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# SOME DETAILS OF THE QUINTIC PROFILE FOR USE IN THE POLHAUSEN-TYPE OF BOUNDARY-LAYER CALCULATION 

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## Summary

The Pohlhausen method for approximate calculation of the laminar boundary layer uses a quartic one-parameter family of velooity profiles. In this paper the general theory is developed for a quintic profile, satisfying an additional boundary condition at the wall. A detailed analysis is given for the case of a linearly retarded mainstream; good agreement is obtained upon comparison with the exact solution.

## 1. Introduction

Since the concept of the boundary layer was first developed by Prandtl more than half a century ago, many exact and approximate solutions of the steady incompressible laminar-boundary-layer equations have been obtained. One of the earliest of the approximate methods of solution was due to Pohlhausen 1 (1921). In this method the boundarylayer equations are not solved everywhere, but nnly at the wall, at the edge of the boundary layer, and on an average by expressing the momentum equation in the integral form due to von Kármán.

For a two-dimensional boundary layer, $x$ is measured along the wall and $y$ perpendicular to it. The velocities in the $x$ and $y$ directions are $u$ and $v$ respectively, $p$ is the pressure $\rho$ the density, $\mu$ the visoosity and $v=\mu / \rho$ the kinematia vincosity of the fluid. At the edge of the boundary layer $u \rightarrow u_{1}(x)$. Then it is well known (Goldstein ${ }^{2}$, 1938) that the momentum integral equation may be written as

$$
\begin{equation*}
\frac{\tau_{0}}{\rho u_{1}^{2}}=\frac{d \delta_{2}}{d x}+\frac{1 d u_{1}}{u_{1} d x}\left(\delta_{1}+2 \delta_{2}\right) \tag{1.1}
\end{equation*}
$$

We express the velocity $u$ in the form

$$
\begin{equation*}
\frac{u}{u_{1}}=f(\eta), \eta=\frac{y}{\delta}, \tag{1.2}
\end{equation*}
$$

where $\delta$ is the boundary layer thickness, assumed. finite. Then in (1.1) the skin-friction $\tau_{0}$, the displacement thickness $\delta_{1}$, and the momentum thickness $\delta_{a}$ are given by


$$
\left.\begin{array}{l}
\frac{\tau_{0}}{\frac{\rho u_{1}^{2}}{}=\frac{v}{u_{1} \delta} f^{\prime}(0)}  \tag{1.3}\\
\frac{\delta_{1}}{\delta}=\int_{0}^{1}(1-f) d \eta \\
\frac{\delta_{2}}{\delta}=\int_{0}^{1} f(1-f) d \eta
\end{array}\right\}
$$

The boundaxy conditions are

$$
f(0)=0, f^{\prime \prime}(0)=-\Lambda, f^{\prime \prime \prime}(0)=0, \ldots \quad \ldots(1.4)
$$

where

$$
\begin{equation*}
\Lambda=\frac{\delta^{2} d u_{1}}{v} \frac{-}{d x} \tag{1.5}
\end{equation*}
$$

and

$$
\begin{equation*}
f(1)=1, f^{\prime}(1)=f^{\prime \prime}(1)=f^{\prime \prime}(1)=\ldots=0 . \tag{1.6}
\end{equation*}
$$

The idea used by Polhausen is to approximate to $f$ as a polynomial in $\eta$, and to satisfy as many of the boundary conditions, (1.4) and (1.6), as possible. In particular, Pohlhausen considered the case of a quartic satisfying the first two conditions (1.4) and the first three conditions (1.6). In this paper we shall consider the case of a quintic, whlch satisfies in addition the third condition of (1.4). Upon satisfying all these conditions we find that

$$
\begin{equation*}
f(\eta)=\frac{1}{2} \eta\left(5-5 \eta^{3}+3 \eta^{4}\right)+\frac{2}{4} \Lambda \eta(1+\eta)(1-\eta)^{3} . \tag{1.7}
\end{equation*}
$$

Upon substitution anto (1.1) and (1.3) a first-order differential equation results for $Z=\frac{\delta^{2}}{\nu}=\frac{\Lambda}{u_{1}^{\prime}}$, taking the form

$$
\begin{equation*}
z^{\prime}=\frac{g(\Lambda)}{u_{1}}+z^{2} u_{1}^{\prime \prime} h(\Lambda) \tag{1.8}
\end{equation*}
$$

which may also be written as an equation for $\Lambda$,

$$
\begin{equation*}
\Lambda^{\prime}=g(\Lambda) \frac{u_{1}^{\prime}}{u_{1}}+\left\{\Lambda+\Lambda^{2} h(\Lambda)\right\} \frac{u_{1}^{\prime \prime}}{u_{1}^{\prime}} \tag{1.9}
\end{equation*}
$$

In this paper the general theory is worked out, and the universal functions, $g(\Lambda)$ and $h(\Lambda)$, tabulated for the case of a quintic velocity profile. A detailed solution is then obtained for the case of a linearly retarded mainstream velocity. It is found that the predicted displacement and momentum thicknesses, the skin-friction and the separation position, are nowhere in error by more than $6 \%$ when compared with the exact solution of Howarth3 (1938).

## 2. General Theory for a Quintic Velocity Distribution

The assumed velocity profile in the boundary layer is

$$
\frac{u}{u_{1}}=f(\eta)=\frac{1}{3} \eta\left(5-5 \eta^{3}+3 \eta^{4}\right)+\frac{1}{4} \Lambda \eta(1+\eta)(1-\eta)^{3}, \quad \ldots(2.1)
$$

satisfying the boundary conditions

$$
\left.\begin{array}{l}
f(1)=1, f^{\prime}(1)=f^{\prime \prime}(1)=0 \\
f(0)=0, f^{\prime \prime}(0)=-\Lambda, f^{\prime \prime \prime}(0)=0
\end{array}\right\}
$$

Then upon substitution from (2.1) into (1.3), the skin friction, the displacement thickness and the momentum thickness are given, after integration by

$$
\left.\begin{array}{rl}
\frac{\tau_{0}}{\rho u_{1}{ }^{2}} & =\frac{\nu}{u_{1} \delta}\left\{\frac{5}{-1}+\frac{1}{3} \Lambda_{4}\right.
\end{array}\right\}, \ldots(2.3)
$$

It follows from (2.3) that separation takes place when

$$
\begin{equation*}
\Lambda=\Lambda_{s}=-\frac{20}{3} \tag{2.6}
\end{equation*}
$$

Upon substitution for $\tau_{0}, \delta_{1}, \delta_{2}$ from (2.3) to (2.5) into the momentum integral equation (1.1), a first-order linear differential equation for $\Lambda$ results. This is

$$
\begin{gather*}
-4- \\
\Lambda^{\prime}=g(\Lambda) \frac{u_{1}^{\prime}}{u_{1}}+\left\{\Lambda+\Lambda^{2} h(\Lambda)\right\} \frac{u_{1}^{\prime \prime}}{u_{1}^{\prime}}, \tag{2.7}
\end{gather*}
$$

where primes note differentiation whth respect to $x$, and the universal functions $g(\Lambda), h(\Lambda)$ are given by

$$
\begin{align*}
& g(\Lambda)=\frac{4}{5} \cdot \frac{831600-165580 \Lambda+9816 \Lambda^{2}+423 \Lambda^{3}}{(20-3 \Lambda)(1240+141 \Lambda)},  \tag{2.8}\\
& h(\Lambda)=\frac{12}{5} \frac{250+141 \Lambda}{(20-3 \Lambda)(1240+141 \Lambda)} . \tag{2.9}
\end{align*}
$$

The equation may alternatively be expressed as an equation in

$$
Z=\frac{\delta^{2}}{\nu}=\frac{\Lambda}{u_{1}^{\prime}},
$$

namely

$$
\begin{equation*}
z^{:}=\frac{g(\Lambda)}{u_{1}}+z^{2} u_{1}^{\prime \prime} h(\Lambda) . \tag{2.11}
\end{equation*}
$$

The functions $g(\Lambda), h(\Lambda)$ and $\Lambda+\Lambda^{2} h(\Lambda)$ are tabulated in Table I.
Now, as is true in the quartio case, since $u_{1}$ vanishes at the forward stagnation point of the flow past a cylindrical obstacle, it follows that $g(\Lambda)$ must be zero there if $Z$ is to reman finite. But the only zero of $g(\Lambda)$ occurs at $\Lambda=-35.7$, which is not a permissible value, sunce by (2.3) j.t corresponds to a negative skin friction. It follows that the fiuw near a stagnation point cannot be dealt with by this method, in much the same way as the ordinary Pohlhausen method cannot be used in certain problems for which $\Lambda$ becomes too large. In problems in which the velocity increases away from a stagnation point, and decreases after the point of minimum pressure, the classical Pohlhausen quartic must be used at least in the region of accelerated flow.

## 3. The Boundary Layer with a Linearly Retarded Mainstream

In certain simple cases equation (2.7) simplifies sufficiently to be solved by direct integration. For example, if the main-stream velocity may be expressed as

$$
\begin{equation*}
u_{1}(x)=u_{0}\left(1-\frac{x}{c}\right)^{n} \tag{3,1}
\end{equation*}
$$

then

$$
\begin{equation*}
\frac{u_{1}^{\prime \prime}}{u_{1}^{\prime}}=\left(1-\frac{1}{n}\right) \frac{u_{1}^{\prime}}{u_{1}} \tag{3.2}
\end{equation*}
$$

and so (2.7) becomes sumply

$$
\begin{equation*}
\Lambda^{\prime}=\frac{u_{1}}{u_{1}}\left\{g(\Lambda)+\left(1-\frac{1}{n}\right)\left[\Lambda+\Lambda^{2} h(\Lambda)\right]\right\} \tag{3.3}
\end{equation*}
$$

This equation may be integrated directly to give

$$
u_{1}(x)=u_{0} \exp \left\{\int_{0}^{\Lambda} \frac{d \Lambda}{g(\Lambda)+\left(1-\frac{1}{n}\right)\left[\Lambda+\Lambda^{2} h(\Lambda)\right]}\right\}, \ldots(3.4)
$$

and the complete solution for the boundary layer is easily obtained.
The simplest example is that of the linearly retarded mainstream, for which $n=1$. This will be considered in some detall, as the exact solution is well known. With $n=1$, and therefore
$u_{1}=u_{0}\left(1-\frac{x}{c}\right)$, equation (3.4) becomes

$$
\begin{equation*}
\frac{x}{c}=1-\exp \left\{\int_{0}^{\Lambda} \frac{d \Lambda}{g(\Lambda)}\right\} . \tag{3.5}
\end{equation*}
$$

The relevant integrations have been carried out, and the results for $\boldsymbol{T}_{0}$ are shown in Table 2. We note that $\tau_{0}$ as $3 \%$ low at $x / c=0$, and the error increases with $x / c$ until it reaches a mexamum of $6 \%$ at about $x / c=0.076$. The error then decreases, until at about $x / c=0.11$ the skin friction is predicted correctly. When $x / c>0.11$ the predicted skin friction is too great, and the distance to separation $X_{s}=0.127 \mathrm{c}$ is too great by $6 \%$. - It courd equally be shown that the predictod $\delta_{1}$ is fairly uniformly about $1 \%$ high and $\delta_{2}$ about $3 \%$ low. The accuracy is therefore most satisfactory.

## References

| No. | Author(s) | Patle, etc. |
| :---: | :---: | :---: |
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| 2 | S. Goldstein (Ed.) | Modern Developments in Fluid Dynamıcs. Vol. 1. O.U.P. (1938). |
| 3 | L. Howarth | On the Solution of the Laminar Boundary Layer Equations. Proc. Roy. Soc. A, 164. p. 542. (1938). |

TABLE 1
The Functions $g(\Lambda), h(\Lambda), \Lambda+\Lambda^{2} h(\Lambda)$

| $3 \Lambda$ | $g(\Lambda)$ | $h(\Lambda)$ | $\Lambda+\Lambda^{2} \mathrm{~h}(\Lambda)$ |
| :---: | :---: | :---: | :---: |
| -20 | 149.76 | $-0.1380$ | -12.800 |
| -19 | 128.07 | -0.1140 | -10.907 |
| -18 | 111.52 | -0.0955 | -9.439 |
| -17 | 98.46 | -0.0808 | -8.260 |
| -16 | 87.88 | -0.0686 | -7.284 |
| -15 | 79.13 | -0.0583 | -6.458 |
| -14 | 71.76 | -0.0495 | -5.744 |
| -13 | 65.48 | -0.04 17 | -5.117 |
| -12 | 60.06 | -0.034 8 | -4.557 |
| -11 | 55.32 | -0.0286 | -4.051 |
| -10 | 51.15 | -0.0228 | -3.587 |
| -9 | 47.45 | -0.0175 | -3.158 |
| -8 | 44.14 | -0.0125 | -2.756 |
| -7 | 41.18 | -0.0077 | -2.375 |
| -6 | 38.50 | -0.0031 | -2.012 |
| -5 | 36.07 | 0.0014 | -1.663 |
| -4 | 33.87 | 0.0059 | -1.323 |
| -3 | 31.86 | 0.0103 | -0.990 |
| -2 | 30.03 | 0.0149 | -0.660 |
| -1 | 28.35 | 0.0194 | -0.331 |
| 0 | 26.83 | 0.0242 | 0 |
| 1 | 25.44 | 0.0292 | 0.337 |
| 2 | 24.18 | 0.0344 | 0.682 |
| 3 | 23.04 | 0.0400 | 1. 040 |
| 4 | 22.03 | 0.0460 | 1.415 |
| 5 | 21.15 | 0.0526 | 1.813 |
| 6 | 20.39 | 0.0599 | 2.240 |
| 7 | 19.77 | 0.0681 | 2.704 |
| 8 | 19.30 | 0.0775 | 3.190 |
| 9 | 18.93 | 0.0883 | 3.795 |
| 10 | 18.92 | 0.1011 | 4.456 |
| 11 | 19.09 | $0.1164_{4}$ | 5.232 |
| 12 | 19.59 | 0.1354 | 6.166 |
| 13 | 20.55 | 0.1595 | 7.328 |
| 14 | 22.17 | 0.1914 | 8.834 |
| 15 | 24.84 | 0.2357 | 10.892 |
| 16 | 29.31 | 0.3018 | 13.918 |
| 17 | 37.34 | 0.4116 | 18.883 |
| 18 | 54.24 | 0.6305 | 28.698 |
| 19 | 106.56 | 1.2861 | 57.919 |
| 20 | $\infty$ | $\infty$ | $\infty$ |

TABLE 2
Comparisons with Howarth's Results

|  | $v^{\frac{1}{2}}\left(\frac{\partial u}{\partial y}\right)_{0}$ |  |
| :---: | :---: | :---: |
| $x / c$ | $-\ldots\left(-u_{1}\right)^{\frac{1}{2}}$ |  |
|  | $u_{1}$ |  |
|  | Curle | Howarth |
| 0.0232 | 1.837 | 1.884 |
| 0.0435 | 1.155 | 1.203 |
| 0.0610 | 0.825 | 0.866 |
| 0.0761 | 0.612 | 0.648 |
| 0.0890 | 0.456 | 0.484 |
| 0.0999 | 0.333 | 0.346 |
| 0.1090 | 0.231 | 0.231 |

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