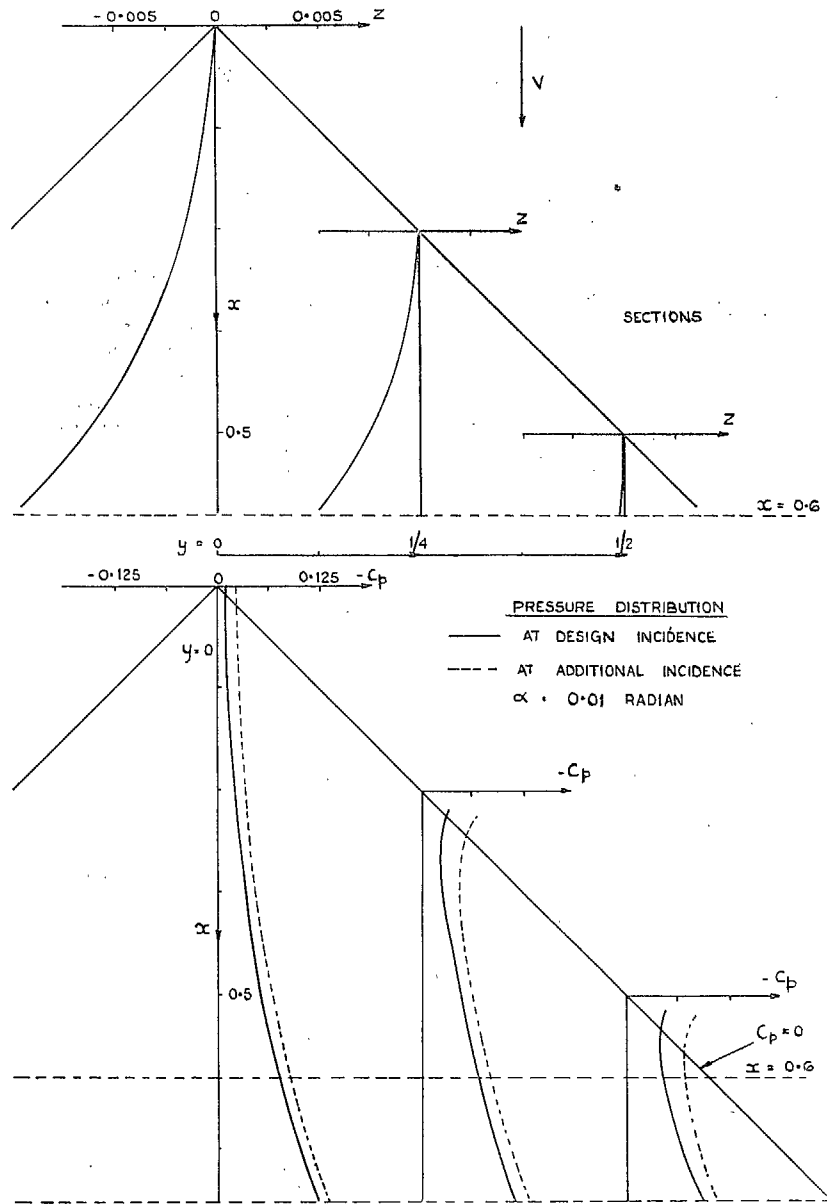


Fig. 13a. Surface (x) for  $\gamma = 45$  deg.  $M = 1.281$ . Shape and pressure distribution.

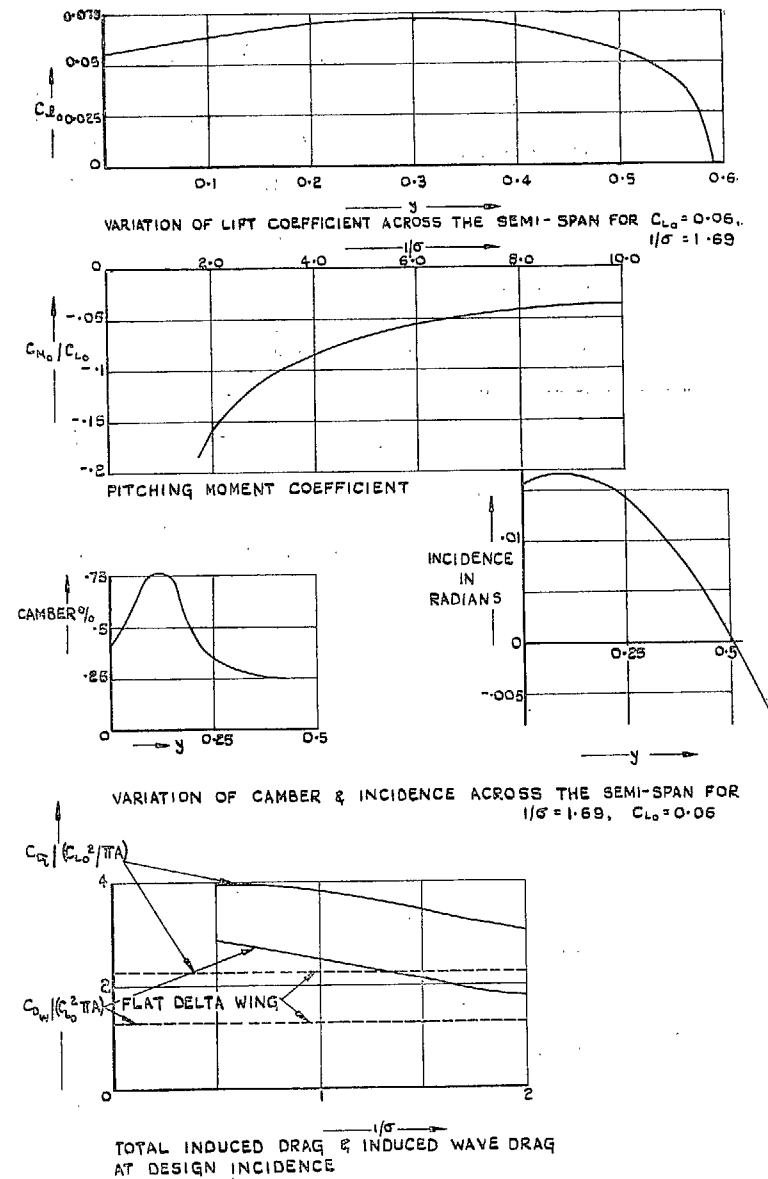


Fig. 13b. Delta wing (x) for  $\gamma = 45$  deg.  $M = 1.281$ .

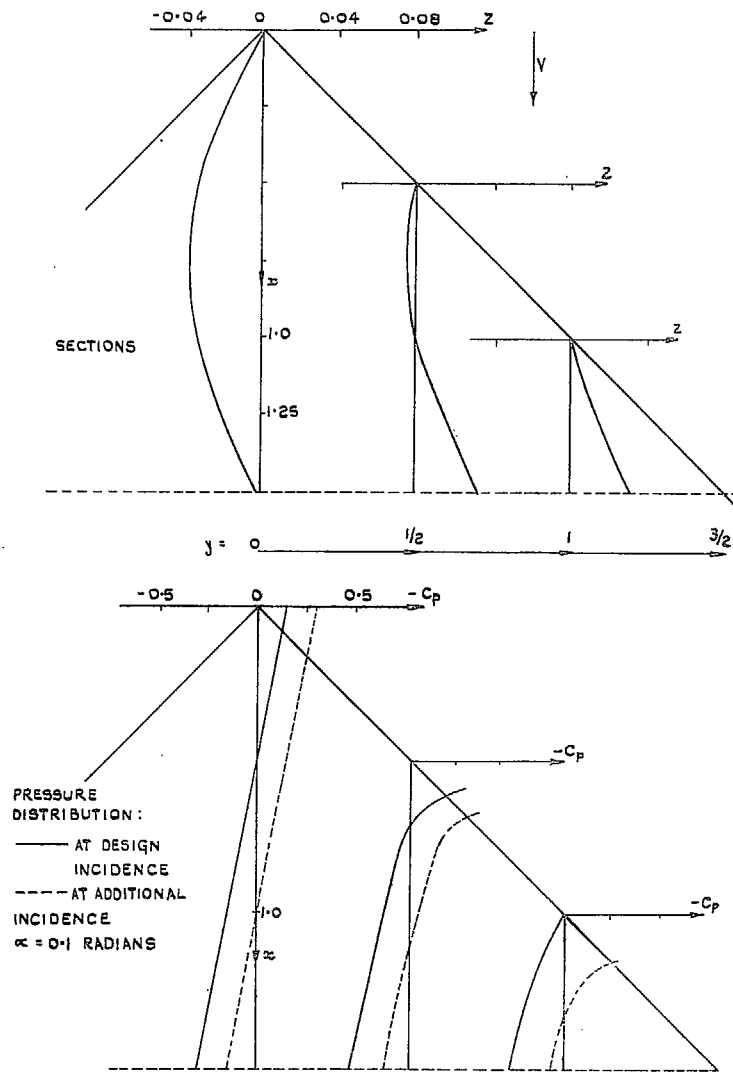


FIG. 14a. Surface (iii) for  $\gamma = 45$  deg.  $M = 1.166$ . Shape and pressure distribution.

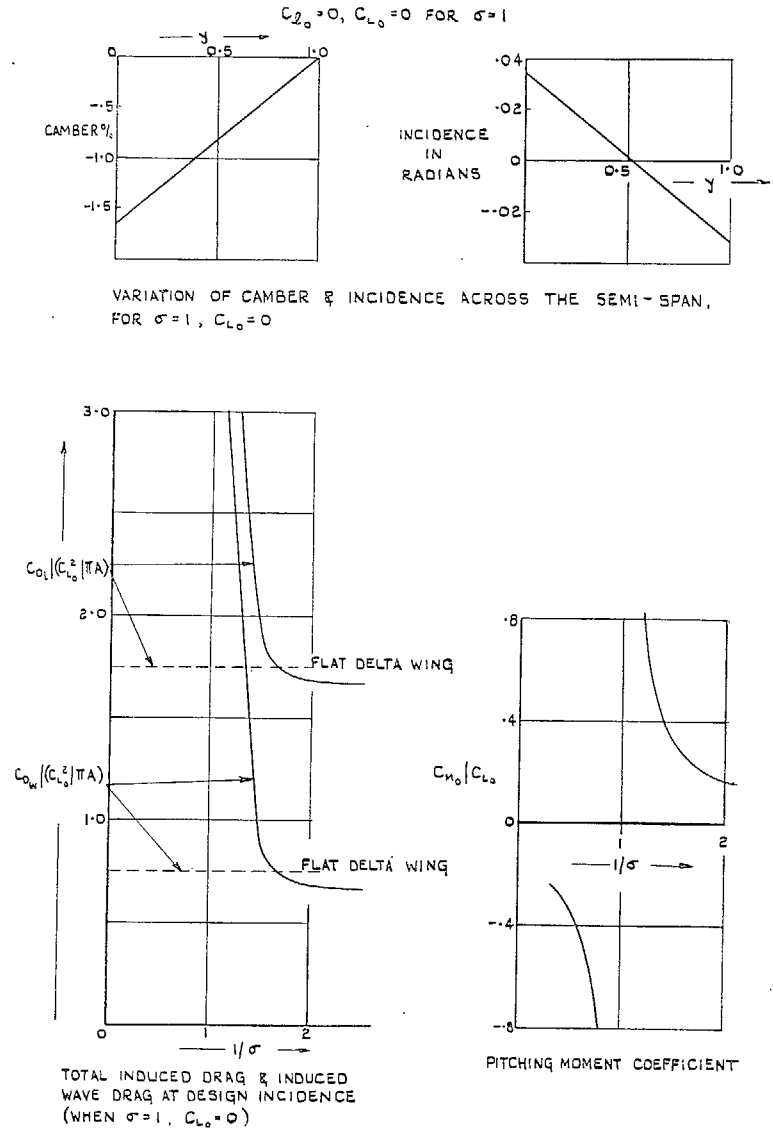
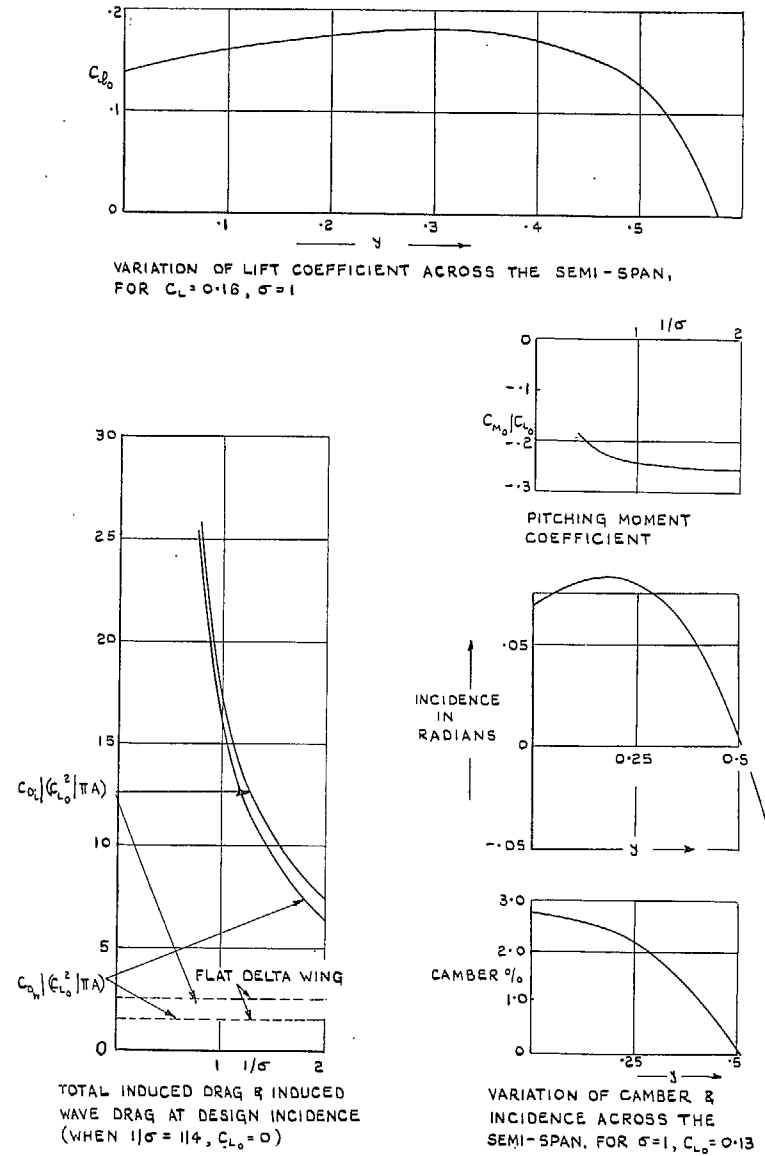
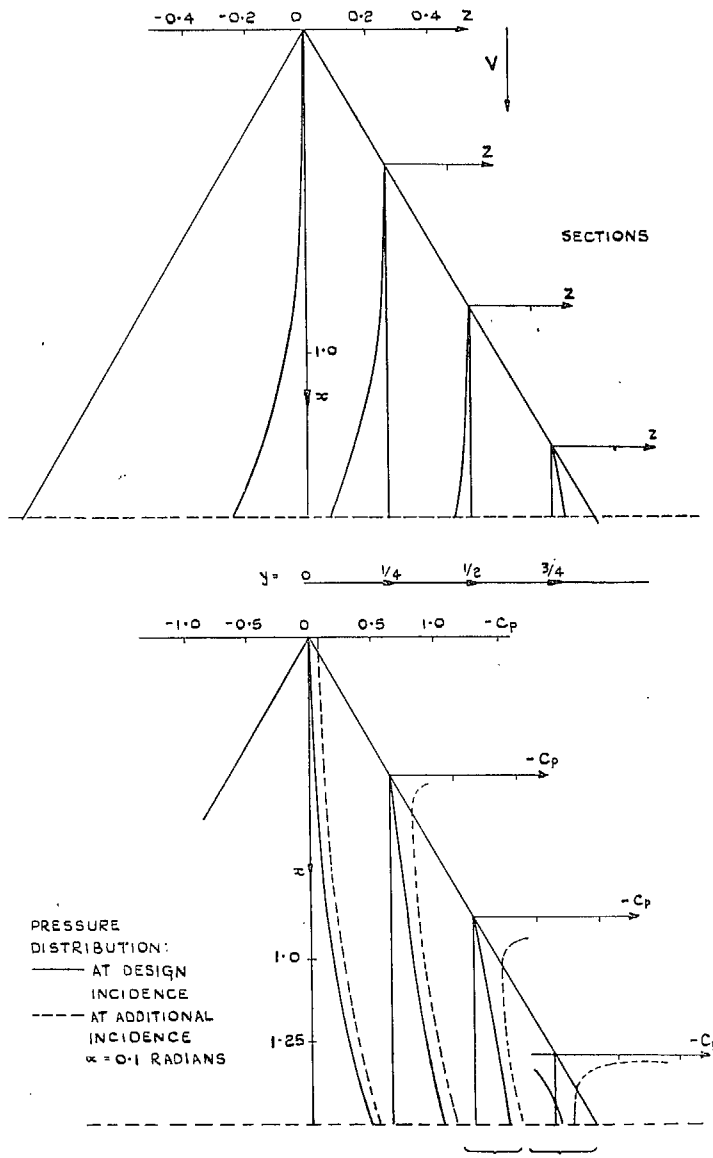


FIG. 14b. Delta wing (iii) for  $\gamma = 45$  deg.  $M = 1.166$ .





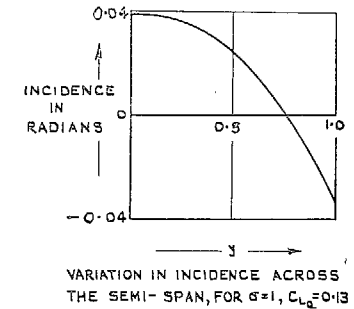
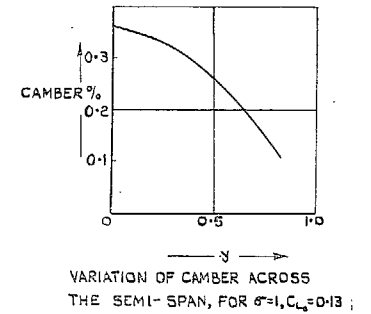
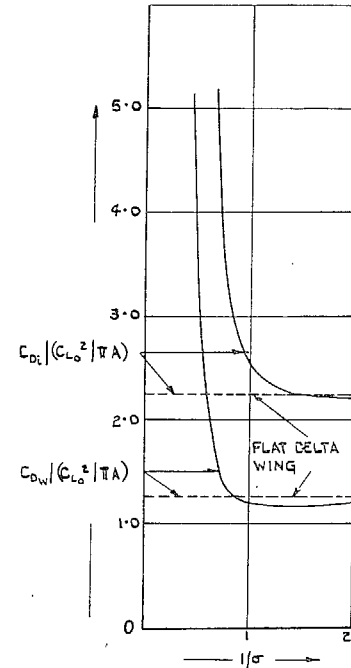
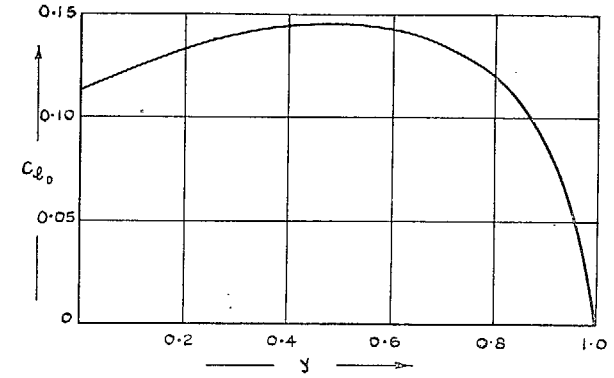
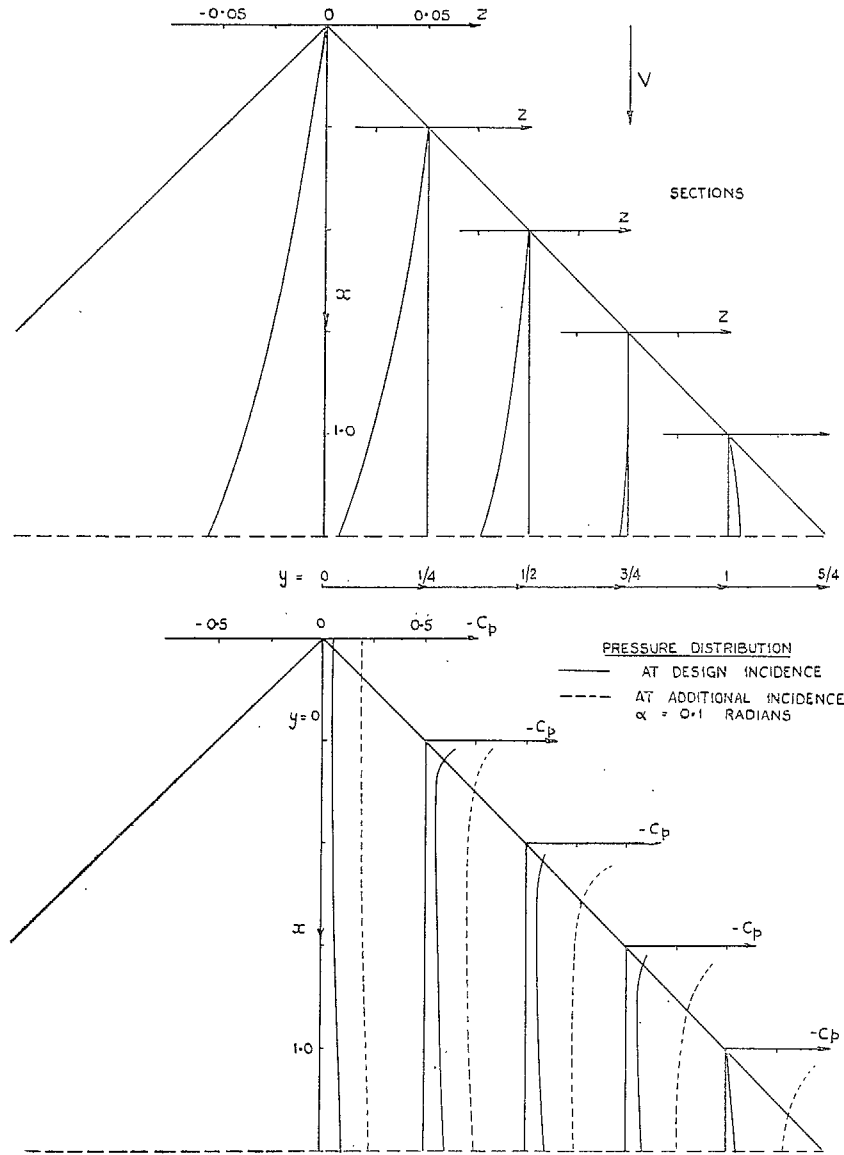


FIG. 16b. Delta wing (xiii) for  $\gamma = 45$  deg.  $M = 1.281$ .



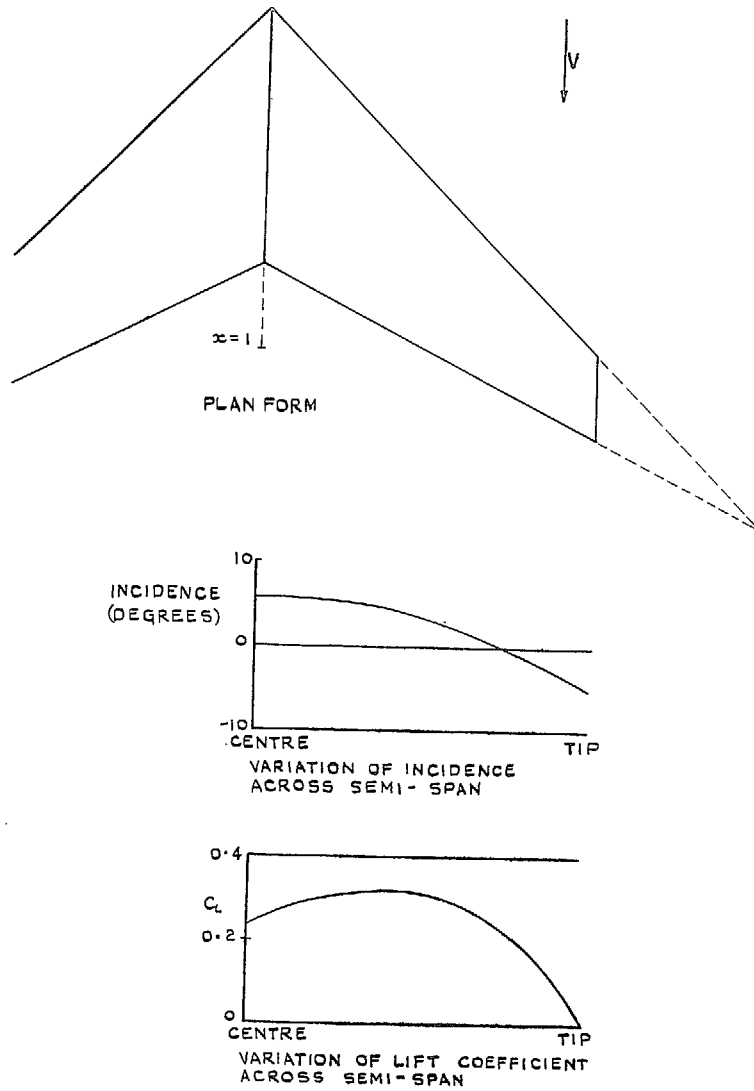


FIG. 18. Calculations for twisted wing of shape (vi),  $\gamma = 45$  deg.  
 $M = 1.345$ ,  $\alpha = 0$ .

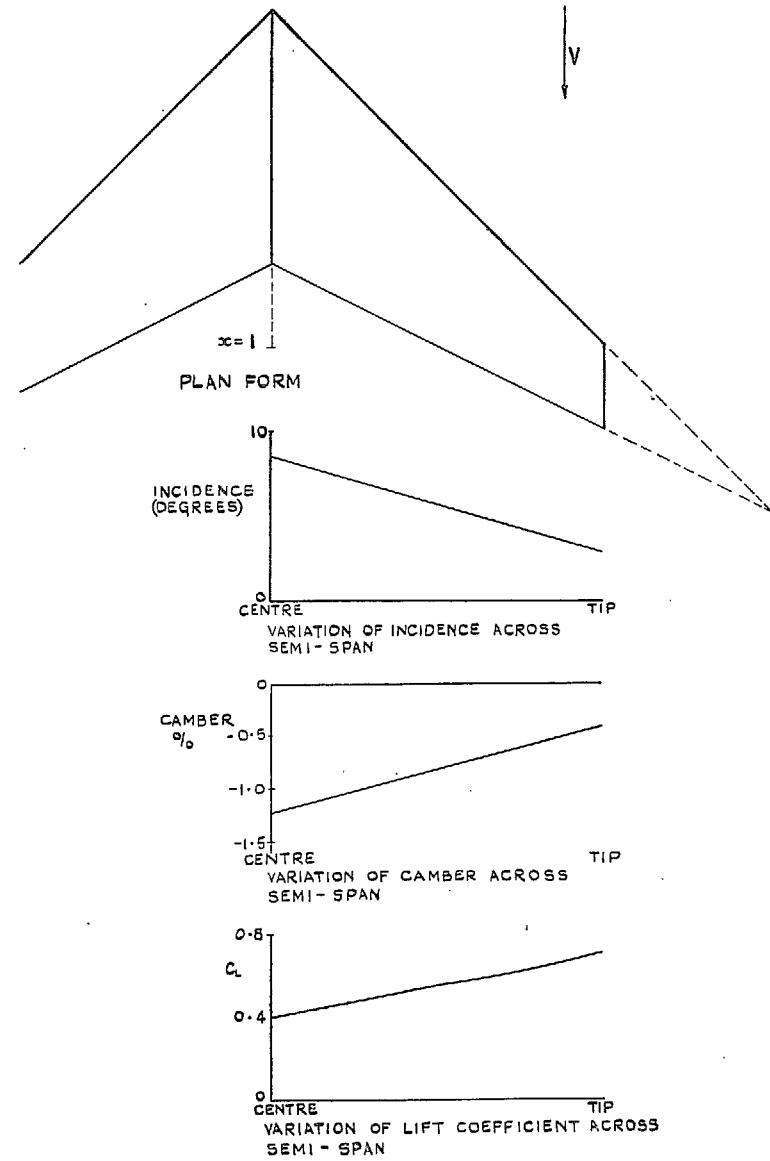
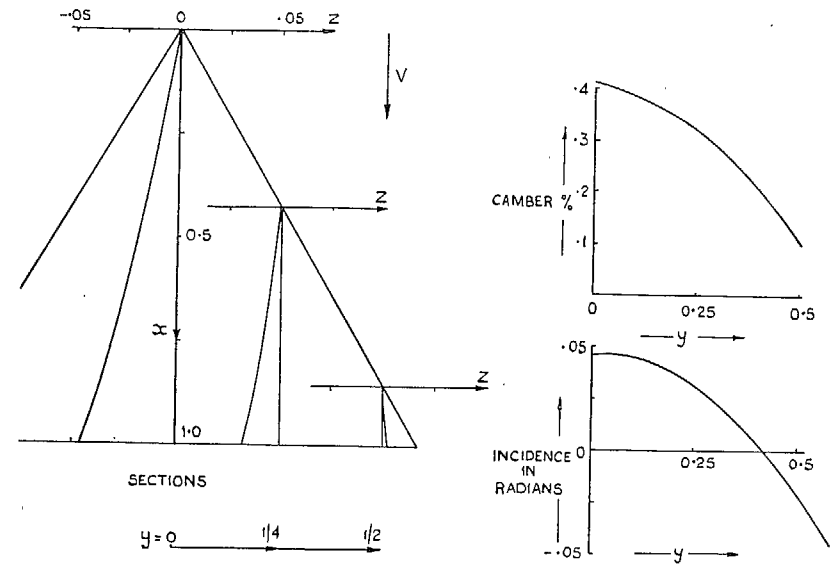


FIG. 19. Calculations for cambered and twisted wing of shape (iii),  
 $\gamma = 45$  deg.  $M = 1.166$ ,  $\alpha = 0.1$ .



VARIATION IN CAMBER & INCIDENCE ACROSS THE SEMI-SPAN

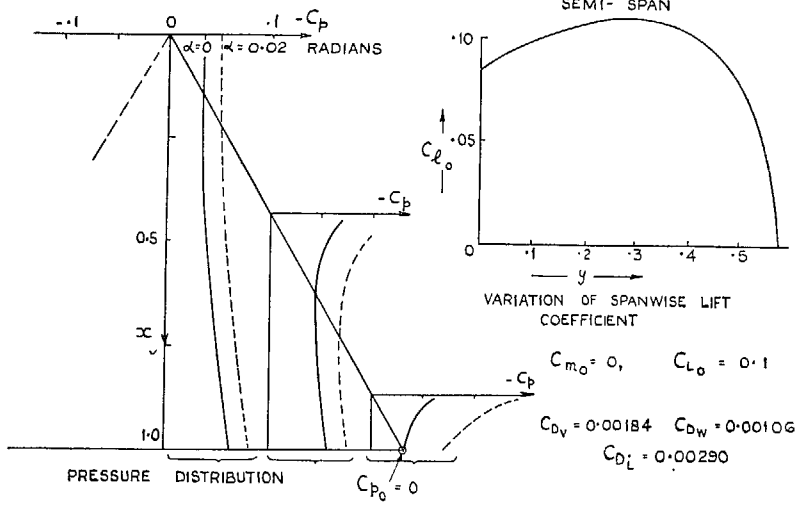
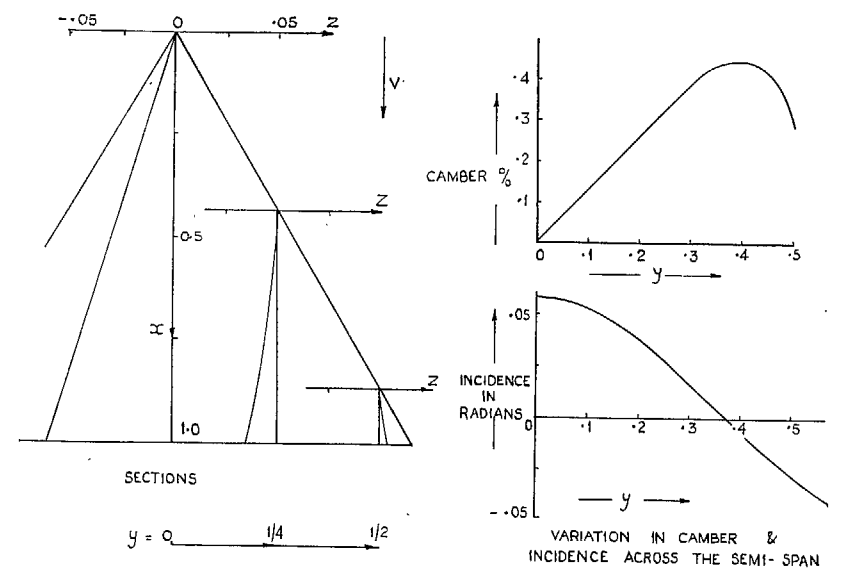


FIG. 20. Delta wing (xiv),  $\gamma = 30$  deg.  $M = 1.442$ . Shape and pressure distribution.



VARIATION IN CAMBER & INCIDENCE ACROSS THE SEMI-SPAN

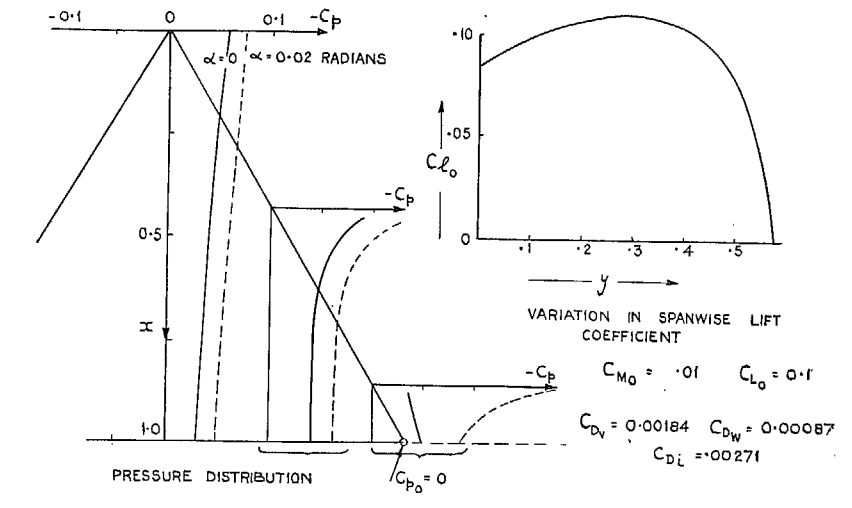


FIG. 21. Delta wing (xv),  $\gamma = 30$  deg.  $M = 1.442$ . Shape and pressure distribution.

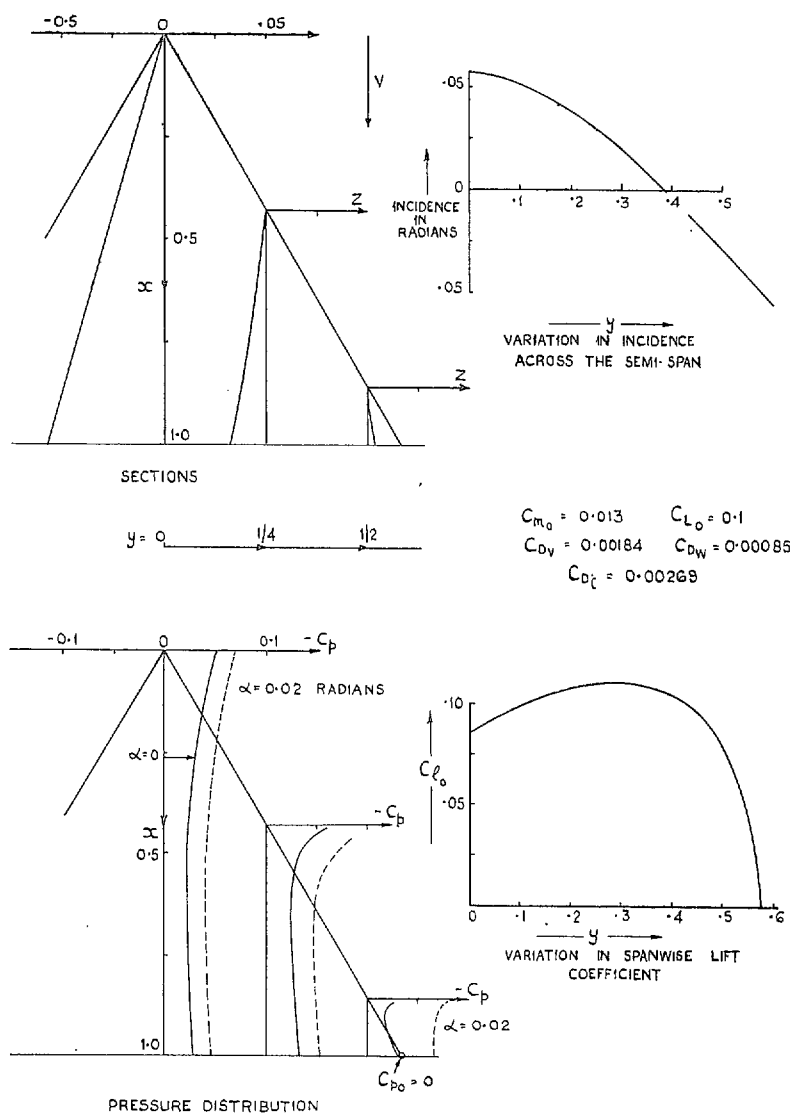


FIG. 22. Delta wing (xvi),  $\gamma = 30$  deg.  $M = 1.442$ . Shape and pressure distribution.

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