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# Theoretical Supersonic Drag of Non-lifting Infinitespan Wings Swept behind the Mach Lines 

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#### Abstract

Summary.-The drag of a non-lifting swept wing of infinite span is investigated for supersonic flow when the Mach lines from the wing apex lie ahead of the wing leading-edge. The wing section is assumed to be arbitrary but identical over the entire wing-span. The drag is found according to the linear equations of supersonic flow by considering the flow due to a system of superposed source planes.

The drag of such a wing is found to be finite and the effect of the speed of flight independent of the section shape assumed. The variation of drag with the section shape is shown to be proportional to the integral over the chord of the product of the local wing thickness and the value of the excess pressure existing in incompressible flow at the same position. The drag of wing-sections given by certain types of formula is evaluated in general terms, and some numerical results are given : the drag of sections with bluff noses and finite trailing-edge angles is generally between 0 and 15 per cent greater than the drag of a wing of the same sweep and thickness having a biconvex section.


Finally, methods of reducing the drag by changing the section shape are considered.

1. Introduction.-A question which is often raised in connection with supersonic aircraft is : how does the section shape affect the drag of a swept wing ? Experimental information on this point is at present limited, and the existing theoretical work is largely confined to wings of biconvex or double-wedge section : it is possible to determine the theoretical wave drag of other sections, but with the more ' realistic 'types of section shape the expressions to be evaluated are so lengthy that the amassing of a comprehensive set of results presents a formidable proggramme of computation ${ }^{6}$. Not only would such an analysis have to deal with the effect of section shape, but also with the variation of drag with aspect ratio and taper ratio, as well as with flight speed.

We shall here try to isolate the effect of section shape, by dealing only with constant-chord wings of infinite span having the same section at all spanwise positions. Clearly there is then no variation of aspect ratiọ or taper ratio to be considered; nor, as we shall see, does the effect of flight speed modify the relative drag of various sections. We assume that the speed of flight is

[^0]sufficiently low that the Mach lines from the wing apex lie ahead of the wing leading edge ; this is the only case of interest at the present time-indeed, if this condition is not satisfied the question we have posed is a trivial one.

It might seem that results for an infinite wing would, even so, be of little application. Certainly the results obtained do not apply exactly to finite wings but there is good reason to suppose that they will afford a guide to the general problem as the drag of a finite constant-chord swept wing is concentrated in the region of the root, and above a certain aspect ratio, increases in the span cause little or no increase in wave drag, as will be shown below.

Again, it may be objected that the effects of taper ratio are important ; this is certainly so, but a comparison of the relative drag of tapered wings of various sections would obviously depend upon the choice of a representative line of sweepback. No general conclusions on the effect of section shape alone can be drawn if the effect of varying sweepback is also included. This problem is outside the scope of the present investigations.

We shall deal with sections, amongst others, which have round noses and for this reason we have to find the drag on a streamtube rear the wing surface and then to find the drag of the wing by allowing this streamtube to approach the surface. This method is necessary as R. T. Jones has shown ${ }^{5}$ that in the type of 'subsonic' flow existing over the wing far outspan there is a contribution to the drag associated with the singularity at the round nose which is not included if we merely intergrate the pressure over the wing surface.

From the general theory for the drag of an infinite wing we shall consider three applications :-
(a) We shall state the results in several forms which are of particular use when the wing section is defined by certain types of formula, or its subsonic pressure distribution is known.
(b) We shall work out a few numerical examples to show the relative drags of various types of well-known sections.
(c) We shall seek to find what features of the wing geometry are of importance both from the aspect of contributing to the drag and of reducing it.
2. Drag of an Infinite Swept Wing.-According to the three-dimensional linear theory of supersonic flow ${ }^{1}$, a uniform plane distribution of sources in the plane $z=0$, bounded upstream by the line $y=m(x-\xi)$ and by the $x$-axis will produce, if

$$
m \sqrt{ }\left(M^{2}-1\right)=\mu \leqslant 1
$$

i.e., if the Mach lines, from $x=\xi$, are ahead of the plane source, a pressure distribution given by*

$$
\begin{equation*}
\frac{\Delta p}{q}=\frac{2}{\pi} \varepsilon \frac{m}{\sqrt{ }\left(1-\mu^{2}\right)} \mathscr{R}\left\{\arg \cosh \left[\frac{X-\xi+\left(1-\mu^{2}\right) \frac{y}{m}}{\left.\mu \sqrt{\left((X-\xi)^{2}+\left(1-\mu^{2}\right)\right.} \frac{z^{2}}{m^{2}}\right)}\right]\right\} . \tag{1}
\end{equation*}
$$

where $X=x-\frac{y}{m}$, and $\varepsilon$ is a constant.

[^1]The distribution of velocity in the $z$-direction is given by

$$
\begin{equation*}
\frac{w}{U}=-\frac{\partial}{\partial z} \int_{-\infty}^{x} \frac{1}{2}\left(\frac{\Delta p}{q}\right) d x \quad . \quad . \quad . \quad . \quad . \quad . \quad . \tag{2}
\end{equation*}
$$

and it may be shown that as $z \rightarrow 0$,

$$
\left.\begin{array}{rlrl}
\frac{w}{U} & =\operatorname{sgn}(z) \varepsilon & \quad \text { for } y \geqslant 0, \quad X>\xi  \tag{3}\\
& =0 & \text { for } y \geqslant 0, X<\xi, \text { and for } y \leqslant 0
\end{array}\right\}
$$

Thus, for small values of $\varepsilon$ this discontinuity in normal velocity satisfies the boundary condition for a semi-infinite oblique wedge having a small wedge angle $2 \varepsilon$, as shown in ${ }^{\text {" Fig. }} 1$.

Similarly, by superposition, it may be shown that a uniform plane distribution of sources in the plane $z=0$ bounded upstream by the lines $y= \pm m(x-\xi)$ will produce, if $\mu \leqslant 1$, a pressure distribution given by

$$
\frac{\Delta p}{q}=\varepsilon[f(x-\xi, y, z)+f(x-\xi,-y, z)]
$$

i.e.,

$$
\begin{equation*}
\frac{\Delta p}{q}=2 \varepsilon g(x-\xi, y, z) \text {, say } \quad \ldots \quad \quad . \quad . \quad . \quad . \quad . \quad . \tag{4}
\end{equation*}
$$

where, from (1),

$$
f(x-\xi, y, z)=\frac{2}{\pi} \frac{m}{\sqrt{\left(1-\mu^{2}\right)}} \mathscr{R}\left\{\arg \cosh \left[\frac{x-\xi-\mu^{2} \frac{y}{m}}{\left.\mu \sqrt{\left[\left(x-\xi-\frac{y}{m}\right)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}\right.}\right]}\right]\right\}
$$

and which satisfies the boundary condition for an infinite oblique wedge symmetrical about the $x$-axis and having a small wedge angle $2 \varepsilon$.

For the purposes of the present investigation we shall define such infinite source planes by their leading boundaries, and we shall call the quantity $\varepsilon$ the strength of the source plane. Thus a system of such source planes formed by:-
(a) a source plane bounded by $y= \pm m x$ of strength $z^{\prime}(0)$,
(b) a distribution of source planes bounded by $y= \pm m(x-\xi)$ of infinitesimal strength $z^{\prime \prime}(\xi) d \xi$, for all values of $\xi$ where $0 \leqslant \xi<c$,
(c) a source plane bounded by $y= \pm m(x-c)$ of strength $-z^{\prime}(c)$,
will together yield a flow which satisfies the boundary condition for an infinite swept wing with leading edges along $y= \pm m x$, trailing edges along $y= \pm m(x-c)$, and a thickness distribution $z= \pm z(X)$ as shown in Fig. 2.

The normal velocity distribution at any point due to the system of sources described above is given by

$$
\begin{aligned}
\frac{w}{U}= & -\frac{\partial}{\partial z}\left[z^{\prime}(0) \int_{-\infty}^{x} g(x, y, z) d x-z^{\prime}(c) \int_{-\infty}^{x} g(x-c, y, z) d x\right. \\
& \left.+\int_{0}^{c} z^{\prime \prime}(\xi)\left(\int_{-\infty}^{x} g(x-\xi, y, z) d x\right) d \xi\right] \\
= & \frac{\partial}{\partial z}\left[\int_{0}^{c} z^{\prime}(\xi) \frac{\partial}{\partial \xi}\left(\int_{-\infty}^{x} g(x-\xi, y, z) d x\right) d \xi\right]
\end{aligned}
$$

and since $g=0$ in front of the Mach cone from the point $x=\xi, y=0$,

$$
\begin{equation*}
\frac{w}{U}=-\int_{0}^{c} z^{\prime}(\xi) \frac{\partial g}{\partial z} d \xi . \quad \ldots \quad \ldots \quad \ldots \quad \ldots \tag{5}
\end{equation*}
$$

Similarly, the pressure distribution is given by

$$
\begin{equation*}
\frac{\Delta p}{q}=2 \int_{0}^{c} z^{\prime}(\xi) \frac{\partial g}{\partial x} d \xi . \quad . \quad . \quad . \quad . \quad . \quad . \quad . \quad . \tag{6}
\end{equation*}
$$

Here the pressure field is described as due to a superposition of source lines each giving an incremental normal displacement $z^{\prime}(\xi) d \xi$. This form of description is preferable to that of superposed source planes if $z^{\prime}(0)$ is infinite.

Consider an infinite streamtube enclosing the wing whose section far upstream in the plane $x=$ constant is formed of the two straight lines $z= \pm \psi$.

The equation for a section of this streamtube in the plane $y=$ constant is, according to the linear theory, given by
so that the drag on such a section is

$$
q \int_{-\infty}^{+\infty} \frac{d z}{d x} \frac{\Delta p}{q} d x=-2 q \int_{-\infty}^{+\infty}\left(\int_{0}^{c} z^{\prime}(\xi) \frac{\partial g}{\partial z} d \xi\right)\left(\int_{0}^{c} z^{\prime}(\xi) \frac{\partial g}{\partial x} d \xi\right) d x
$$

where $y$ is treated as a constant and $z$ is related to $x$ by equation (7). The drag on the complete wing is then given by

$$
\begin{equation*}
D=-8 q \lim _{\psi \rightarrow 0} \int_{0}^{\infty} d y \int_{-\infty}^{+\infty}\left(\int_{0}^{c} z^{\prime}(\xi) \frac{\partial g}{\partial z} d \xi\right)\left(\int_{0}^{c} z^{\prime}(\xi) \frac{\partial g}{\partial x} d \xi\right) d x \ldots \tag{8}
\end{equation*}
$$

where the limit is taken to mean the value of the integrand as the streamtube selected approaches the surface,

From (4), if $x-\xi \geqslant \frac{\mu}{m} \sqrt{ }\left(y^{2}+z^{2}\right)$

$$
\begin{gathered}
\frac{\partial g}{\partial z}=-\frac{1}{\pi}\left[\left\{\frac{x-\xi-\mu^{2} \frac{y}{m}}{\left(x-\xi-\frac{y}{m}\right)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}}+\frac{x-\xi+\mu^{2} \frac{y}{m}}{\left(x-\xi+\frac{y}{m}\right)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}}\right\}\right. \\
\times \frac{\frac{z}{m}}{\left.\sqrt{\left[(x-\xi)^{2}-\mu^{2}\left(\frac{y^{2}}{m^{2}}+\frac{z^{2}}{m^{2}}\right)\right]}\right]} \\
\frac{\partial g}{\partial x}=\frac{1}{\pi}\left[\left\{\frac{\left(\frac{y^{2}}{m^{2}}+\frac{z^{2}}{m^{2}}\right)-\frac{y}{m}(x-\xi)}{\left.\left(x-\xi-\frac{y}{m}\right)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}+\frac{\left(\frac{y^{2}}{m^{2}}+\frac{z^{2}}{m^{2}}\right)+\frac{y}{m}(x-\xi)}{\left(x-\frac{y}{m}\right)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}}\right\}}\right.\right. \\
\left.\times \frac{m}{\left.\left.\sqrt{(x-\xi)^{2}-\mu^{2}\left(\frac{y^{2}}{m^{2}}\right.}+\frac{z^{2}}{m^{2}}\right)\right]}\right]
\end{gathered}
$$

and both derivatives are zero if $x-\xi<\frac{\mu}{m} \sqrt{ }\left(y^{2}+z^{2}\right)$.
As was shown in Ref. 1, the integral

$$
\int_{0}^{c} z^{\prime}(\xi) \frac{\partial g}{\partial z} d \xi
$$

vanishes as $z \rightarrow 0$, except for those values of $x$ and $y$ such that for some value of $\xi$ between 0 and $c$,

$$
x-\xi-\frac{y}{m}=0
$$

i.e., on or near the wing surface. Near such a point,

$$
\lim _{z \rightarrow 0} \frac{\partial g}{\partial z} \rightarrow \lim _{z \rightarrow 0}\left[-\frac{z}{\pi m} \frac{\sqrt{ }\left(1-\mu^{2}\right)}{\left(x-\xi-\frac{y}{m}\right)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}}\right]
$$

and the integration may be confined to values of $\xi$ close to $\left(x-\frac{y}{m}\right)$.

Thus, near $z=0$, we may write equation (5) as

$$
\begin{equation*}
\frac{w}{U}=\frac{1}{\pi} \frac{z}{m} \sqrt{ }\left(1-\mu^{2}\right) \int_{0}^{c} \frac{z^{\prime}(\xi) d \xi}{(x-\xi)^{2}+(1-\mu)^{2} \frac{z^{2}}{m^{2}}} \quad \ldots \quad \ldots \quad \because . \tag{9}
\end{equation*}
$$

so that introducing independent variables $X$ and $y$, from (7), $\frac{w}{U}$ and $z$ become independent of $y$; and instead of (8) we may write

$$
\begin{equation*}
D=8 q \lim _{\psi \rightarrow 0} \lim _{b \rightarrow \infty}\left\{\int_{-\infty}^{+\infty}\left[\int_{0}^{c} z^{\prime}(\xi)\left(\left.\int_{0}^{b} \frac{\partial g}{\partial x}\right|_{X} d y\right) d \xi\right] \frac{w}{U} d X\right\} . \ldots \tag{10}
\end{equation*}
$$

But if $\left(1-\mu^{2}\right) \frac{y}{m} \geqslant \mu \sqrt{ }\left((X-\xi)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}\right)-(X-\xi)$

$$
\begin{aligned}
& \left.\int \frac{\partial g}{\partial x}\right|_{X} d y=\left\{\frac{m^{2}\left(3-\mu^{2}\right)}{2 \pi\left(1-\mu^{2}\right)^{3 / 2}} \arg \cosh \left[\frac{X-\xi+\left(1-\mu^{2}\right) \frac{y}{m}}{\mu \sqrt{\left((X-\xi)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}\right)}}\right]\right. \\
& -\frac{m^{2}(X-\xi)}{\pi\left(1-\mu^{2}\right)\left[(X-\xi)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}\right]} \sqrt{ }\left[\left(X-\xi+\frac{y}{m}\right)^{2}-\mu^{2}\left(\frac{y^{2}}{m^{2}}+\frac{z^{2}}{m^{2}}\right)\right] \\
& -\frac{m^{2}}{2 \pi} \frac{\left[2(X-\xi) \alpha-\left(1+\mu^{2}\right) \frac{z^{2}}{m^{2}}+(X-\xi)^{2}\right]}{\sqrt{\left\{\mathscr{D}\left[4 \alpha^{2}+4(X-\xi) \alpha+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}+(X-\xi)^{2}\right]\right\}}} \arctan \left[A\left(\frac{y}{m}-\alpha\right)\right] \\
& +\frac{m^{2}}{2 \pi} \frac{\left[2(X-\xi) \beta-\left(1+\mu^{2}\right) \frac{z^{2}}{m^{2}}+(X-\xi)^{2}\right]}{\left.\sqrt{\left\{\mathscr{D}\left[4 \beta^{2}+4(X-\xi) \beta+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}+(X-\xi)^{2}\right]\right\}} \arg \tanh \left[B\left(\frac{y}{m}-\beta\right)\right]\right\}}
\end{aligned}
$$

where

$$
\begin{aligned}
& A=\left(\frac{\mathscr{D}}{\left[4 \alpha^{2}+4(X-\xi) \alpha+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}+(X-\xi)^{2}\right]\left[\left(1-\mu^{2}\right) \frac{y^{2}}{m^{2}}+2(X-\xi) \frac{y}{m}+(X-\xi)^{2}-\mu^{2^{2}} \frac{z^{2}}{m^{2}}\right]}\right)^{i / 2} \\
& B=\left(\frac{\mathscr{D}}{\left[4 \beta^{2}+4(X-\xi) \beta+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}+(X-\xi)^{2}\right]\left[\left(1-\mu^{2}\right) \frac{y^{2}}{m^{2}}+2(X-\xi) \frac{y}{m}+(X-\xi)^{2}-\mu^{2} \frac{z^{2}}{m^{2}}\right]}\right)^{1 / 2}
\end{aligned}
$$

$$
\alpha=\frac{\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}-(X-\xi)^{2}}{(X-\xi)} \quad \beta=-\frac{2(X-\xi)}{\left(1-\mu^{2}\right)}
$$

and

$$
\mathscr{O}=\left[\left(1-\mu^{2}\right)(X-\xi)^{2}+\left(1+\mu^{2}\right)^{2} \frac{z^{2}}{m^{2}}\right]
$$

On the other hand, if

$$
\left(1-\mu^{2}\right) \frac{y}{m}<\mu \sqrt{ }\left((X-\xi)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}\right)-(X-\xi)
$$

then

$$
\left.\int \frac{\partial g}{\partial x}\right|_{x} d y=0
$$

Hence if $b \rightarrow \infty$ and $z \rightarrow 0$,

$$
\begin{aligned}
\left.\int_{0}^{b} \frac{\partial g}{\partial x}\right|_{X} d y \rightarrow & \left\{\frac{m^{2}\left(3-\mu^{2}\right)}{2 \pi\left(1-\mu^{2}\right)^{3 / 2}} \ln \frac{1}{\left.\sqrt{\left((X-\xi)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}\right.}\right)}\right. \\
& \left.-\frac{m b}{\pi \sqrt{ }\left(1-\mu^{2}\right)} \frac{(X-\xi)}{\left[(X-\xi)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}\right]}+c_{1}+c_{2} \operatorname{sgn}(X-\xi)+O\left(\frac{1}{b}\right)\right\}
\end{aligned}
$$

where $c_{1}$ and $c_{2}$ are constants involving $b$, and $z$ has been included only in those connections which affect the singularities of the integral in the limit as $z \rightarrow 0$.
Now,

$$
\lim _{\varphi \rightarrow 0} \int_{-\infty}^{+\infty}\left[\int_{0}^{c} z^{\prime}(\xi)\left[c_{1}+c_{2} \operatorname{sgn}(X-\xi)\right] d \xi\right] \frac{w}{U} d X=0
$$

so that

$$
\frac{D}{q}=\lim _{y \rightarrow 0} \int_{-\infty}^{+\infty}\left(V_{1}-V_{2}\right) d X
$$

where

$$
\begin{aligned}
V_{1}= & \frac{4 m z}{\pi^{2}}\left(\frac{3-\mu^{2}}{1-\mu^{2}}\right)\left\{\int_{0}^{c} z^{\prime}(\xi) \ln \frac{1}{\left.\sqrt{\left((X-\xi)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}\right)} d \xi\right\}}\right. \\
& \times\left\{\int_{0(X-\xi)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}}^{c}\right\} \\
V_{2}= & \frac{8 b z}{\pi^{2}}\left\{\int_{0}^{c} \frac{z^{\prime}(\xi) d \xi}{}\right\} \\
& =z^{\prime}(\xi)(X-\xi) d \xi \\
& \left\{\int_{0}^{c} \frac{z^{\prime}(\xi) d \xi}{(X-\xi)^{2}+\left(1-\mu^{2}\right) \frac{z^{2}}{m^{2}}}\right\}
\end{aligned}
$$

The integral involving $V_{2}$ is merely proportional to the drag force on the given wing section in two-dimensional incompressible flow, and may be shown to be zero, Hence

$$
\frac{D}{q}=\lim _{\psi \rightarrow 0} \int_{-\infty}^{+\infty} V_{1} d X .
$$

This integral may be simplified by finding the limiting value of the integrand as $z \rightarrow 0$, and then integrating with respect to $X$ whence

$$
\frac{D}{q}=\frac{4 m^{2}}{\pi} \frac{3-\mu^{2}}{\left(1-\mu^{2}\right)^{3 / 2}} \int_{0}^{c} z^{\prime}(X)\left[\int_{0}^{c} \frac{z(\xi)}{\xi-X} d \xi\right] d X,
$$

an expression which we shall put in a more useful form by writing

$$
\frac{X}{c}=s, \quad \frac{\xi}{c}=\sigma, \quad z(X)=\frac{t}{2} \zeta(s)
$$

where $t$ is the maximum thickness of the wing.
Then,

$$
\begin{equation*}
\frac{D}{q m^{2} t^{2}}=\frac{1}{\pi} \frac{3-\mu^{2}}{\left(1-\mu^{2}\right)^{3 / 2}} I \quad . . \quad . \quad . \quad . \quad . . \quad . \quad . . \quad . \quad \text {.. } \tag{11}
\end{equation*}
$$

where

$$
\begin{equation*}
I=\int_{0}^{+1} \int_{0}^{+1} \zeta^{\prime}(s) \zeta^{\prime}(\sigma) \ln \left|\frac{1}{\sigma-s}\right| d s d \sigma \quad . \quad . \quad . \quad . \quad . \tag{12}
\end{equation*}
$$

This equation applies to wings of infinite span.
A more detailed examination of equation (10) will show that for wings of finite span, far outboard the local drag is negative and tends to zero inversely as the cube of the span. The drag of a high aspect ratio wing is, therefore, equal to the drag of the infinite wing if we neglect terms of order $1 / A^{2}$ and higher compared with unity, where $A$ is the aspect ratio. In terms of the drag coefficient based on the wing area $S$ the drag of a finite wing of high aspect ratio is given by

$$
C_{D}=\frac{D}{q S}=\frac{(t / c)^{2}}{\tan \Lambda} \frac{1}{\pi} \frac{3-\mu^{2}}{\left(1-\mu^{2}\right)^{3 / 2}} \frac{I}{A \tan \Lambda} .
$$

For a wing of biconvex section $I=4$, and a comparison of this approximation with correct theoretical values for finite untapered wings of biconvex section is shown in Fig. 3.
3. Applications of Result.-3.1. Drag of Some Elementary Wing Sections with Round, Angular and Cusped Edges.-The quantity D/qm ${ }^{2} t^{2}$ as obtained from equation (11) is the product of two terms, one depending only on the Mach number and sweepback angle (i.e., on $\mu$ ), and the other a function only of the section geometry; we may write
where

$$
\frac{D}{q m^{2} t^{2}}=h(\mu) \frac{I}{4}
$$

where

$$
h(\mu)=\frac{4}{[\pi} \frac{3-\mu^{2}}{\left(1-\mu^{2}\right)^{3 / 2}}
$$

is plotted in Fig. 4.
At a given Mach number, two infinite wings of the same sweepback and thickness have a drag which is proportional only to $I$ : accordingly the drag of various elementary sections* can usefully be quoted in terms of $I$ as in Table 1 or Fig. 5.

[^2]It may legitimately be objected that the theory is not applicable to sections with round noses, because the perturbation velocities are not small in the region of the nose. In particular, at the wing-root leading-edge the pressure is infinite: but far outspan the pressure distribution resembles that in linearised two-dimensional incompressible flow. However the analysis in section 2 remains valid if we allow $z^{\prime}(0)$ to approach infinity.

Fig. 5 displays the fact that sections having a continuous slope and round edges generally have a high drag. The drag may be reduced by sharpening the edges, and still further reduced by cusping. The relatively low drag of the double-wedge sections is also evident. Most of the theoretical data on finite wings have been obtained for biconvex and double-wedge sections. It will be seen from Fig. 5, that the drag of the 'conventional' section, which resembles those commonly used on aircraft, is just over 10 per cent greater than a biconvex section, and over 60 per cent greater than a double-wedge section.
3.2. Drag of Wing Sections expressed as a Fourier Series.-Wing profiles are commonly derived from formulae of the type

$$
\begin{equation*}
\zeta(s)=\sum_{1}^{2 m+1} \beta_{n} \sin n \theta, \quad \text { where }\left(\frac{1-\cos \theta}{2}\right)=s \quad \ldots \quad \quad . \quad . \quad . \tag{13}
\end{equation*}
$$

with some modification of the shape near the trailing edge. It may be shown that for sections given by equation (13)

$$
\begin{equation*}
I=\frac{\pi^{2}}{2} \sum_{1}^{2 m+1} n \beta_{\pi 2}{ }^{2} . \quad . \quad . \quad . \quad \quad . \quad \text {.. .. .. .. } \tag{14}
\end{equation*}
$$

From equations (13) and (14), or otherwise, it may be shown that the profile having the least drag for a given cross-sectional area is the ellipse. However, apparently there is no optimum shape of profile having the least drag for a given thickness. It is always possible to find a section which has a drag less than any given finite value, so that the minimum value of $I$ is theoretically zero. Such 'low-drag' sections as are obtained in this limiting process are characterised by their thin (or cusped) edges and very marked regions of concavity.

In section 4.4 it will be shown that any modification to the shape of a double-wedge section (with maximum thickness at half-chord) to produce less drag, will introduce a region of concave curvature.

Thus, of the sections having no concave curvature, the double-wedge section has the smallest drag for a given thickness.
3.3. Drag of Wing Sections in Terms of the Subsonic Pressure Distribution.-An alternative form for $I$ which is of interest is obtained as follows :

$$
\begin{align*}
& I=\int_{0}^{1} \zeta^{\prime}(\sigma)\left(\int_{0}^{1} \zeta^{\prime}(s) \ln \left|\frac{1}{s-\sigma}\right| d s\right) d \sigma=\int_{0}^{1} \zeta(\sigma)\left(\int_{0}^{1} \frac{\zeta^{\prime}(s)}{\sigma-s} d s\right) d \sigma \\
& I=-\pi\binom{c}{\bar{t}} \int_{0}^{1} \zeta(\sigma)\left[\frac{\Delta p}{q}\right]_{\text {inc }} d \sigma \quad . \quad . \quad . \quad . \quad . \quad . \quad . \tag{15}
\end{align*}
$$

where $\left[\frac{\Delta p}{q}\right]_{\text {inc }}$ is the pressure distribution over the section in linearised two-dimensional incompressible flow. Generally, special wing-sections are designed for a given simple low-speed pressure distribution, and together with the tabulated list of ordinates, equation (15) can be a useful method for computing $I$ numerically-especially if the formal expression of the surface shape is obscure.

This method was used to compute the drag of the RAE $100-104$ series of aerofoil sections* and the results are given in Table 2. The drag of these wings is only 5 -10 per cent higher than the biconvex section.

Because most practical 'low-drag' sections are designed to have a more or less uniform pressure distribution in incompressible flow (i.e., with no high suctions), it follows from equation (15) that their relative drags are roughly proportional to the sectional area.
3.4. Drag of a Thin Wing Section derived from Conformal Transformation of Circle.-If $W$ is the complex potential of an incompressible flow (with velocity $U$ parallel to the $x$-axis at infinity) about a thin profile, let us consider the expression

$$
\begin{equation*}
\int_{c}\left(\frac{d W}{d Y}-U\right) Y d Y=\int_{c}(u-U-i w)(x+i z)(d x+i d z) \quad . . \quad . \tag{16}
\end{equation*}
$$

where $C$ is a closed contour, $u$ and $w$ are the velocity components parallel to the $x$ - and $z$-axes, and $Y=x+i z$.

We wish to find $I$, where, from equation (15), since the profile is thin, we have

$$
\begin{equation*}
I=\frac{4 \pi}{t^{2}} \int_{0}^{c}\left(\frac{u-U}{U}\right) z d x \quad . \quad . \quad . \quad . . \quad . . \quad . \quad . \quad . \tag{17}
\end{equation*}
$$

Now if the contour $C$ is formed by the zero streamline (including the upper surface of the profile) between $x=R$ and $-R$, and the large semicircle $T$ in the upper half-plane of radius $R$ about the origin, then, from equation (16), using the fact that on a streamline $w d x=u d z$,

$$
\begin{gather*}
\int_{0}^{c}(U-u) z d x=U \int_{0}^{c} z d x+\mathscr{I}\left\{\int_{\Gamma}\left(\frac{d W}{d Y}-U\right) Y d Y\right\} \\
-\mathscr{I}\left\{\int_{c}\left(\frac{d W}{d Y}-U\right)\right\} Y d Y \ldots \quad . . \quad . \tag{18}
\end{gather*}
$$

where, since the profile is thin, we have neglected terms of powers higher than 2 in $w / U$ and $z / c$. Thus the problem of finding $I$ is reduced to that of evaluating the integrals on the righthand side of equation (18).

Let us assume that the profile is derived from a transformation of a circle in the $(\xi, \zeta)$-plane, where

$$
\begin{equation*}
Y=f(H)=H+\frac{\alpha_{1}}{H}+\frac{\alpha_{2}}{H^{2}}+\ldots \ldots . \tag{19}
\end{equation*}
$$

and where $H=\eta+i \zeta$. Now, in the absence of circulation, if the profile is symmetrical about the $x$-axis,

$$
\begin{equation*}
W=U\left(H^{\prime}+\frac{a^{2}}{H^{\prime}}\right) \quad . . \quad . . \quad . \quad . \quad . \quad . \quad . \quad . \tag{20}
\end{equation*}
$$

where $H^{\prime}=H-h, h$ being a positive constant $<a$, and $a$ being the radius of the circle to be transformed.

[^3]It follows that in equation (18), if we let $R \rightarrow \infty$,

$$
\begin{equation*}
\int_{0}^{c} \frac{(u-U)}{U} z(x) d x=\left[\pi\left(a^{2}-\alpha_{1}^{*}\right)-V\right] \quad \ldots \quad . . \quad . . \quad . \quad . \tag{21}
\end{equation*}
$$

where

$$
V=\int_{0}^{c} z(x) d x, \text { and } \alpha_{1}^{*}=\mathscr{R}\left(\alpha_{1}\right)
$$

Thus, from (17)

$$
\begin{equation*}
I=\frac{4 \pi}{t^{2}}\left[\pi\left(a^{2}-\alpha_{1}^{*}\right)-V\right] . \quad . \quad . . \quad . \quad . . \quad . . \quad . \quad . \tag{22}
\end{equation*}
$$

Now from equation (12) it is clear that the value of $I$ depends only on the profile, or relative shape, and is independent of the thickness/chord ratio of the section. But it is important that in (22) the values of $t$ and $V$ are those for which the values of $a$ and $\alpha_{1}$ obtain; i.e., they are the geometrical characteristics of the profile obtained by the transformation.

As a simple example, consider the Joukowski transformation given by $\alpha_{1}=k a^{2}$ and $\alpha_{2}=\alpha_{3}=\ldots=0$. This transforms the circle with centre at the origin into an ellipse with a thickness/chord ratio of $(1-k) /(1+k)$. From equation (22) we find

$$
I=\frac{\pi^{2}}{2}
$$

as obtained in section 3.1.
3.5. Drag of Wing Sections Given by General Algebraic Formulae.-Generally, the expression for the shape of an aerofoil in terms of a Fourier series (as in equation (13)) is inadequate because the trailing edge is either cusped or round. For this reason, if a wing section is derived to give a certain pressure distribution and is expressed as a Fourier series the section shape is often modified over the rear part to give a finite trailing-edge angle, and to remove any concave curvature. Once this is done it is not possible to express the drag in such a simple manner as described in equation (14), and the elegance of this method of expression is lost.

Generally, it is possible to fit wing sections to a formula of the type* :-
where

$$
\left.\begin{array}{ll}
\zeta=\zeta_{1}(s) & \left(0 \leqslant s \leqslant s_{0}\right)  \tag{23}\\
\zeta=\zeta_{2}(s) & \left(s_{0} \leqslant s \leqslant 1\right)
\end{array}\right\} \quad \ldots \quad \quad . \quad \ldots \quad . . \quad \ldots \quad \ldots
$$

$$
\zeta_{1}(s)=\sum_{n=0}^{2 m} a_{n} s^{n / 2}
$$

and $\quad \zeta_{2}(s)=\sum_{n=0}^{2 m} b_{n} s^{n / 2}$.

$$
\begin{aligned}
& \text { * For example (Current Paper 683), the N.A.C.A. have published the formula of the NACA } 0012 \text { section in the form } \\
& \qquad \zeta=a_{1} s^{1 / 2}+a_{2} s+a_{4} s^{2}+a_{6} s^{3}+a_{8} s^{4}
\end{aligned}
$$

and the NACA 0012-63 section is given by a formula of the type

$$
\left.\begin{array}{l}
\zeta_{1}=a_{1} s^{1 / 2}+a_{2} s+a_{4} s^{2}+a_{6} s^{3} \\
\zeta_{2}=b_{0}+b_{2} s+b_{4} s^{2}+b_{6} s^{3}
\end{array}\right\} .
$$

Again, the thickness distribution of the Clark Y section has been fitted to equations of the type

$$
\left.\begin{array}{l}
\zeta_{1}=a_{1} s+a_{3} 3^{3 / 2}+a_{5} 5^{5 / 2}+a_{7} s^{7 / 2} \\
\zeta_{2}=b_{0}+b_{2} s+b_{4} s^{2}+b_{6} s^{3}+b_{8} s^{4}
\end{array}\right\}
$$

In particular $a_{0}=0$, and it is usually sufficient to assume that $b_{1}=b_{3}=\ldots=b_{2 m-1}=0$, (i.e., the rear part of the section may be fitted by a polynomial in $s$ ).

If the formula is made up of two different expressions ( $i . e ., s_{0} \neq 1$ ), the expression for $I$ is lengthy and its calculation labourous. However, it may be shown that, if $s_{0}=1$, the expression for $I$ reduces simply to

$$
\begin{align*}
& I=\sum_{p=1}^{2 m} \sum_{q=1}^{2 m} a_{p} a_{q}\left(\frac{2 p}{p+q}\right)\left\{\left[\frac{(-1)^{q}-(-1)^{p}}{2}\right] \ln 2+\sum_{\nu=0}^{[(q-1) / 2]} \frac{1}{q-2 v}\right. \\
& \left.-\sum_{p-0}^{[(p-3) / 2]} \frac{1}{p-2 v-2}\right\} \quad . \quad . \quad . \quad . \quad . \quad . \quad . \tag{24}
\end{align*}
$$

the square brackets denoting the integral part of the upper limits of summation.
In particular, if the $p$ 's and $q$ 's are all even or all odd,

$$
\begin{align*}
I= & 2 \sum_{p=1}^{2 m} \sum_{q=1}^{p-2} a_{p} a_{q}\left[\frac{1}{p}-\frac{p-q}{p+q}\left(\frac{1}{p-2}+\frac{1}{p-4}+\cdots\right.\right. \\
& \left.\left.+\frac{1}{q+2}\right)\right]+\sum_{p=1}^{2 m}\left(\frac{a_{p}^{2}}{p}\right) \quad \ldots  \tag{25}\\
\cdots & \cdots
\end{align*} \ldots \quad \ldots \quad \ldots .
$$

We may apply equation (24) to the calculation of $I$ for the N.A.C.A. uncambered 'fourfigure ' airfoil series, whose profiles are given by the formula :-

$$
\frac{1}{2} \zeta=1 \cdot 484 s^{1 / 2}-0 \cdot 630 s-1 \cdot 758 s^{2}+1 \cdot 421 s^{3}-0 \cdot 508 s^{4}
$$

These sections have a small finite thickness at the trailing edge, but as this is only 1 per cent of the maximum thickness its effect may be neglected. The nose radius of curvature of these sections is $1 \cdot 1 t^{2} / c$, the trailing-edge angle is $2 \cdot 3 t / c$ radians, and the maximum thickness is at 30 per cent chord. The value of $I$ computed from equation (24) is $4 \cdot 47$.
4. Effect of Changes of Profile Shape on Drag.-4.1. Effects of Changes in Nose Radius and Traiting-Edge Angle.-Ideally, it would be useful to be able to state the drag of a wing section in terms of its main geometrical features ; for example, the nose radius of curvature, the chordwise position of the maximum thickness, and the trailing-edge angle.

From the few worked examples of the last sections it will be noticed that sections which have a small radius of curvature and a small trailing-edge angle also tend to have a small drag. In general if a family of sections is described by an equation whose parameters are related to the three geometrical features named above, then this effect is very pronounced.

A simple example will illustrate this : if we choose as the family of profiles those given by the formula

$$
\zeta(s)=\sum_{n=1}^{4} \beta_{n} \sin n \theta+B \sin ^{2} \theta, \quad\left(s=\frac{1-\cos \theta}{2}\right)
$$

the value of $I$ is simply

$$
I=\frac{\pi^{2}}{2} \sum_{n=1}^{4} n \beta_{n}{ }^{2}+8 \pi B\left(\frac{\beta_{1}}{3}-\frac{\beta_{3}}{5}\right)+4 B^{2} .
$$

Accordingly the drag may be quoted in terms of :-
(a) leading-edge radius of curvature
(b) maximum thickness position, and
(c) trailing-edge angle
since the five parameters may be found in terms of these quantities, and the implied conditions that
(d) the section ordinate is known $(\zeta=1)$ at the chordwise position of maximum thickness
(e) the trailing-edge is sharp.

The results are shown in Fig. 6 where the value of (I/4)-which is the drag of the section relative to that of the biconvex profile-is plotted as a function of nose radius for various trailing-edge angles and positions of maximum thickness.

The increase in drag with increase in nose radius and trailing-edge angle is evident from an examination of the figures. But this effect has little significance either quantitatively or qualitatively. For we shall seek to show in the two following sections that :-
(i) an increase in trailing-edge angle leads to a decrease in drag (and under certain conditions so also does an increase in nose radius), if the necessary increase in the section ordinates only affects the shape of the profile over a limited and localised region of the chord (section 4.2) ;
(ii) a change in profile shape leaving the three named geometrical features unaltered, can produce a change in the drag of the same order as the difference in drag we are attempting to find (i.e., the difference in drag between the chosen profile and that of the biconvex section), as shown in section 4.3.
These conclusions mean that the value of nose radius or trailing-edge angle is no guide to the drag of the section per se. The effect on drag of an increase in nose radius or trailing-edge angle will depend upon the way in which this increase modifies the shape of the rest of the section: the modification can-and generally does-produce an increase in drag, but if performed in a certain particular manner it can have the opposite effect.
4.2. Localised Variations of Shape.-To obtain an insight into the effect of localised variations of profile shape, let us assume that we change a profile whose ordinates are given by $\zeta=\zeta(s)$ by adding an infinitesimal increment so that the shape is given by

$$
\zeta=\zeta(s)+\delta(s) .
$$

Then from equation (12),

$$
\left.\begin{array}{rl}
\delta I= & \delta I_{1}+\delta I_{2}=2 \int_{0}^{1} \int_{0}^{1} \delta^{\prime}(\sigma) \zeta^{\prime}(s) \ln \left|\frac{1}{s-\sigma}\right| d s d \sigma  \tag{26}\\
& +\int_{0}^{1} \int_{0}^{1} \delta^{\prime}(\sigma) \delta^{\prime}(s) \ln \left|\frac{1}{s-\sigma}\right| d \delta d s
\end{array}\right\} \ldots \quad \ldots \quad \ldots
$$

which we may express, as in equation (15), in the form

$$
\begin{equation*}
\delta I=-2 \pi\left(\frac{c}{t}\right) \int_{0}^{1} \delta(\sigma)\left[\frac{\Delta p}{q}\right]_{\mathrm{inc}} d \sigma+O\left(\delta^{\prime 2}\right) \quad \ldots \quad \ldots \quad \ldots . \tag{27}
\end{equation*}
$$

where $[\Delta p / q]_{\text {inc }}$ is the linearised incompressible pressure distribution over the undistorted profile.

For the general group of profiles defined by equation (23) the pressure distribution is given by Ref. 3. Near the leading edge of the wing :-

$$
\begin{equation*}
\frac{\Delta p}{q}=a_{2} \ln \frac{1}{\sigma}+C_{1}+O\left(\sigma^{1 / 2}\right) . \quad . . \quad . \quad . \quad \ldots \quad \ldots \tag{28}
\end{equation*}
$$

Similarly near the trailing edge :-

$$
\begin{equation*}
\frac{\Delta p}{q}=\zeta_{2}{ }^{\prime}(1) \ln |1-\sigma|+C_{2}+O(1-\sigma) \ldots \quad \ldots \quad \ldots \quad \ldots \tag{29}
\end{equation*}
$$

where the values of the constants $C_{1}$ and $C_{2}$ are determined by the general shape of the profile, and may be either positive or negative.

It follows from equation (29) that, since $\zeta_{2}{ }^{\prime}(1)$ is negative for sections with a finite trailing-edge angle, $[\Delta p / q]_{\text {inc }}$ is positive near the trailing edge, and therefore from (27) any small increase in the ordinates near the trailing edge will reduce the drag. A change in the ordinates near the leading edge might work one way or the other, as for a round-nose airfoil the coefficient $a_{2}$ in equation (28), which has no simple geometrical significance, could be either positive or negative.
4.3. Variation of the Shape of the RAE 101 Section.-We shall now attempt to justify the fact that the drag can be changed significantly by a change in profile shape which leaves the nose radius and trailing-edge angle unaltered. This conclusion may be justified most easily by an example.

Let us consider a variation of the profile shape of the RAE 101 section. The change in drag due to an increase in the ordinates of the section at $s=\sigma$ of amount $\delta(\sigma)$ is given by equation (26), where the linearised incompressible pressure distribution over the undistorted section is given by ${ }^{2}$

$$
\left.\begin{array}{rlrl}
{\left[\frac{\Delta p}{q}\right]_{\mathrm{inc}}} & =-2 \cdot 957\left(\frac{t}{c}\right) & & \text { for } 0 \leqslant \sigma \leqslant 0 \cdot 3 \\
& =(5 \cdot 707 \sigma-4 \cdot 669)\left(\frac{t}{c}\right), & \text { for } 0 \cdot 3 \leqslant \sigma \leqslant 1 \tag{30}
\end{array}\right\}
$$

A variation which will produce a first-order decrease in $I$ is such that

$$
\begin{aligned}
& \delta(s) \leqslant 0 \text { for } s \leqslant 0 \cdot 8 \\
& \delta(s) \geqslant 0 \text { for } s \geqslant 0.8
\end{aligned}
$$

since $[\Delta p \mid q]_{\text {inc }}=0$ approximately at $0.8 c$. In particular we have

$$
\delta(0)=\delta(1)=0
$$

and we shall assume further that the leading-edge radius of curvature and the position of maximum thickness are left unchanged. Such a modification aft of the maximum thickness, however, is liable to introduce a concave curvature which is undesirable. Accordingly we shall assume

$$
\begin{aligned}
\delta(s) & =-\varepsilon\left[s^{2}(0 \cdot 3-s)\right]^{3 / 2}, & & s \leqslant 0 \cdot 3 \\
& =0, & & s \geqslant 0 \cdot 3 .
\end{aligned}
$$

We then find from equation (26) that

$$
\delta I=-0.0111 \varepsilon+0.0000421 \varepsilon^{2}
$$

If we are to avoid any concave curvature on the nose, $\varepsilon$ must be less than about 35 , so that if we chose $\varepsilon=30$ we are making a 'reasonable ' modification and we obtain a reduction in drag given by $\delta I=-0 \cdot 30$ so that $I=3 \cdot 89$ (i.e., a 7 per cent reduction of the figure quoted in Table 2 for the undistorted RAE 101 profile, bringing it to a value less than that of a biconvex section). The required change in the section ordinates are listed in Table 3 ; the changed shape is shown in Fig. 7 together with the effect on the pressure distribution, which is small.
4.4. Variations for the Shape of the Double-Wedge Section.-We shall now seek to show that the double-wedge section is that which has least drag for a given thickness at half-chord, if regions of concave curvature and discontinuous concave changes in profile slope are precluded.

The linearised incompressible pressure distribution over a double-wedge wing with maximum thickness at half-chord is given by :-

$$
\begin{equation*}
\left[\frac{\Delta p}{q}\right]_{\mathrm{inc}}=\frac{t / c}{\pi} \ln \left[\frac{\left(\frac{1}{2}-\sigma\right)^{2}}{\sigma(1-\sigma)}\right] . \quad . \quad . \quad . \quad . \quad . \quad . \quad . \quad . \tag{31}
\end{equation*}
$$

If we are to obtain any first-order decrease in drag by a small variation of the section shape, it follows from equations (27) and (31) that it is sufficient to increase the thickness near the leading or trailing edges (where the pressure is high) and decrease the thickness near the maximum thickness (where pressure is low). But the thickness cannot anywhere be decreased if the position of maximum thickness is left unaltered, since the curvature must not be concave. Thus the wing ordinates may only be increased.
Suppose that the incremental addition to the wing ordinate at $\sigma=\frac{1}{2} \pm \frac{1}{2 \sqrt{ } 2}$, where $\left[\frac{\Delta p}{q}\right]_{\text {inc }}=0$, is $|\varepsilon|>0$. Then

$$
\int_{\frac{1}{2}-\frac{1}{2} \sqrt{2} 2}^{\frac{1}{2}} \delta(\sigma)\left[-\frac{\Delta p}{q}\right]_{\text {inc }} d \sigma \geqslant \int_{\frac{1}{2}-\frac{1}{2} \sqrt{2} \frac{1}{2}}^{\frac{1}{2}} 2 \sqrt{ } 2|\varepsilon|\left(\frac{1}{2}-\sigma\right)\left[-\frac{\Delta p}{q}\right]_{\text {inc }} d \sigma
$$

and

$$
\int_{0}^{\frac{1}{2}-\frac{1}{2 \sqrt{2}}} \delta(\sigma)\left[+\frac{\Delta p}{q}\right]_{\mathrm{inc}} d \sigma \leqslant \int_{0}^{\frac{1}{2}-\frac{1}{2 \sqrt{2}}} 2 \sqrt{ } 2|\varepsilon|\left(\frac{1}{2}-\sigma\right)\left[+\frac{\Delta p}{q}\right]_{\mathrm{inc}} d \sigma
$$

because of the restriction on surface curvature. Thus

$$
\int_{0}^{1 / 2} \delta(\sigma)\left[\frac{\Delta p}{q}\right]_{\text {inc }} d \sigma \leqslant 2 \sqrt{ } 2|\varepsilon| \int_{0}^{1 / 2}\left(\frac{1}{2}-\sigma\right)\left[\frac{\Delta p}{q}\right]_{\text {inc }} d \sigma=0, \quad \text { from }(31)
$$

By considerations of symmetry, it follows that, in equation (26)

$$
\delta I_{1} \geqslant 0
$$

and since $\delta I_{2}$ is essentially positive

$$
\delta I>0 .
$$

Hence any change of section shape which leaves the maximum thickness and its chordwise position unaltered, and does not introduce concave curvature, increases the drag.

If the maximum thickness position is ahead of the half-chord point, then the double-wedge section is no longer the shape having least drag and some thickening of the wing ahead of the maximum thickness position reduces the drag.
5. Conclusions.-(a) The drag in supersonic flow of an infinite swept wing with edges swept behind the Mach lines, may be expressed as the product of two terms, one a function of Mach number and of sweepback, and the other depending only on the section shape. It follows that the relative drag of two wings of different section is independent of Mach number (see equation (11)).
(b) If the shape of the wing section is given by a formula which is
(i) a Fourier series,
(ii) a conformal transformation of a circle, or (iii) a general algebraic polynomial,
the drag of various sections may be computed in terms of the parameters of the formulæ, as given in equations (14), (22) and (24).
(c) The drag of various sections is proportional to the integral along the chord of the product of the section ordinate and the local value of the excess pressure existing over the profile according to the linearised incompressible-flow theory (see equation (15)).
(d) A wing of elliptic section has the least drag for a given cross-sectional area. It is possible to construct a section which has a drag smaller than any given finite value if only the maximum thickness of the section is fixed. If concave curvature of the surface is inadmissible, the doublewedge wing yields the least drag for a given half-chord thickness.
(e) The drag of infinite swept wings with sections having round noses and sharp trailing-edges is generally between 0 and 15 per cent greater than that of wings with biconvex section. The following figures refer to the relative drag of sections having the same maximum thickness:-

| Ellipse | $1 \cdot 23$ |
| :--- | :--- |
| NACA 0012 series | $1 \cdot 12$ |
| RAE 101 | $1 \cdot 05$ |
| Biconvex | $1 \cdot 00$ |
| Double-wedge (max $t / c$ at $c / 2$ ) | 0.69 |

(f) An increase in nose radius or trailing-edge angle of a section generally leads to an increased drag, but this largely depends upon the manner in which this change affects the shape of the rest of the profile.
(g) It is possible to deduce the change of shape required to reduce the drag of any particular section if its low-speed pressure distribution is given.
(h) The absolute drag of high aspect ratio constant-chord wings is higher than that of the infinite wing with the same sweepback and wing section, but the difference is due to a term which varies inversely as the square of the wing aspect ratio. Thus it is reasonable to suppose that the results quoted above are a guide to the drag of finite wings of moderate aspect ratio (e.g., $A \tan A \geqslant 4$ ) at low supersonic speeds.

## LIST OF SYMBOLS

| $a$ | Radius of circle in $(\eta, \zeta)$-plane |
| ---: | :--- |
| $a_{n}, b_{n}$ | Coefficients of polynominal in $s^{1 / 2}$ representing $\zeta(s)$ |
| $b$ | Semi-span of wing |
| $c$ | Chord of wing (measured in free-stream direction) |
| $h$ | Distance of centre of circle in $(\eta, \zeta)$-plane along real axis from origin |
| $m=$ | $\cot A$ |
| $\Delta p$ | Difference between local and static air pressure |


| $q$ | $\frac{1}{2} \rho U^{2}$ |
| :---: | :---: |
|  | $X / c$ |
| $t$ | Thickness of wing |
| u | Component of air velocity parallel to the $x$-axis |
| w | Component of air velocity parallel to the $z$-axis |
| $x$ ) | System of Cartesian co-ordinates, origin at wing apex, the point |
| $y\}$ | $(c, 0,0)$ being the wing root trailing edge, and the wing being in the |
| $z$ | plane $z=0$ |
| $z(X)$ | Value of $z$ as a function of $X$ on surface of wing section |
| $A$ | Wing aspect ratio ( $=2 b / c$ ) |
| $C_{D}=$ | $D / q S$ |
| D | Wing drag at zero lift |
| $I=$ | $\int_{0}^{1} \int_{0}^{1} \zeta^{\prime}(s) \zeta^{\prime}(\sigma) \ln \left\|\frac{1}{s-\sigma}\right\| d s d \sigma=\left[\frac{\pi\left(1-\mu^{2}\right)^{3 / 2}}{\left(3-\mu^{2}\right)}\right] \frac{D}{q m^{2} t^{2}}$ |
| (I/4) | Drag of section relative to that of biconvex section |
| $M$ | Mach number of speed of wing relative to air |
| $S$ | Wing area ( $=2 b c$ ) |
| U | Free-stream velocity |
| V | Cross-sectional area of wing section $\left(=\int_{0}^{c} z(X) d x\right)$ |
| (dW/dY) | $u$-iw |
| $X=$ | $x-y / m$ |
| $Y$ | $x+i z$ |
| $\mathscr{R}()$ | real part of () |
| $\mathscr{I}()$ | imaginary part of () |
| H | $\xi+i \eta$ |
| $H^{\prime}$ | $H-h$ |
| $\Lambda$ | Angle of sweep of wing leading edge |
| $\alpha$ | Trailing-edge total angle |
| $\alpha_{n}$ | Coefficient of $H^{-n}$ in conformal transformation between $Y$ and $H$ |
| $\alpha_{n}{ }^{*}$ | Real part of $\alpha_{n}$ |
| $\beta_{n}$ | Coefficient of $\sin n \theta$ in Fourier series for $\zeta(s)$ |
| $\delta(s)$ | Incremental change in $\zeta(s)$ |
| $\varepsilon$ | Semi-angle of wedge (except in section 4.4) |
| $\zeta(s)=$ | $2 z(X) / t$ |
| $\zeta^{\prime}(s)$ | $d \zeta / d s$ |
| $(\eta, \zeta)$ | System of co-ordinates in plane of flow about a circle |
| - | $\operatorname{arc} \cos (1-2 s)$ |
| $\mu$ | $m \sqrt{ }\left(M^{2}-1\right)$ |
| $\xi$ | Value of $X$ corresponding to leading edge of source plane considered |
| $\rho$ | Air density |
| e | $\frac{\text { Leadingedede radius of curvature }}{\text { Wing chord }}$ in Fig. 6 |
| $\sigma$ | $\xi / 0$ |
| $\tau=$ | Thickness/chord ratio |
| $\psi$ | Half-depth of streamtube at $x=-\infty$ |
| $\left.F\right\|_{x}$ etc. | Value of the function $F$ with $X$ (a variable) held as constant and arbitrary |

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TABLE 1
Relative Drag of Various Sections

| Section | Formula | Maximum thickness position* | L.E. | T.E. | I |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Ellipse | $\zeta(s)=2[(1-s) s]^{1 / 2}$ | $\frac{1}{2} c$ | Round | Round | $\frac{\pi^{2}}{2}=4.93$ |
| Conventional | $\zeta(s)=\frac{3 \sqrt{ } 3}{2}(1-s)(s)^{1 / 2}$ | $\frac{1}{3} c$ | Round | Angular | $\frac{9}{2}=4 \cdot 50$ |
| Joukowski | $\zeta(s)=\frac{16}{3 \sqrt{ } 3}(1-s)^{3 / 2}(s)^{1 / 2}$ | $\frac{1}{4} c$ | Round | - Cusped | $\frac{4 \pi^{2}}{9}=4.39$ |
| Biconvex | $\zeta(s)=4(1-s) s$ | $\frac{1}{2} c$ | Angular | Angular | $4=4 \cdot 00$ |
| Biconvex cusped | $\zeta(s)=\frac{25}{6} \sqrt{\frac{5}{3}}(1-s)^{3 / 2} s$ | ${ }_{5}^{2} c$ | Angular | Cusped | $\frac{625}{162}=3.86$ |
| Double-cusp | $\zeta(s)=8[(1-s) s]^{3 / 2}$ | $\frac{1}{2} c$ | Cusped | Cusped | $\frac{3 \pi^{2}}{8}=3 \cdot 70$ |
| $\left.\begin{array}{c}\text { Double-wedge } \\ ", " \\ " \quad "\end{array}\right\}$ | Discontinuous | $\left\{\begin{array}{c}\frac{1}{2} c \\ \frac{1}{3} c \\ \frac{1}{4} c\end{array}\right\}$ | Angular | Angular | $\left\{\begin{array}{r} 4 \ln 2=2 \cdot 77 \\ \left(\frac{3}{2} \ln 3+3 \ln \frac{3}{2}\right)=2 \cdot 87 \\ \left(\frac{4}{3} \ln 4+4 \ln \frac{4}{3}\right)=2 \cdot 99 \end{array}\right.$ |
| Flat-sided Double-wedge | Discontinuous | $\left\{\begin{array}{c}0.15 c \\ \text { to } \\ 0.45 c\end{array}\right\}$ | Angular | Angular | $4 \cdot 56$ |

*The drag is unaltered when the sections are reversed (i.e., when $s$ is changed to $-s$ ). It is assumed that profiles with the maximum thickness behind the half-chord are of little interest.

TABLE 2
Drag of RAE 100-104 Sections

| Section | Maximum $t / c$ position <br> per cent chord | $\frac{\text { L.E. radius } \times \text { chord }}{\text { (thickness) }^{2}}$ | $\frac{\text { T.E. angle (radn) }}{(t / c)}$ | $I$ |
| :---: | :---: | :---: | :---: | :---: |
| RAE 100 | $27 \cdot 0$ | $1 \cdot 10$ | $1 \cdot 71$ | $1 \cdot 79$ |
| 101 | $31 \cdot 0$ | $0 \cdot 76$ | $1 \cdot 91$ | $4 \cdot 38$ |
| 102 | $35 \cdot 6$ | $0 \cdot 69$ | $2 \cdot 09$ | $4 \cdot 19$ |
| 103 | 41.9 | $0 \cdot 63$ | $2 \cdot 37$ | $4 \cdot 21$ |
| 104 | 0.59 | $4 \cdot 42$ |  |  |

TABLE 3
Modification to Nose Shape of RAE 101 Section to Effect 7 per cent Reduction in Drag

| $s$ | Ordinates of unmodified section <br> (Maximum thickness $=2$ ) | Ordinates of modified section <br> (Maximum thickness $=2$ ) |
| :---: | :---: | :---: |
| 0 | 0 | 0 |
| 0.005 | $0 \cdot 1741$ | $0 \cdot 1723$ |
| $0 \cdot 01$ | $0 \cdot 2453$ | $0 \cdot 2406$ |
| 0.025 | $0 \cdot 3834$ | $0 \cdot 3663$ |
| 0.05 | $0 \cdot 5319$ | $0 \cdot 4901$ |
| $0 \cdot 1$ | $0 \cdot 7215$ | $0 \cdot 6368$ |
| $0 \cdot 15$ | $0 \cdot 8440$ | $0 \cdot 7428$ |
| $0 \cdot 2$ | $0 \cdot 9261$ | $0 \cdot 8414$ |
| $0 \cdot 25$ | 0.9770 | 0.9351 |
| $0 \cdot 3$ | 0.9994 | 0.9994 |



Fig. 1. Source plane of strength $\varepsilon$ bounded by lines $y=m(x-z)$ and $y=0$.


Fig. 3. Variation of drag with span of wings with biconvex section.


Fig. 2. Symbols for swept wings.


Fig. 4. Variation of drag of infinite swept wing with arbitrary section as a function of Mach number.


Fig. 6. Effect of leading-edge curvature and trailing-edge angle on drag of a family of wings.


Fig. 7. Effect of modification to nose shape of RAE 101 section whereby drag is reduced by 7 per cent.

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[^0]:    * R.A.E. Tech. Note Aero. 2073, received 3rd April, 1951.

[^1]:    * Here ' arg cosh ' denotes the inverse hyperbolic cosine, as in American papers ; later the function 'In' is introduced to denote natural logarithms.

[^2]:    * In the sections which follow we shall use the term 'drag of sections . . ' where we should more correctly write 'drag of an infinite swept wing with sections . . $\therefore$

[^3]:    * The sections were calculated to give a 'roof-top.' pressure distribution by the linear incompressible-flow theory, and the section ordinates are given in Ref. 2.

