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# The Interpretation of Strain Measurements for Flight Load Determination

by

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### THE INTERPRETATION OF STRAIN MEASUREMENTS FOR FLIGHT LOAD DETERMINATION

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### SUMMARY

The procedures of N.A.C.A. Report No.1178 for the interpretation of measured flight strains as structural loads are not entirely satisfactory for applications to delta or slender-body configurations. Problems arise from the severe non-linearities in the gauge response with the position of the calibrating load and from the need to support the aircraft representatively during the ground calibrations. These difficulties are overcome if distributed load data, obtained either directly or by superposition, are used in place of individual load data. In contrast to the criginal N.A.C.A. Report, the procedure will then establish directly the reliability of any particular flight load measurement. The modified technique is illustrated by an application to the Lightning fin in laboratory tests.

Replaces R.A.E. Tech. Note No. Structures 363 - ARC 26659

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### 1 INTRODUCTION

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Flight load measurements on military and civil aircraft in the interests of safety and structural efficiency have been standard practice in the U.S.A. for many years and it has been usual to deduce the net flight loads from structural strain measurements. Similar strain measurements have also been made on many British aircraft but their interpretation as flight loads has not been based on a statistical method commonly used in America. This method<sup>1</sup>, developed by Skopinski et al of the N.A.C.A. in the late 1940's, permits the rapid processing of the flight data. With the possibility that flight load measurement may become an essential part of the clearance procedure for British aircraft it was thought worthwhile to review the American technique. It was apparent that the method of N.A.C.A. Report No.1178, herein referred to as the N.A.C.A. method but not implied to be the current N.A.S.A. method, was satisfactory for the medium and high-aspect ratio aircraft for which it was developed but it had some deficiencies when applied to modern low-aspect ratio aircraft.

The N.A.C.A. method is based on the fact that, although the stress in a structural member is not necessarily a simple function of the three loading parameters, M the bending mement, V the shear and T the torque, it is often possible to combine the responses of selected strain gauges to provide a measure of each parameter. The selected gauges and their combination coefficients are chosen by statistical methods from a sample comprised of the gauge responses due to the successive application of a single load at various points on the structure. The appraisal of the N.A.C.A. technique for applications to some current and future aircraft showed that difficulties could arise from:

(a) The need to support the aircraft during the application of each calibration load. The choice of support position influences the stress distributions and hence also the gauge responses induced by the load. The satisfactory application of a statistical treatment requires that the sample data should be consistent with flight conditions and it is essential that the ground calibration load should produce the same gauge responses as those due to a flight load of the same magnitude acting at the same position. It is relatively easy to satisfy these conditions on an aircraft with high-aspect ratio wings and long fuselage, but the choice of supports for the delta and slender body configurations presents many difficulties because of the integrated wing and fuselage construction.

(b) The multiplicity of the load paths which result from the more redundant structure. With such designs the internal loads are not completely diffused into the structure for some distance from the applied external load. Thus, although the gauge response is directly proportional to the magnitude of the load, the responses are not linearly related to the chordwise or spanwise positions of a load of constant magnitude. These non-linearities are important because they influence the accuracy with which a combination of gauges can be fitted to the calibration data. If the external flight loads in the vicinity of the gauges make small contributions to the total external load, as in the case of a high-aspect ratio wing, then the poor diffusion of the local loads is comparatively unimportant. However the preponderance of non-linear responses in a multi-spar structure of low-aspect ratio, (see Figs.3 and 4) from the individual calibration loads adversely affects the confidence in an estimate by the combination of gauges.

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It can be shown that both these difficulties are overcome by changing from a statistical sample based on individual loads<sup>1</sup> to a sample based on distributed loads more representative of those which occur in flight. Furthermore this latter sample gives the statistical data necessary for assessing the accuracy of any particular load measurement in flight.

This Note discusses these problems and then illustrates the proposed procedure by an application to a Lightning fin on which laboratory tests were conducted at the R.A.E.

### 2 COMMENTS ON THE N.A.C.A. METHOD

The statistical approach adopted by the N.A.C.A. was a valuable contribution to solving the problem of the interpretation of flight strain measurements. The alternative method of comparing the measured strains with either those estimated by calculations or those measured by similar gauges at similar positions on the strength test specimen introduce errors arising from differences in material characteristics and dimensions of the two structures and from variations in strain gauge sensitivities. Furthermore, in many practical cases the stressing or test information will not be for the appropriate flight conditions.

To overcome these difficulties, Skopinski et al<sup>1</sup> used standard statistical methods to interpret the responses of selected gauges attached across a section of wing or tailplane as net bending moments, shears and torques at that section. They make use of calibrations of the gauge installations in which individual loads are applied successively at a number of stations on the structure. The gauges are usually installed to measure the shear and bending strains in the spars and these quantities are dependent on the position of the calibration load in a simple or complex manner according to the detail design of the structure.

It is now postulated that the responses  $\mu_1$ ,  $\mu_2$ , ... of the gauges  $G_1$ ,  $G_2$ , ... at different locations on the section can be combined such that, for example,

$$M = \beta_{11} \mu_1 + \beta_{12} \mu_2 + \beta_{13} \mu_3 \tag{1}$$

where  $\beta_{11}$ ,  $\beta_{12}$ ,  $\beta_{13}$  etc are constants to be obtained from the calibration data.

In general the gauges  $G_1, G_2$  ... are attached to the more important load paths at the section and the individual load calibrations must be sufficiently extensive to represent the constituents of the flight distributions. Thus it can be expected that there will be more than sufficient equations to solve for the constants  $\beta_{11}$ ,  $\beta_{12}$  etc and these quantities are then determined by a least squares procedure as described in the Appendix.

This procedure of fitting an expression of the type shown in equation (1) is included in regression analysis<sup>2</sup> commonly used in statistics. The form used

in this application is called a linear regression and there are standard computer programmes for calculating the coefficients of the regression and its standard error.

In many applications it is found that some gauges have very similar responses and consequently the accuracy of prediction can be improved by the elimination of the "redundant" gauges. It is also possible for the contributions,  $\beta \mu$ , of particular gauges to be small and the loss of accuracy is negligible when these "irrelevant" gauges are omitted from the regression, Thus it can be expected that the final regressions for each loading parameter will utilise different gauges. It must be appreciated that the standard error only reflects the probable accuracy of the regression in predicting a particular calibration load of the sample from its associated gauge responses. It can be expected, from small sample theory, that about 2 out of 3 of the calibration loads will be estimated within ± the standard error and there is a 99% probability that the estimate will be within ± 3 times the standard error. Any justification for the application of this regression to distributed loadings must be sought from an application of the principle of superposition. However the necessary conditions of linearity and elasticity will be satisfied by most modern structures in the practical range of flight loads. The gauge responses from the distributed loadings are therefore the algebraic sums of the responses from the constituent loads, each of which can be estimated by the regression. Thus the statistical sample must be representative of all the constituent loads that can produce responses from the gauges. It is necessary therefore to include loads inboard of the measuring section because the gauges respond to the self-equilibrating systems of loads generated by the inboard loads. However these responses must be associated with zero inputs of M, V and T because the regressions are chosen to estimate M, V and T due to the loads outboard of the section. Under these conditions the standard error, expressed as a percentage, loses much of its significance as an indication of the accuracy obtainable from the regression. The N.A.C.A. Report did not use the standard error other than for the selection of the gauges, and the accuracy in the general application was implied by the satisfactory prediction, i.e. within ±5%, of one or more distributed loadings which were applied to the tailplanes in the two quoted examples.

It might be concluded from the above considerations that the N.A.C.A. method caters automatically for distributed loadings over a limitless range of centres of pressure. Certainly the regressions are the same regardless of the sign of the loads, but the probable accuracies of their predictions would vary for each distribution and their establishment in any particular case would present many formidable problems.

The N.A.C.A. procedure also recommended the electrical combination of gauge stations prior to the fitting of the regression. This has the advantage of reducing the number of recording channels and the subsequent processing of the flight data; but its adoption increases the number of gauge installations because a particular gauge station can be used only in the electrical circuit appropriate to one of the three parameters. The combining of selected gauges reduces the possibility of redundant gauges and the non-linearities in the data sample because the higher-than-average response of one gauge is balanced by the corresponding lower-than-average response(s) of the other gaugo(s) to the same calibration load.

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### 3 CHOICE OF SUPPORTS DURING THE CALIBRATION

It is implicit in the statistical treatment of the N.A.C.A. method that the calibration load should produce the same responses at the gauge stations as those due to a flight load of the same magnitude acting at the same positions. Thus if the sample is comprised of individual loads it is essential that the supports for the calibrations should not influence the stress distributions at the gauges. This is easy to specify but difficult to obtain in practice because there are a very limited number of strengthened positions for ground supports and their provision is not dictated by the flight condition. Although the number of potential support positions, such as undercarriages, jacking points etc, is about the same for the delta and slender body configurations as for the older high-aspect ratio aircraft, owing to the more compact layout and structural design a larger proportion of the structure will be affected by the diffusion of concentrated loads reacted at these points.

In general it is desirable to estimate the critical loads as accurately as possible rather than all flight loads at a lower accuracy. This is best effected by using regressions fitted to distributed load samples, each of which caters for a range of uncertainty in the expected flight distribution. The direct application of distributed loads which are representative of a flight condition overcomes the problem of supports. However the acquisition of the sample data would be most expensive because the different distributions must include all those investigated in flight and their number must exceed the number of gauges in the regression. Thus for practical and economic reasons it seems essential to retain the convenience of the individual load calibrations and to assemble the distributed load data by superposition. The calibrations provide the responses  $\mu_{rs}$  of each gauge  $G_s$  for unit load at  $x_r, y_r$ . Then for any system of loads  $P_r$  at  $x_r, y_r$ , total response of

$$G_{s} = \sum_{r=1}^{r=n} P_{r} \mu_{rs}$$

is independent of the support positions if

$$\sum_{r=1}^{n} P_{r} = 0$$

and the other conditions of equilibrium are satisfied.

These conditions are automatically satisfied by the aerodynamic and inertial loads in the flight condition and consequently the responses of the gauges for the sample can be evaluated from the expected flight loads and the individual load calibrations obtained under any arbitrary support condition. This implies that the calibration must be very comprehensive. However in any practical application there will be supports which can reduce the extent of the calibration. Their availability will depend on the particular structure and the scope of the flight investigations. As one is concerned with the interpretation of total responses the criterion for the inclusion of any particular calibration is the relative contribution made to the total response. Thus it becomes unnecessary to calibrate for loads in areas where either the expected local flight load is small or the gauge responses under the particular conditions of support are expected to be small.

### 4 PROPOSED METHOD USING DISTRIBUTED LOAD DATA

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A change from an individual load sample to a distributed load sample for the statistics automatically reduces the non-linearities in the data. The higher-than-average response(s) of a particular gauge to some load(s) is balanced by the lower-than-average responses of the same gauge to loads at different positions and the regressions fitted to such data will have smaller standard errors. If the distributed load sample is typical of the distributions to be measured in flight the standard error can be used directly to assess the reliability of any subsequent estimation by the regression. One obvious criterion of the typicality of the sample is whether the centre of pressure of the measured loads falls within the range of the sample. Any extrapolation to higher stress levels than those induced by the individual load calibrations would be justified by test or other technical knowledge.

The following section illustrates the N.A.C.A. and proposed methods by an application to the Lightning fin. It is acknowledged that the choice of support presented no difficulties in the laboratory experiment but the "non-linearities" encountered in a low-aspect ratio multi-spar construction were present.

### 5 APPLICATION OF METHODS TO A LIGHTNING FIN

### 5.1 Description of specimen and strain gauge installations

The fin was a 5 spar structure (Figs.1 and 2); the spars were mounted vertically from fuselage frames and ribs ran horizontally between the front and rear shear walls which completed the main structure. A leading edge structure, of 16 S.W.G. skin and ribs normal to the front shear wall, was attached to the front shear wall. The main skin was 12 S.W.G.

For the laboratory programme the fin was bolted to a rear fuselage specimen in order to ensure a representative mounting. The fin and fuselage were rotated through 90° to ease the task of loading.

British Thermostat SE/A/2 200  $\Omega$  strain gauges were bonded with Araldite strain gauge cement at a section outboard of rib 1. Calibration loads of 1000 lb were applied in increments at each of the stations shown in Fig.2. The gauges were arranged to respond either to shear or to bending strains in the spars and the responses of the half-bridge installations were recorded by the R.A.E. Strain Recorder. The accuracies of measurement are estimated to be within ±1 digit (1000 digits = 0.5%  $\Delta$ R/R) for the electrical strains and within ±10 lb for the loads. It may be noticed in the subsequent tables

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that the **electrical** strains are given in fractions of a digit, this arizes from the use of a Deuce Programme to provide the electrical strain for a nominal load of 1000 lb at each loading point from the slope of gauge response against load obtained by a least squares method.

### 5.2 Experimental results

Table 1 lists the responses, in digits, of the gauges at the section for 1000 lb load applied separately at each of the calibration points identified in Fig.2. Zero inputs (i.e. M = V = T = 0) indicate that the load was applied inboard of the section.

Table 2 lists the responses of the same gauges obtained by superposition of selected data from Table 1. The combinations of the individual loads used to obtain the "distributed load" responses are also given in Table 2. The inputs, M, V and T, given in the table were calculated from the individual loads outboard of the section and the resultant centres of pressure of these loads lie within the shaded area shown in Fig.2. The responses and inputs were scaled to V = 1000 lb.

Table 3 lists the gauge responses obtained by the superposition of the individual loads shown in Table 4 and a comparison is made with the mean responses obtained from two direct applications of the same distribution.

### 5.3 Regressions for the determination of M, V, and T

### 5.3.1 Individual load calibration method

The non-linear gauge responses with the position of the load are illustrated in Figs. 3 and 4. The responses of A, a conventional shear gauge arrangement on Spar 5, are plotted as influence coefficients for a load of 1000 lb applied at each point. Similarly the responses of A<sub>2</sub>, a "bending gauge" on the same spar, are plotted in Fig.4, but in this case the response is due to a single load which has been scaled to produce a bending moment of  $10^5$  lb in at Section XX. The figures show the higher-than-average responses for bending moments and shears induced by loads adjacent to the gauge station and demonstrate, at least for multi-spar construction of low-aspect ratio, the futility of attempting to deduce an accurate estimate of unknown loads from a single gauge calibrated by a single load. Thus it is necessary to follow the N.A.C.A. procedure and combine several gauges in order that the higher-than-average responses of one gauge are balanced by the lower-than-average responses of other gauges to the same calibration loads. The selection of the appropriate gauges from the mass of calibration data in Table 1 presents many difficulties and an attempt was made to sort the gauges by fitting linear surfaces to the individual responses of each gauge. Thus typically

> response of  $A_7 = 19 + 0.35x + 0.43y$ response of  $A_5 = 6.3 + 0.85x + 0.01y$

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where x and y are the distances from the reference axes in Fig.2. In each expression the sensitivities of the gauge to shear, bending moment and torque are indicated by the constant, x coefficient and y coefficient respectively. Redundant gauges tend to have linearly related coefficients and to select gauges for a shear regression it is preferable to use gauges which tend to have, in combination, net zero coefficients of x and y. However little success was obtained and this was attributed to the poor fits obtained by the linear surfaces. To select possible combinations by fitting quadratic surfaces to the responses of each gauge is a most laborious task.

It was decided therefore to adopt the alternative procedure of fitting a regression containing a large number of the gauges to the data and to discard successively those gauges shown to be either irrelevant or redundant. A Mercury computer programme provided the information for this purpose and a typical product of the computation is shown in the Appendix.

Table 5 summarises the regressions obtained for the estimation of the bending moment (M) at Section XX and the regression coefficients based on individual load calibrations are given in column (b). Thus

	$M \times 10^{-3}$	11	0•958A <sub>8</sub> -	0·037D <sub>7</sub> +	0•001B <sub>2</sub> -	0•072A <sub>9</sub>	+ 0.002D6	+	0·0828 <sub>4</sub>
or		1	0•961A <sub>8</sub> -	0•037D7	-	0.072A9	+ 0.002D6	+	0.082B
or		11	0•982A <sub>8</sub> -	0•037D7	-	0•074A <sub>9</sub>		+	0.050B
or		=	-	0•398D 7		0.006A9	+ 0.608D	÷	0•468a <sub>5</sub>
or		H	0•998A <sub>8</sub> -	0•029D7	-	0•077A <sub>9</sub>		+	0·011A <sub>5</sub>

etc.

Each of these regressions was used to estimate the distributed load detailed in Table 4 and the contributions made by each gauge are listed in column (e) of Table 5. The percentage error of the prediction is compared with the percentage standard error of the regression. Similarly Tables 6 and 7 summarise the regressions for the estimation of shear and torque. Many of these regressions use the bending moment (M) as one of the independent variables and this is justified only if the estimation of M is well established by its own regression.

Incidentally, in each of the regressions for M, V and T the responses have been scaled to unit values of bending moment, shear and torque respectively for the outboard loads. This was done to allow the standard error to be expressed as a percentage rather than an absolute quantity. Such a procedure has more relevance for the regressions based on distributed loads; the difficulty for those based on individual loads arises from the lack of significance of the standard error as an indicator of the probable accuracy when the regression is used to forecast a distributed load. The best agreements between known and estimated distributed loadings in Tables 5, 6 and 7, i.e. within 1% for bending moment, 4.2% for shear and 1.5% for torque, are better than would be expected from the quoted standard errors and could be fortuitous. The performance of the regression  $A_8 A_9 D_7 B_4$  in predicting the bending moment from the responses in Table 2, indicated a standard error of 5.8% which compares favourably with the 3.2% obtained directly from the data. Its evaluation involved additional computation and it would seem more logical to use the data in Table 2 directly as in Section 5.3.2.

No attempt was made to use the technique of partial combination as discussed and applied in the N.A.C.A. Report. This technique has practical disadvantages and does not overcome the difficulties of establishing the reliability of a forecast of a distributed load by a regression based on individual load data.

### 5.3.2 Distributed load calibration method

The data for the distributed load sample are given in Table 2 and were obtained by superposition from the data in Table 1. The justification for this procedure was based on the knowledge that the structural components would not buckle at the stress levels used for the subsequent loading shown in Table 3. A check of the gauge responses for that particular loading and those obtained by superposition is included in Table 3 and agreement within  $\pm 2\%$  was obtained except for the lower responses where reading accuracy was significant.

The inspection of Table 2 shows that the non-linearities in the response data were reduced - partly as a result of combining high and low responses and partly as a consequence of restricting the range of o.p. position. The coefficients of the regressions fitted to these data are given in columns (c) ef Tables 5, 6 and 7, and in columns (f) are the contributions made by the selected gauges ef each regression in the estimation of the directly applied distributed loading. The accuracy of the estimates varied for the different regressions and it was not always the case that the regressions with the smallest standard error predicted this particular distribution with the highest accuracy. However there were regressions which, 2 times out of 3, would predict any one of the statistical sample to within  $\pm 1.5\%$  for shear, (regression  $A_7, A_9, B_2, C_5, D_1, D_6, M)$ , within  $\pm 3\%$  for bending moment ( $A_8, A_9, B_4, D_6, D_7$ ) and  $\pm 2\%$  for torque ( $A_7, A_9, B_2, C_5, D_2, D_6$  M). For higher levels of confidence, say 99 times out of 100, these accuracies would be worsened to  $\pm 4.5\%, \pm 9\%$  and  $\pm 6\%$  respectively.

### 5.4 Influence of the sample size

The extent of the individual load calibrations must be governed to some degree by the redundancy of the structure and, in either method, must allow a satisfactory synthesis of the expected flight loadings. In the case of the N.A.C.A. method the synthesis is made subsequent to the regression analysis and consequently there is little scope for any reduction in the size of the

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matrix. For the modified method there is a lower limit in the number of distributions to be used; there must be at least as many independent calibration data as there are gauge stations in the regression and it is advisable to have an excess in order to prevent ill-conditioning.

To illustrate the influence of sample size Table 8 lists in columns (b) and (c) the coefficients of regressions using the same gauges for samples of 29 and 10 distributed load data - the latter sample comprised the distributions marked with an asterisk in Table 2. It will be noted that the regression coefficients differ for the two samples but the standard errors for shear and bending moment are satisfactorily small. In the case of the torque regression there was an indication of redundancy and the omission of gauge  $A_{o}$  improved

the fit and the standard error. These standard errors indicate how each regression fits its own sample and it is more realistic to compare the accuracies of the two regressions for the same sample; i.e. the standard errors have been calculated for the applications of the 10 member regressions to the estimation of the 29 member sample. On this basis of comparison, the accuracy changed from 1.4% to 4.1% for shear, from 2.9% to 3.9% for bending moment and from 2.1% to 10% for torque when the sample size was changed from 29 to 10 distributions.

It should be appreciated that the statistical procedure does not lead automatically to the "best solution"; at any stage a decision can be made that the probable accuracy is adequate for the intended purpose but confidence in any estimate must depend on initial assumptions such as the extent of the calibration as well as on statistical theory.

### 6 <u>CONCLUSIONS</u>

A review of the N.A.C.A. technique for flight load measurement has shown that its application to future aircraft may not be entirely straightforward. The difficulties arise from the non-linearities in the strain gauge responses to the individual calibration loads and from the need to support the aircraft during their application. The former can be severe if the design incorporates multi-spar construction of low-aspect ratio and the choice of supports for delta and slender-body configurations may not be obvious or practical to fulfil the condition that the individual loads of the ground calibration must be reacted in a manner similar to that of the flight condition.

It is shown that the problem of the supports can be overcome by determining the combinations of gauge responses, which interpret the flight measurements, from a sample of the gauge responses to distributed loads instead of to individual loads as recommended in N.A.C.A. Report No.1178. It is necessary in the general case for the distributed load systems to be in equilibrium. The statistical method of analysing flight strains requires a large number of calibrations and it is suggested that these can be obtained by the superposition of individual load data instead of the direct application of distributed loads. This procedure would retain the convenience of individual load calibration and under certain conditions need not satisfy the general requirement that the distribution of loads should be in equilibrium.

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The change to a sample of distributed load data automatically reduces the non-linearities in the gauge responses and consequently acceptable standard errors for the combinations of gauge responses should be obtained for multi-spar structures of low-aspect ratio. Furthermore, in contrast to the N.A.C.A. procedure, these standard errors can be used directly to assess the reliability of a particular load measurement and this is important if the measured flight load is to be used for the structural clearance of the aircraft.

Laboratory tests on a Lightning fin, which admittedly did not introduce any difficulties of supporting the structure representatively, showed that the modified method interpreted the strain measurements at a chordwise section as net bending moments, torques and shears within ±3% at the 67% confidence level.

### SYMBOLS

D Sellerar Symbol Ior Dendring momenter prode or our	L	general	symbol	for	bending	moment.	shear	or	torque
--	---	---------	--------	-----	---------	---------	-------	----	--------

M bending moment 1b in

T torque lb in

V shear lb

β coefficient in load equation

b estimated coefficient in load equation

c oovariance of bridges

ε residual, difference between calculated and applied load

i row index

j column index

n number of loadings

μ non-dimensional bridge response

S standard error of estimate on the sample

s.e. standard error of individual forecast

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SYMBOLS (Contd.)

- q number of bridges
- v variance of bridge
- x distance from torque reference line in
- y distance outboard from strain gauge section in

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### APPENDIX

### METHOD OF ANALYSIS

The relationship between the expected values of one dependent variable and the observed values of a number of independent variables can be expressed in the form of a regression equation.

Once the regression equation has been established it may be used to derive estimates of the dependent variable.

In the application of regression analysis to flight load measurement the equations relating the response of the strain gauge bridges  $(\mu)$  and the three loads, bending moment (M), shear (V), and torque (T) are required.

The relationship between each of these and the responses can be expressed by a multiple linear regression equation of the form

$$\mathbf{L} = \beta_{1} \mu_{1} + \beta_{2} \mu_{2} + \beta_{3} \mu_{3} + \dots + \beta_{n} \mu_{n}$$
(1)

where L = appropriate values of M, V or T.

Thus the equations for n calibration loads at different locations may be written in the form

$$L_{1} = \beta_{1} \mu_{11} + \beta_{2} \mu_{12} + \beta_{3} \mu_{13} + \cdots + \beta_{j} \mu_{1j} \cdots + \beta_{q} \mu_{1q}$$

$$L_{2} = \beta_{1} \mu_{21} + \cdots + \beta_{j} \mu_{ij} \cdots + \beta_{q} \mu_{iq}$$

$$L_{i} = \beta_{1} \mu_{i1} + \cdots + \beta_{j} \mu_{ij} \cdots + \beta_{q} \mu_{iq}$$

$$\vdots$$

$$L_{n} = \beta_{1} \mu_{n1} + \cdots + \beta_{j} \mu_{nj} \cdots + \beta_{q} \mu_{nq}$$

$$(2)$$

j = 1,2 .... q i = 1,2 .... n

When n = q the equations (2) can be solved for  $\beta_1 \beta_2 \cdots \beta_n$  directly. This however may not lead to a reliable estimate of the load. The number of

oalibration loads is therefore chosen to be greater than the total number of bridges. The coefficients are estimated by the least squares method.

If the estimated coefficients are represented by  $b_1, b_2 \cdots b_q$  then the general form of equations(2) is now written

$$L_{i} = b_{1} \mu_{i1} + b_{2} \mu_{i2} \cdots + b_{j} \mu_{ij} \cdots + b_{q} \mu_{iq} + \varepsilon_{i}$$
(3)

where  $\varepsilon$  is the error or residual in the estimation of L.

The sum of squares of these residuals is required to be a minimum.

Consider for simplicity the solution for three bridge coefficients and n loadings.

The sum of squares of residuals to be minimised is

$$\sum_{1}^{n} \varepsilon_{i}^{2} = \sum_{1}^{n} \left[ L_{i} - (b_{1} \mu_{i1} + b_{2} \mu_{i2} + b_{3} \mu_{i3}) \right]^{2}$$
(4)

2

i = 1,2,,, n.

The necessary conditions are that:

$$\frac{\partial}{\partial b_1} \sum_{i=1}^{n} \varepsilon_i^2 = 0, \quad \frac{\partial}{\partial b_2} \sum_{i=1}^{n} \varepsilon_i^2 = 0, \quad \frac{\partial}{\partial b_3} \sum_{i=1}^{n} \varepsilon_i^2 = 0 \quad (5)$$

and the following three simultaneous equations are obtained which are solved for the coefficients  $b_1, b_2, b_3$ .

$$\sum_{1}^{n} (\mu_{i1})^{2} b_{1} + \sum_{1}^{n} (\mu_{i1} \mu_{i2}) b_{2} + \sum_{1}^{n} (\mu_{i1} \mu_{i3}) b_{3} = \sum_{1}^{n} L_{i} \mu_{i1}$$

$$\sum_{1}^{n} (\mu_{i1} \mu_{i2}) b_{1} + \sum_{1}^{n} (\mu_{i2})^{2} b_{2} + \sum_{1}^{n} (\mu_{i2} \mu_{i3}) b_{3} = \sum_{1}^{n} L_{i} \mu_{i2}$$

$$\sum_{1}^{n} (\mu_{i1} \mu_{i3}) b_{1} + \sum_{1}^{n} (\mu_{i2} \mu_{i3}) b_{2} + \sum_{1}^{n} (\mu_{i3})^{2} b_{3} = \sum_{1}^{n} L_{i} \mu_{i3}$$

$$(6)$$

- 16 -

If equations (6) are expanded it will be seen that  $\mu$  and L are always associated in product terms, e.g.  $(\mu_{i1})^2$ ,  $(\mu_{i1} \mu_{i2})$ ,  $(\mu_{i1} \mu_{i3})$  and  $(L_i \mu_{i1})$  and since changing the sign of L, (i.e. loading direction reversed) automatically changes the signs of  $\mu_{i1}$ ,  $\mu_{i2}$ ,  $\mu_{i3}$  and has no effect on the above equations; thus  $b_1$ ,  $b_2$  and  $b_3$  are the same as before.

If the responses of any one bridge are linearly related to the response of any other bridge then equations (6) become ill-conditioned and this is indicated by large standard errors.

The selection of strain gauge bridges is made by starting with an equation containing all possible bridges and rejecting successively the bridge having the lowest value of coefficient divided by its own standard error.

The best set is reached when the further rejection of a bridge does not reduce the standard error of the estimate.

The smaller the standard error the more accurate the estimate is likely to be

standard error of estimate =  $\int \frac{\text{residual sums of squares}}{\text{degrees of freedom}}$ 

and the general form for q independent variables is:

$$\int_{1}^{n} \left[ L_{i} - (b_{1} \mu_{i1} + b_{2} \mu_{i2} + \cdots b_{q} \mu_{iq}) \right]^{2}$$

$$n - q$$

The general multiple regression calculation was performed by a Mercury digital computer using the O.U.C.L. programme Stat/11.

A typical set of results is tabulated below and it corresponds to the estimation of bending moment from  $A_8$ ,  $A_9$ ,  $B_4$ ,  $D_7$  using combined load data (see Table 5).

It is possible to deduce from the standard error of estimate the variances of the b's and the covariances of the pairs of b's. The computer programme provides these values, as well as the standard error (Variance) of each b. The ratio of the coefficient to its standard error will determine the relevance of a particular b, being small for irrelevant coefficients.

- 17 -

L	Mean values	\$
Bending moment	1.000000	2
Bridge A <sub>8</sub>	1.229552	2
Bridge D_	-6.790000	1
Bridge Ag	3.069621	2
Bridge B <sub>4</sub>	3.583793	1

	Sums of squares	Degrees of freedom	Mean square ( <u>sums of squares</u> ) (degrees of freedom)	Variance ratio
Total	2.900000 5	28	1.03571 4	7097•14
Residual	2.551600 2	25	1.02064 1	
Regression	2.897448 5	4	7.2L362 4	

	Coefficien and covariance	nts es	Variano	9	Standard (/varia	error nce)	<u>Ceefficient</u> standard error
Ccofficient of A8	6.197572	-1	1.10279	-2	1.05014	-1	5.902
Covariance of A <sub>8</sub> and D <sub>7</sub>	5•97585	-3					
Covariance of A8 and A9	-1.49211	-3					
Covariance of Ag and Bh	-1.36721	-2					
Coefficient of D7	-5.258621	-1	6.49925	-3	8.06179	-2	<del>~</del> 6 <b>。</b> 523
Covariance of D, and A	-3,26202	-4					
Covariance of D7 and B1	-5.44623	-3			1		
Coefficient of Ag	-7-990783	-2	2.82071	-4	1.67950	-2	-4.758
Covariance of Ag and B	2.07733	-3					
Coefficient of B4	3.496938	-1	1.88299	-1	1.37222	-1	2•548

Thus  $M \times 10^{-3} = 0.62 A_8 - 0.526 D_7 - 0.08 A_9 + 0.35 B_4$  and the  $10^{-3}$ 

factor must be inserted because the dependent variable was scaled before computation.

<u>NOTE</u>: The single figure columns contain the power of 10 by which the preceding columns are to be multiplied.

(1) The standard error of sample  $(S) = \pm (10.2064)^{\frac{1}{2}} = \pm 3.2$  and expressed as a percentage of the mean value of the bending moment =  $\pm 3.2\%$ .

(2) The standard error of an individual forecast  $(s_{\bullet}e_{\bullet})$ . When the responses of an individual forecast are scaled by the ratio of the mean of the sample and the individual forecast it is then possible to use

$$\mathbf{s}_{\bullet}\mathbf{e}_{\bullet} = \pm \left[ \mathbf{S}^{2} \left( \mathbf{1} + \frac{1}{n} \right) + \Sigma \mathbf{v}_{i} (\boldsymbol{\mu}_{i} - \boldsymbol{\mu}_{i})^{2} + \Sigma \mathbf{e}_{ij} (\boldsymbol{\mu}_{i} - \boldsymbol{\mu}_{i}) (\boldsymbol{\mu}_{j} - \boldsymbol{\mu}_{j}) \right]^{\frac{1}{2}}$$

where

$$i \neq j$$
,  $c_{ij} = c_{ji}$  and  $i$  and  $j = 1, 2, \dots, q$ .

For the particular distributed load in Table 4 s.e. =  $\pm 4.5\%$  to be compared with the actual error of 1.1%.

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,	66	65	64	63	ଛ	64	6	55	¥	53	52	5	5	4	£	35	4	ы К	25	4	23	22	<u>د</u> در	с G	04	S S	02	2	8	Pad No.
	1-1-1	0.0	15•5	29•8	55•8	63•3	82•2	0.0	10.3	90.6	89•2	80•2	0.0	15•5	25•5	0.0	15.5	<b>3</b> 8•8	0.0	15-5	32•8	50•8	58 <b>•</b> 8	0.0	15.6	32•8	50•8	58.8	80•3	*(M)×10 <sup>-3</sup>
	1000	0	1000	1000	1000	1000	1000	0	1000	1000	1000	1000	0	1000	1000	0	1000	1000	0	1000	1000	1000	1000	0	1000	1000	1000	1000	1000	(V)
	83•0	0.0	49•5	68•0	98•3	107•3	130-0	0•0	53•8	148.9	141.5	149•8	0.0	72.0	72.0	0•0	87•5	87•5	0.0	102•3	102•3	102•3	111.8	0.0	126•3	130•3	133.3	135-0	138•3	*(T)×10 <sup>-3</sup>
	41.4	7.5	13.8	28.1	65•2	61.6	74•3	8•0	13.0	88•0	80.0	76-0	6.5	20.0	25.0	1.5	20.0	40.7	-13.5	45.4	44.9	52.9	58•1	- 2.7	22•5	38•4	53•2	57.1	73•9	A5
ſ	50.0	8•8	16•3	33.3	74.5	69.69	83.8	8•0	14.0	0.88	92•0	82•0	5.0	23.0	30-0	-6.5	32.5	4.8•7	0.0	21.3	40.1	56•3	63.6	4.0	18•8	33-7	54.7	60.7	81 • 2	<sup>8</sup> A
	0.0	0.0	0.0	4.7	27.6	28.6	50.0	0.0	0.0	62•0	58.0	56.0	0.0	5.0	0.0	0.0	3.8	13-1	4.5	4•8	12.0	20.6	27.3	-35.0	4.0	23.4	32.5	37.0	53•4	в <sub>4</sub>
	45.7	7.5	17.5	37.9	59•0	52.0	61.4	5.0	14.0	68•0	0.89	56.0	0.0	31.0	36•8	5.0	21.3	43.8	6.4	17.5	32.3	46.1	4.8.7	4.9	16.1	27.2	37.6	42.0	58.0	с <sub>4</sub>
	4•6	- 3.8	15-0	30•8	73•3	68•9	87.4	0•0	11-0	96•0	94.0	82•0	0.0	14.0	24.0	-10.5	12.3	45.0	1.9	16.3	37.4	55•7	64.5	3.0	17.9	32.3	52•8	62.9	86•7	C <sub>12</sub>
	0.0	45.0	-15.0	- 9-2	11.2	13.0	25.6	-24.0	-21.0	34.0	30.0	30.0	-18.0	- 9.0	-10.0	- 9.5	- 3.8	- 2.7	- 7.3	0:0	5.7	8•6	16.5	0.0	4.0	11-4	19.5	20.9	29.0	<sup>t</sup> d
Ţ	-27.1	41.3	-87.5	-43.4	-18.6	- 8.1	11.6	- 29.0	-124.0	34•0	26-0	36-0	-12.5	-34.0	-42.0	- 9•5	-20-0	-24.02	- 4.4	- 9.7	-10•9	-14.0	13.4	0.6	10-1	15.4	18.6	18.5	21.5	2 <sup>d</sup> 3
	37-1	2.5	20.0	35-2	43.3	35-1	36.1	-13.0	19•0	32.0	32.0	32.0	5.0	20•0	27.0	6.5	15.0	25•0	6.1	15-1	22.5	32.9	32.2	3.1	<u>б</u>	13.2	23.2	26.3	32.8	_م 
	-34.3	0.0	-16.3	-34-3	-39.8	-35.4	37.6	20.0	- 4.0	-38.0	-40.0	-36.0	1 4.0	-16-0	-31.0	+ 5•C	-13-8	-31.9	- 4-9	-12-3	-20.3	-32.0	-31.6	- 2.5		-15-1	-22-2	-24	-34-8	U U
ł	87.1	12.5	28•8	57.3	115.6	90•3	72.8	13.0	28•0	70.0	68•0	78-0	15.5	43.0	59-6	10.5	83-8	94-9	-67.1	24.3.8	151.3	105-1	9.66	35-5	125.5	5 130.9	+ 112.3	102.2	3 76-2	
t	110.	22.	S.	90.	111.	87.	74.	20.	43.	62•	70.	56.	ż	79.	93.	-55.	232.	116.	12.	76.	92.	%	æ	27.	52.	67.	67.	67.	10	A
	0	5 6	0-12	8 - <u>-</u> 10	9 	<b>1</b> 28	1 =	6	0 -10	0 82	0 60	0 120	5	0  4	5 0	0 7	5 22	2 18	 	3 65	8 70	38	53		8 296	1 184	4 145	6 125	1 7	ш ш
	<u>.</u>		5		i N	.7 2	o ₽	<u>.</u>	<u>.</u>	·0 7	<u>•</u>	0 8	ড	ò	ò	ò	5 -	2 1	5 	6 2	. <del></del>	-7 2	2 2 3	0 -	•2 9	 9	7	7 9	÷ 6	N
-	0.0	0	0	5-1-12	1.2 2	6.0	+•0	0.0	+•0	6.0	6.0	2.0	1.5	0.0 2	0.0 1	5.5	N.5	0.2	4		0.3	4° 	f- 	÷.	7.4	0 0	8.6	<b>4</b> .	1.9	в 3
	37-1	3-12	72.5	8	31.00 	52·9	20.2	16.0	0.99	- 0.95	+ <u>6</u> .0	-0-8č	5. 0	29.0	τ. ε	12.5	51.3	• 9 • • 98	14.8	38.9	57.0	63.7	56•9	12.5	22.7	39.0	32.7	34.4	46.3	ഄ൨
	-18.6	15.0	17.5	8•8	- 62-5	- 77•8	-133-8	0.0	10.0	-172-0	-156-0	-158•0	0.0	4.0	0.0	• ••	- 40.0	- 23-8	- 10-9	- 35.0	- 49.5	- 58•9	. 8.4	- 25.7	- 61.4	- 87.5	-106-6	-119•8	-143.3	C <sub>13</sub>
	17.1	-103-8	-51.3	0.0	35.3	38.6	57.6	0.0	-18.0	70.0	68•0	66•0	<u>।</u> ড	1.2	7•6	1. 5	7.5	19•6	3.2	11-8	22.5	28•6	36•6	7.3	20.7	33.7	6.04	4.8.8	57•8	D2
	-205-0	- 28-8	5•0	36.6	73.7	71.5	90.6	15-0	19-0	102-0	96.0	92•0	4.0	20.0	35.0	8.0	23-8	4.5	9•6	25.1	41.4	56•0	67•3	13.2	30.2	45.9	63•9	72.5	89•7	D <sub>4</sub>
Ť	60.0	85•0	24,3•8	91.9	59•2	45.7	34•4	-95.0	323.0	22.0	30.0	20.0	- 1.5	46.0	94.0	8•0	31.3	6.tz	8.6	24•6	37.2	43•2	39-4	8•1	10.1	7.5	20-9	21.4	28.6	D <sub>6</sub>

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Strain gauge responses at Section XX for 1000 lb load at loading pads

TABLE 1

or combined loads	Completions of loeding pads	00 03 04 23 25 33 44 55 64	01 03 04 05 24 45 52 62 63 64	02 04 22 23 24 34 35 53 65 66	00 02 03 05 22 23 24 34 35 ¼	00 01 02 03 04 05 11 22 33 35 43 54 55 60 61 62 63 64 66	01 02 04 22 25 34 44 45 60 61 63	22 24 25 34 14 55 60 61 62 63 64 65 66	00 03 cd. 05 23 24 25 33 43 44 51 52 55 60 64 66	00 %4 05 22 23 43 55 60 62 63 65	00 24 25 44 55 64 66	00 04 05 35 14t 51 52 53 55 64	23 24 33 34 44 45 55 65	05 04 22 24 34 35 44 45 54 54	23 24 25 33 34 44 44 45 54	ट4 34 35 43 44 54 55 63 64	이나 22 2나 34 35 나나 나5 5나 5나 63 6나	23 24 33 34 35 43 43 54 55	22 23 24 25 33 34 43 44 45	00 04 05 35 43 44 51 52 53 55 64	00 01 02 03 04 05 23 24 25 33 43 44 51 52 53 60 64 66	02 04 11 22 23 24 34 35 53 60 65 66	00 03 04 23 25 33 44 55 64	00 00 m3 04 23 24 25 25 33 44 44 55 55 64 64 66	00 03 04 23 25 33 14 55 64 66 66	23 24 33 34 44 45 55 62 62 65	아 22 24 34 35 43 44 45 54 54 54 60 60 64	23 24 25 33 34 43 44 44 45 54 63 66	24 33 34 34 35 43 44 54 55 63 64	22 23 34 43
ads f	D6	48 <b>.</b> 8	61.9	42.8	31•9	68.7	39.1	6*29	47.1	9•61	63.3	46•0	36•5	103.6	81.5	109.7	127.0	81.7	48.3	52.0	68•3	41.6	48•9	54.8	51.3	1.54	128.8	81.6	94•8	51.4
ding 1	D4	31.1	50.3	14.5	48.4	37.7	53.2	16•3	32•2	52.8	-14•0	63.0	23.0	33.6	29.6	22•5	27.4	31.0	37.1	59•5	42•0	27•5	<b>38.</b> 8	16.7	-15.4	37•5	28•9	7.4	25.1	39.1
f loa	D2	15.4	21.6	14.6	26.6	6• સ	27.3	i <b>1</b> •6	26.4	16.7	8•0	34.5	<b>-8.</b> 5	<b>6•</b> 3	6 <b>.</b> 8	-5.7	-1-9	8•6	14•4	31.1	31.04	21.1	15•3	12•3	15.7	4.0	6•0-	2.0	-1-4	16.6
ions c	c13	- 50.7	- 65.2	- 67.0	- 68•9	- 60.8	- 66.3	- 39.2	- 67.8	- 63.9	- 37.3	<b>-1</b> 00 <b>.</b> 6	- 25.9	- 35.9	- 20.2	6 <b>.</b> 2	-17°0	-21.7	-30-6	-88-0	-80°0	-75-0	-50.8	-45.1	-4.J.a.3	-36.4	-13.2	-15.1	-11-9	-37.1
binat	c <sup>c</sup>	83.5	53.2	55°4	74.1	5.69	72.2	93•0	76.9	80.7	100.9	75.9	95•5	68.7	100.6	100.9	78.9	<b>69</b> •3	93.2	84 <b>.</b> 4	68.0	55•0	83.5	2.06	84 <b>.</b> 3	91.7	88 <b>.</b> 6	109.1	100.8	81.8
nd con	B	41.5	41.8	14.44	37.8	<b>32.</b> 4	40 <b>.</b> 6	15.3	37.0	30.3	18.4	49•7	16.9	30.3	13.0	4.1	16.4	12.1	17.0	4.54	14.5	43,44	41+5	31.9	32•2	18.1	13.0	8•6	5.7	16.7
XX an	<sup>B</sup> 2	92.4	79.5	90•2	63.7	56.7	6•11	20 <b>•</b> 9	64.1	54.0	28•6	76.5	26.4	1.0L	26.4	10.4	43.7	25.7	32.8	6•99	73.8	81•5	92.4	65.8	7.8	33.0	34.8	17.5	12.6	32.9
tion	49	80.1	78.7	94,•0	93•6	<b>19.</b> 4	96•7	105.7	82.1	93•4	83•5	61.8	131.0	80.7	106.7	0•06	6-62	101.9	115.6	65.7	77-8	91.1	80•0	81•5	86.7	125.6	82.1	104.1	108.6	127.4
t Sec	A7	86.0	115.4	125•2	124.7	90•3	82.9	89.1	95.9	103.1	86.0	Ъ.1	132•6	100.7	92•3	81.9	86.0	106.4	105.0	76.6	94.9	117-4	85•9	85.9	86•2	127.8	81•0	85•0	83.4	100•0
ises e	۲a	-18.8	-25.1	-23.7	-21.8	-26.5	-26.3	-25.7	-25•0	-27-9	-19-7	-25.7	-15-7	-15.6	-17.6	-16.1	-17.0	<b>-18</b> -5	-23.8	-26.4	-26.9	-25-9	-18.7	-19-1	-23-2	<b>-</b> 22°6	-19.9	-22-3	-17•6	-24.3
espor	D5	19.0	25•0	24.1	8.9	27•5	26.7	28 <b>•</b> 5	24.02	28•5	23.6	24.6	18•4	20•2	21.1	20.7	21.5	20•6	54.0	24.9	25.6	26.1	19-0	20•9	23.0	25•6	23.2	24.7	20•5	24.2
uge 1	50	-20.4	-11-6	1.6	- 4.2	-21.1	- 8.6	-24.4	10.7	- 8.1	-34.0	- 3.3	-19-9	6•6£-	-39.1	-22-0	-52.1	-141=5	-24.05	- 8.2	- 2.4	6•0	-20•5	-26.1	-21 •9	-19-5	-50.4	-38.6	-49-5	-51-7
in g	t a	- 1:1	4.4	1.8	6.6	L.J	6.1	-5.4	5.3	<b>-0-</b> L	- 0-5	6•6	-19-4	- 6.1	- 9•3	-14-5	-10-3	-10.8	- 5•0	7•4	10•4	5•7	- 1-1	- 2•9	<b>6</b> •0 -	-10-6	-10-2	- 8.4	-12•0	0.4
stra	c12	35.7	48.2	34.8	37.5	45.4	45•0	37•6	13.2	51.6	27.7	58.9	24.2	22.6	21.7	16.2	19•3	23•0	29.6	52.8	48.4	1.3.1	35.7	32.4	23.8	<b>38.3</b>	20.8	21.2	19•0	<b>\$</b> 2•5
posed	c <sub>4</sub>	33.9	36•3	37.1	35•1	41.2	35.1	40.8	40.6	45.6	36•2	47.1	31.7	25•3	28.2	26.6	24.Å	30.4	33.6	45.9	41.9	140.7	6•1 <u>C</u>	34.9	36.5	<b>39.</b> 5	26.8	31.8	27.9	34.1
Super	Bt	15.2	15.5	17.5	15.0	17.9	20.2	14.1	18.4	17.1	11.7	ิลิ	2.7	8 <b>.</b> 8	5.6	5.6	5	5   T+•8	7-8	5 25.4	7 23.2	1 21.7	5 15.2	1 13.8	1 11.8	1 13.4	5 4.3	1 4.64		7 9.1
	A8	5 38.5	5 44.9	2.21	t [[2•5	T-01 t	5 48.6	5 47.5	2 48.6	0 54.9	8 40.0	<u>4</u> 58 <b>.</b> 1	5 37.5	\$ 8	<u>କ</u> ଷ	0 57*6	3 25.2	9 31.6	6 36.	8 277•(	7 51.	0 51.	5 38.5	6 39.	8 41.	3 48.	4 26.	2 32.	1 28.	7 39.
	3 A5	35.	11/1-	17.	3	45.1	12	10	45.	20	37.	54.	38.	31.	28	55.	Şę	31.	34.	20	48•	51	35.	36	36.	1 <sup>1</sup> 6.	56	53	 50	35.
	<del>/</del> (T) x 10	100-9	106.4	110.7	108.5	101.6	106.8	0•06	106.5	104.7	0•68	118.0	90•3	91.4	82•5	72.2	79.5	82.5	<b>99.</b> 4	112.3	112.6	112•7	100•9	95•9	6 <b>•</b> 96	92•7	77.8	80•0	75.5	91.0
	ß	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000
	FM) x 10-3	33.0	39.1	39.4	36.7	44.5	42 <b>-</b> 4	- <b>38.</b> 8	43.7	46.6	34•2	55•2	23.6	23 <b>°</b> 0	20•5	18•2	19•8	23.4	27•8	51.5	48•0	45•6	33 <b>•</b> 0	33•5	35•5	32.8	21.3	24.3	20 <b>•</b> 2	31.1
	NO	e -	<u></u>	m	4	ې ۹	ف: ري	~	<u></u>	0	ğ	I	12#	13	14	15	16 <del>a</del>	17	18	19 <del>4</del>	ଷ୍ପ	ស	ືສູ	ຄ	<b>с</b> т.	ধ্য	26 <b>*</b>	27	28	29 <b>¢</b>

TABLE 2

of loading pads for combined loads 4 2 τ 4

- 20 -

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<b>r</b> 0	η.
	E.
	•

# 7 See Fig.2 for reference axes.

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TABLE 3	
Contraction of the local division of the loc	

Measured and superposed strain gauge responses for distributed load (Table 4)

4

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Bridge	<sup>A</sup> 5	A <sub>7</sub>	<sup>A</sup> 8	<sup>А</sup> 9	<sup>B</sup> 2	в <sub>4</sub>	с <sub>5</sub>	D <sub>1</sub>	<sup>D</sup> 2	D <sub>3</sub>	D <sub>6</sub>	D <sub>7</sub>
Superposed response	183	361	198	362	174	76	308	17	78	-78	284	-115
1st dist.load 2nd dist.load	187 183	350 363	196 197	362 365	173 169	76 78	298 298	14 14	72 75	-78 -85	2 <b>83</b> 283	<b>-1</b> 18 -115
Mean	185	356	196	364	171	77	298	14	74	-81	283	-117
% age error on mean	-1•1	1•4	1•0	-0•5	1:8	-1•3	3•4	21.5	5•4	-6•1	0•4	-1•7

1 21 1 .

TABLE 4

Distributed load

	500	500	310	290	245	225	190	145	125	100	70
Pad No. 00	61,63	64 <b>,</b> 66	24	34	35	44	45	04	25	02,03	05

Predicted E	Λ <sub>8</sub> 0.982
Actual B.M.	Α <sub>9</sub> -0.074
Percentage	Β <sub>4</sub> 0.050
Percentage	D <sub>7</sub> -0.033
.M. x 10 <sup>-3</sup>	0.620
x 10 <sup>-3</sup>	-0.080
arror	0.350
standard error	-0.526
	196 364 77 -117
173.4	192.5
179.0	- 26.9
- 3.2	3.9
9.4	3.9
180.9	121.5
179.0	- 29.1
1.1	27.0
3.2	61.5

D 45 7

-0.006 0.608 -0.398

-0.045 0.749 -0.744

185 364 77 -117

- 2.2 46.8 46.6

- 16.4 57.7 87.0

48 A8 A9

0•468

0.308

86.6

57.0

.

Predicted B.M. x 10<sup>-3</sup> Actual B.M. x 10<sup>-3</sup>

Percentage error Percentage standard error

177.8 179.0 - 0.7 20.4

185.3 179.0 3.5 4.2

0 3•3	- 2.9 9.7		ror Indard error	ercentage er: ercentage stu	סי. טי
179•5 179•0	173.9 179.0		• x 10 <sup>-3</sup> 10 <sup>-3</sup>	redicted B.M. ctual B.M. x	₽ P
53-7	403	-117	-0-459	-0.037	
1.7	0.6	283	0,006	0,002	. <sup>D</sup> 6
25.6	6,3	77	0.333	0.082	Bų
0.5	0.2	הו	0.003	0.001	<b>ი</b>
- 30.2	- 26.2	364	-0.083	-0.072	وA و
128.2	188.7	196	0.654	0.958	8 <sup>A</sup>

D<sub>7</sub> D<sub>6</sub> D<sub>7</sub> D<sub>7</sub>

0.082 0.002 0.002

0.645 0.359 0.007

196 364 77 283 -117

188.5 - **26.2** 6.3 0.6 4.3

- 29**.**9 27**.**7

2•0 53•9

126.5

Percentage error Percentage standard error

1

180.2 179.0 0.7 2.9

3•2 9•5

173•5 179•0

Predicted B.M. x 10<sup>-3</sup> Actual B.M. x 10<sup>-3</sup>

Pe	. Pi Ac	D <sub>6</sub> D <sub>7</sub>	в <sub>4</sub>	Ag .	A8	A5	Gauge . station (a)
rcentage er rcentage st	edicted B.M. tual B.M. x	0.002 -0.057	0.105	-0 <b>-</b> 069	0,903	0.035	Regression Individual load (b)
ror andard error	• x 10-3 10-3	6.008 -0.433	0•354	-0.083	0.721	-0,062	coefficient .Cambined loed (c)
		283 -117	7	t9£	196	185	Gauge station response (d)
-3.0 9.9	173•7 179•0	0.6 6.7	8 <b>.</b> 1	- 25.1	177-0	6•5	Distribui contrit Individual load (e)
0.6 7.1	178.0 179.0	2•3 + 50•7	24.9	- 30.2	141.0	- 11.5	ted load ution Combined load (f)

-

	<sup>ე</sup> ი ი <sup>B</sup> <sup>A</sup> ა ა ი ი ი <sup>B</sup> <sup>A</sup> ა	Gauge station (a)	R
Predicted B. Actual B.M. Percentage s Percentage s	1.152 -0.1142 0.017 -0.013 0.001 -0.193	Regression Individual load (b)	egression
M. X 10-3 X 10-3 MITOR MANDAIN ETTO	1.016 -0.177 0.048 0.008 -0.009 -0.415	<u>coefficient</u> Combined load (c)	s for est
-1	185 356 177 288 283	Gauge statien response (d)	imating be
184.4 179.0 3.0 9.9	213.1 - 50.6 - 3.9 - 3.9 0.3 22.6	Distribute contribu Individual load (e)	ending mo
181-7 179-0 1-5 3-1	188.0 - 63.0 8.2 2.4 - 2.5 48.6	ad load ition Combined load (f)	ment

TABLE 5

gression	coefficient	្រុងរាទទ	Distribute	ed load	
dividual	Combined	station	Individual	Combined	
load	load	response	load	10ad	
(b)	(c)	(d)	(e)	(1)	
1.152	1.016	185	213•1	188.0	
-0-142	-0.177	356	- 50.6	- 63.0	
710•0	840-0	17	2.9	8.2	
-0,013	0.008	298	- 3.9	2.4	
0.001	600	283	0.3	- 2•5	
-0.193	-0.415	-117	22,6	48•6	
dicted B.I ual B.M.	х 10-2 К. х 10-3		184•1 179•0	181.7 179.0	
centage e	ITOF		3 (J) 2 (D)	• • • •	
		٢			

טי≪ סיני	рд А А У У С С С С	סי כל טי טי	А В В В 4 С С С С С С	Gauge station (a)
Predictec Actual B. Percentag Percentag	0,00 9998 0,00	Predicter Actual B. Percentar Percentar	-0.000 -0.001 0.01 -0.011 -0.011	n Individ

1 22 1

sion	coefficient	Gauge	Distribute	d load
duel	Combined	station	Individual	Combined
	(c) (c)	response (d)	(e)	(1) (1)
N	0•326	185	81.8	60,3
б	670.0-	364	- 2.2	-17.8
0	-0.016	ולו	- 1-7	- 2.7
<u></u>	104.0	7	54+3	58.8
	-0.003	283	3•1	- 0,9
•	-0.767	-117	43.4	89.7
d B.M	10 <sup>-3</sup>		178.7	187.4
ge er	ror		- 0.2	4.7
ge st	andard error		18.1	4.3
	(c) 0.326 -0.049 -0.016 0.764 -0.003 -0.767 10 <sup>-3</sup> 10 <sup>-3</sup> 10 <sup>-3</sup>		81.8 178.7 178.7 18.1 18.1	(E) 60.3 -17.8 - 2.7 58.8 - 0.9 89.7 179.0 179.0 4.7 4.3

d B.N M. J ge ei ge s	9781
1. x 10 <sup>-3</sup>	0.040
x 10 <sup>-3</sup>	0.836
rror	-0.120
tandard errot	-0.430
	185 196 364 -117
175.0	2.0
179.0	195.6
- 3.5	- 28.0
9.5	3.4
177.9	7.4
179.0	163.9
- 0.6	- 43.7
3.5	50.3

Pred Actu Perc Perc	6 - 6
icted B 1 B.M. entage	011 034 077
"M. x 10 <sup>-3</sup> "x 10 <sup>-3</sup> error standard err	-0.0072 1.113 -0.093
or	364 196
172•7 179•0 - 3•6 9•4	- 2.0 202.7 - 28.0
170.9 179.0 - 4.5 5.2	- 13 <b>.</b> 3 218.1 - 33.9

Gauge	Regression	coefficient	Gauge	Distribute contrib	ed load ition
station	Individual load	Combined load	station response	Individual Leubividual	Combined load
10	1000	1.103	356	105_0	531-5
A A	2;149	1.821	364	782.3	662.8
ہ م ھ	1.663	2•064	171	284.64	352•9
۲ v	2.517	3.333	298.	1-052	993•2
<u>م</u> م	1.987	2.274	283	562.4	64.3.5
2 R	5.119	4.640	621	916.4	830.6
	Predicte Actual s	d shear hear		0,2 147 1,0001	02.14 14014=5
	Percente Percente	ge errvir ge standard (	TOTIE	-4•2 9•9	-3.8 1.7

0.3 1237.1 9.7 1663.1 2.4 1037.8	2.4 3938.6 0.0 4170.0 7.9 -5.5 5.2 7.1
356 136 298 127 179 120	384 1417 417 -
3.477 5.581 5.738	icted shear al shear entage error entage standard
3.821 4.294 6.77	Pred Actu Perc
M C2	

TABLE 6	sions for estimating shear
	Regressions

\*\*

load	Gauge	Regression (	coefficient	Gauge	Distribut contrib	ed load Ition
Combined Load (f)	station (a)	Individual load (b)	Ccmbined load (c)	station response (d)	Individual load (e)	Combined load (f)
624.1 677.8	A A A A	1.969 3.601	1.757 2.668	356 196	701.0 705.8	625.5 522.9
331.6 1103.5	, <sup>A</sup> 9, 28	2•031 1•672	1.674 1.988	364	739.3 285.9	609.3 340 <b>.</b> 0
44.5 664.5	ນ <sub>ປີ</sub> ດີ	2.766 3.581	3 <b>.</b> 836 4.328	298	824.3 50.1	1143 <b>•1</b> 60 <b>•</b> 6
566.7	D6	2•234	2.124	283	623•3	686
4012,7 4170		Predict Actual	ed shear shear		3938+7 4170	3987.4 4170
-3.8 1.4		Percente Percente	age error age standard	error	<del>-5</del> •9 10•2	-4.4 1.64

356         1373.44         1168.7           298         880.61         1047.62	2012 201 2012 2013 2013 2013 2013 2013 2	3975.3 4147.7 4170.0 4170.0	-0.5
3.514 3.514	7.097	ted shear shear	tage error
, 3.858 2.953	6.651	Predict Actual	Percent
А <sub>7</sub> с5	9 <mark>02</mark> .		

38 <b>.</b> 8 1882.4 71.5 1725.4	56.38 3608.3 70.0 4170.0 2.2 -15.6 9.0 9.9
356 205 298 157	H 11
5•288 5•792	cted shear L shear ttage error ttage standard
5•859 5•294	Predic Actual Percen Percen
A <sub>7</sub> c <sub>5</sub>	

.

.

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- 23 -

Gauge	Regression	coefficient.	Gauge	Distributed contribut	- 3
station (a)	(d) (bad · (b)	Combined load (c)	station response (d)	Individu <del>a</del> l load (e)	Ū
A-7	1.996	1.753	356	70.6	
9. 64	2.260	1.862	364	822.6	
В В	1.623	1.939	17	277.5	
c C	2.684j	34703	208	8.667	-
<u>م</u>	2•521	3.178	14	35•3	
D6	2.147	2.348	283	607.6	
н	14•036	3.166	179	722.4	
	Predicte Actual s	d zhear hear		3975•8 4170•0	t t
	Percenta Percenta	ge error ge standard er	TOL	-4.0 9.4	

104.3.4 250.7 1009.0 574.5 1057.2	3934.8 4170 -6.0 10.7
356 171 298 283 179	ror
2.809 1.727 4.349 2.058 4.299	d shear hear ge error ge standard ei
2.931 1.466 3.386 2.030 5.906	Predicte Actual s Percenta
A7 C5 D6 M	

1000.0 295.3 1296.0 582.4 769.5 3943.2 4170 -5.4 2.5

		D <sub>6</sub>	с б	B4	- 2 <sup>g</sup>	A <sub>7</sub>
Percentage Percentage	Predicted T Actual Torq	0,092	0.236	1.327	0.172	0,423
error stan_ard err	orque x 18 <sup>-3</sup> lue x 10 <sup>-3</sup>	0.087	0.299	1.683	0,239	0•318
ог Г		283	298	77	171	356
-8.2	378•5 409•6	26.0	70,3	102,2	29•4	150-6
-3.0 3.4	397 <b>.</b> 4 409 <b>.</b> 6	24.6	89.1	129.6	6°0ħ	113-2

		М	D6	с <sub>5</sub>	х <sup>в</sup> .	A-7
Percentage Percentage	Predicted Actual Ton	1.056	0,076	0.165	0,267	0,256
error standard eri	Torque x 10 <sup>-3</sup> que x 10 <sup>-3</sup>	بلباو•٥	0,059	0,230	0,283	0,268
Gr	ŭ	179	283	298	171	356
-3.3	396 <b>.</b> 5	189	21.5	49.2	45.7	91.1
-2,6 2,5	398 <b>.</b> 0	169,0	16.7	68.5	48.4	95-4

•

-2.4 2.1	-1.5	or	error standard er	Percentage Percentage	
9°601 9°66£	9°607 9°£07	3	Torque x 10 <sup>-3</sup>	Predicted Actual Tor	
139-1	183-1	179	0.777	1.023	н
21:2	19_8	283	0.075	0.070	D6
5.2	1.4	14	0.371	0,097	- <sup>D</sup> ,
و•مر	32.5	298	0,238	0.109	С <sup>7</sup>
47.7	49.2	171	(*279	0,288	B
23.3	52.8	364	0.064	0.145	. گې
92.2	64.8	356	0.259	0,182	A7
Combined load	Individual load	station response	Combined load	Individual load	station
ition	Distribute	Gauge	coefficient	Regression	ជួយវត្ថុទ

		Ħ	D6	D2	ኇ	N <sup>B</sup> 1	٩ و۸	Ay	station	Gauge	
Percentage Percentage	Predicted ( Actual Tor	0,963	080_0	0.050	0.115	0.274	0.155	0_185	Individual load	Regression	Regi
error standard err	forque x 10 <sup>-3</sup> que x 10 <sup>-3</sup>	0.795	0,376	0.234	3.211	0,269	0.054	0,219	Combined load	coefficient	essions f
Ør		179	283	74	298	171	364	356	station response	Gauge	TABLE 7 or estima
-1-8	402.2 409.6	172.4	22.6	3.7	34.3	46.9	56-4	65 <b>•</b> 9	lugivipul pact	Distribut contrib	ting torq
-2.7 2.0	398 <b>.</b> 2 409 <b>.</b> 6	142.3	21.5	17.3	62.9	0•91	19•6	6_88	Combined load	ed load ution	10

	м 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	Gauge station
Predicted To Actual Torqu Parcentage e Percentage s	0,252 0,271 0,154 -0,155 0,069 1,1111	Regression Individual load
rque x 10 <sup>-3</sup> e x 10 <sup>-3</sup> rror tendard erro	0.306 0.266 0.274 0.274 0.376 0.765	coefficient Combined load
Ϋ́,	356 171 298 14 179	Gauge station response
-2°3 96°1	89.7 46.3 45.9 -2.2 19.5 198.9	Distribut contrib Individual load
397.3 409.6 -3.0 2.2	108.9 45.5 81.7 5.3 19.0 136.9	red load aution Combined load

- 24 -

TABLE 8

Influence of size of sample

_								
Bending moment	Coefficients based on 10 pt data (o)	0 <b>.</b> 726	-0-100	0.200	-0 <b>-</b> 006	-0-543		3.1
	Coefficients based on 29 pt data (b)	0.645	<b>-0</b> ,082	0.359	200•0	-0-461		2•9
	Gauges	84 8	A9	B 4	D6	D7	a b b c b c b c b c b c b c b c b c c b c c b c c b c b c c b c c b c c b c	LOTIOU C V

	Coefficients based on 10 pt data	0.354		0.229	0.214	0•305	0.061	0.718	1.5
Torque	Coefficients based on 10 pt data (o)	0.875	-0-371	0.115	0•404	1.404	0•057	<b>-</b> 0•396	5•9
	Coefficients based on 29 pt data (b)	0•249	0°054	0.269	0.211	0•234	0*076	0•795	2.1
-	Gauges	A	4 <sup>9</sup>	° B	5	D2 D2	D6	W	% standard error

· · · · · · · · · · · · · · · · · · ·	Coefficients based on 10 pt data (c)	3 <b>.</b> 848	0,821	1 • 696	3°660	6 <b>°</b> 336	2,153	1.411	0,8
Shear	Coefficients based on 29 pt data (b)	1.753	1。862	ʻi <b>.</b> 939	3.703	3.178	2°348	3.166	1.4
	Gauges	. A.	. Ag	B, ,	°2	, A	90 1	N	% standard error



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FIG. 3. RESPONSE OF GAUGE A7 WITH POSITION OF LOAD. (1000 LB).



FIG. 4, RESPONSE GAUGE  $A_5$  WITH POSITION OF LOAD. (LOAD SCALED TO PRODUCE BM = 10<sup>5</sup> LB. IN. AT SECTION XX)

ARC C.P. No. 339	533 <b>.6.048.1:</b> 531.71	ARC C.P. No. 839	533 <b>.6.048.1:</b> 531 <b>.71</b>
THE INTERPRETATION OF STRAIN MEASUREMENTS FOR FLI Hovell, P.B, Webber, D.A, Roberts, T.A. Augus	GHT LOAD DETERMINATION. t 1964.	THE INTERPRETATION OF STRAIN MEASUREMENTS FOR 1 Hovell, P.B. Webber, D.A. Roberts, T.A. Au	FLIGHT LOAD DETERMINATION. gust 1964.
The procedures of N.A.C.A. Report No. 1178 measured flight strains as structural loads are n for applications to delta or slender-body configu from the severe non-linearities in the gauge resp the calibrating load, and from the need to suppor representatively during the ground calibrations. overcome if distributed load data, obtained eithe position, are used in place of individual load da original N.A.C.A. Report, the procedure will then reliability of any particular flight load measure technique is illustrated by an application to the laboratory tests.	for the interpretation of ot entirely satisfactory rations. Problems arise onse with the position of t the aircraft These difficulties are r directly or by super- ta. In contrast to the establish directly the ment. The modified Lightning fin in	The procedures of N.A.C.A. Report No. 11 measured flight strains as structural loads are for applications to delta or slender-body confi from the severe non-linearities in the gauge re the calibrating load, and from the need is sup representatively during the ground calibrations overcome if distributed load data, obtained eit position, are used in place of individual load original N.A.C.A. Report, the procedure will the reliability of any particular flight load measure technique is illustrated by an application to the laboratory tests.	78 for the interpretation of e not entirely satisfactory igurations. Problems arise esponse with the position of port the aircraft s. These difficulties are ther directly or by super- data. In contrast to the hen establish directly the urement. The modified the Lightning fin in
		ARC C.P. No. 839	533 <b>.6.048.1:</b> 531 <b>.7</b> 1
		THE INTERPRETATION OF STRAIN MEASUREMENTS FOR F Howell, P.B, Webber, D.A, Roberts, T.A. Au	FLIGHT LOAD DETERMINATION. gust 1964.
		The procedures of N.A.C.A. Report No.117 measured flight strains as structural loads are for applications to delta or slander-body conf from the severe non-linearities in the gauge re the calibrating load, and from the need to supprepresentatively during the ground calibration overcome if distributed load data, obtained ei position, are used in place of individual load original N.A.C.A. keport, the procedure will to reliability of any particular flight load meass technique is illustrated by an application to a laboratory tests.	8 for the interpretation of e not entirely satisfactory igurations. Problems arise esponse with the position of port the aircraft s. These difficulties are ther directly or by super- data. In contrast to the hen establish directly the urement. The modified the Lightning fin in

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